CRH8508 DOUELE UNIT CCD

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CONTENT

Introduction

The main function of this program is to utilize a single set of CCD to identify the presence of ICs, and to transmit the results back to the Handler. This program communicates with the Handler using the LSI3101 card to trigger imaging and I/O to return the recognition results.

Basic function

- Identify the presence of ICs.
- CCD parameters can be set by the program. For example: Exposure Time, OffsetY, ReverseX and ReverseY.
- Recognition parameters can be set by the program. For example: Color Difference, Matching Ratio, Stitching images pixel, Grabbing images Position, Recognition Area, Sample Position, and Sample Size.
- Create a new profile/Switch profile using Modbus protocol.
- Language switch.
- I/O Settings (SOTP、SOTN、EOT、OK、NG)

MMain Form description

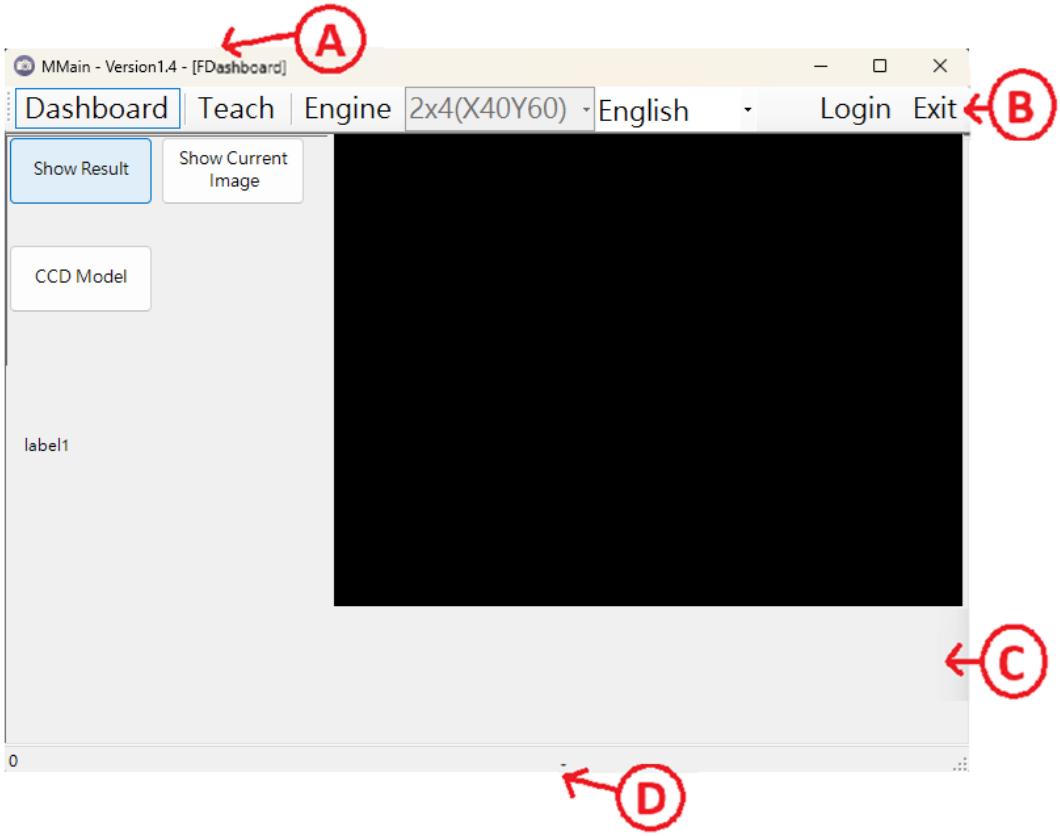
Upon entering the program, the main interface is as follows, which can be divided into 4 areas:

A. Title Bar: Includes the window name and the current page window.

B. Main Function Bar: Socket-based types, Language Selection, Dashboard page, Teach page, Engine page, Login page.

C. Page Content Display Area: Includes Dashboard page content, Teach page content, Engine page content, Login page content.

D. Status Bar: Displays current engine point, image recognition processing time, and image recognition results.



Main Function Bar operation DESCRIPTION

Socket-based types

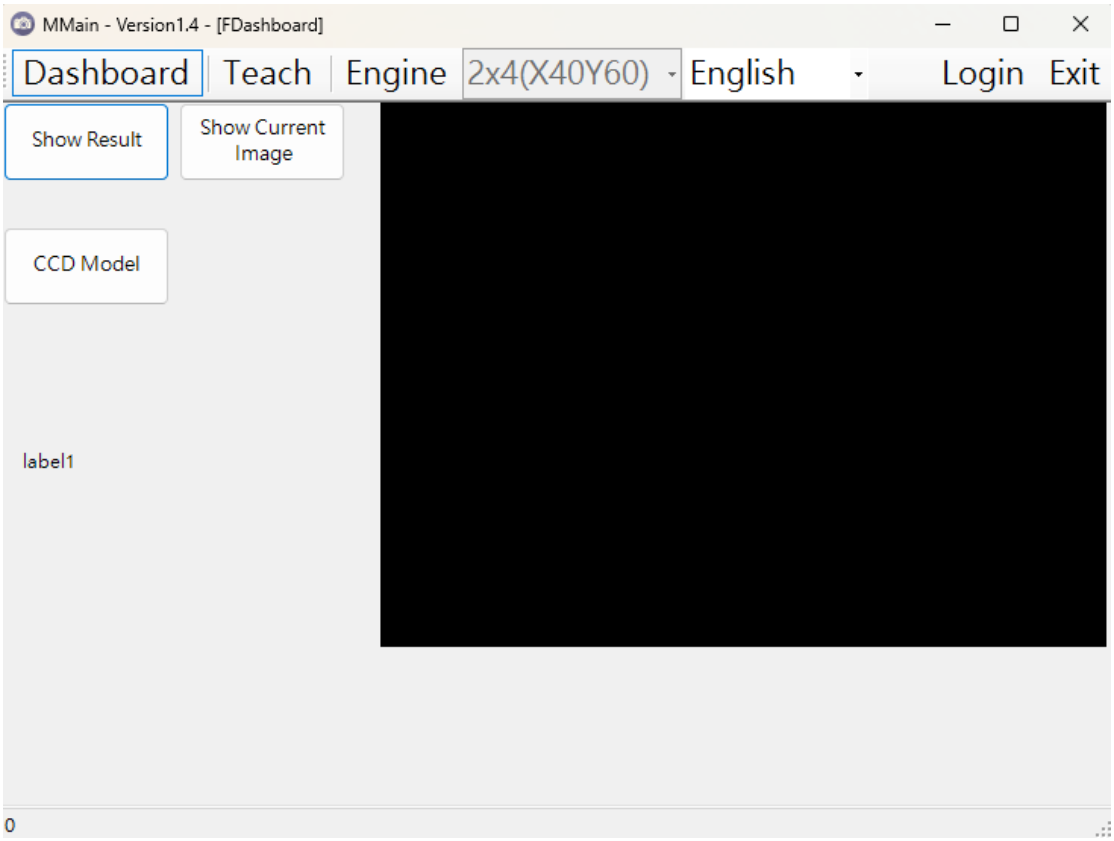
Switching socket base types. X40 indicates a 40mm spacing between each socket in the horizontal axis, and Y60 indicates a 60mm spacing between each socket in the vertical axis.

Language switch

Page Content Display Area operation DESCRIPTION

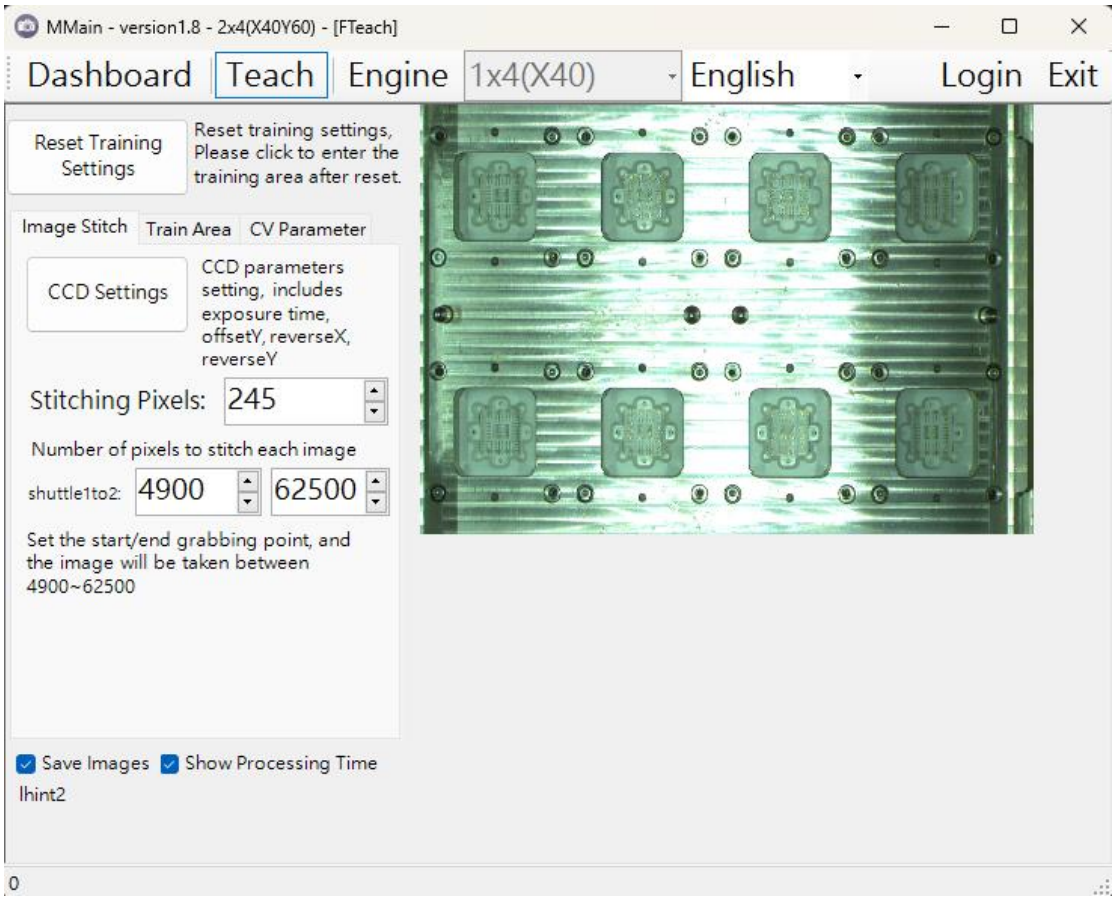
Dashboard page

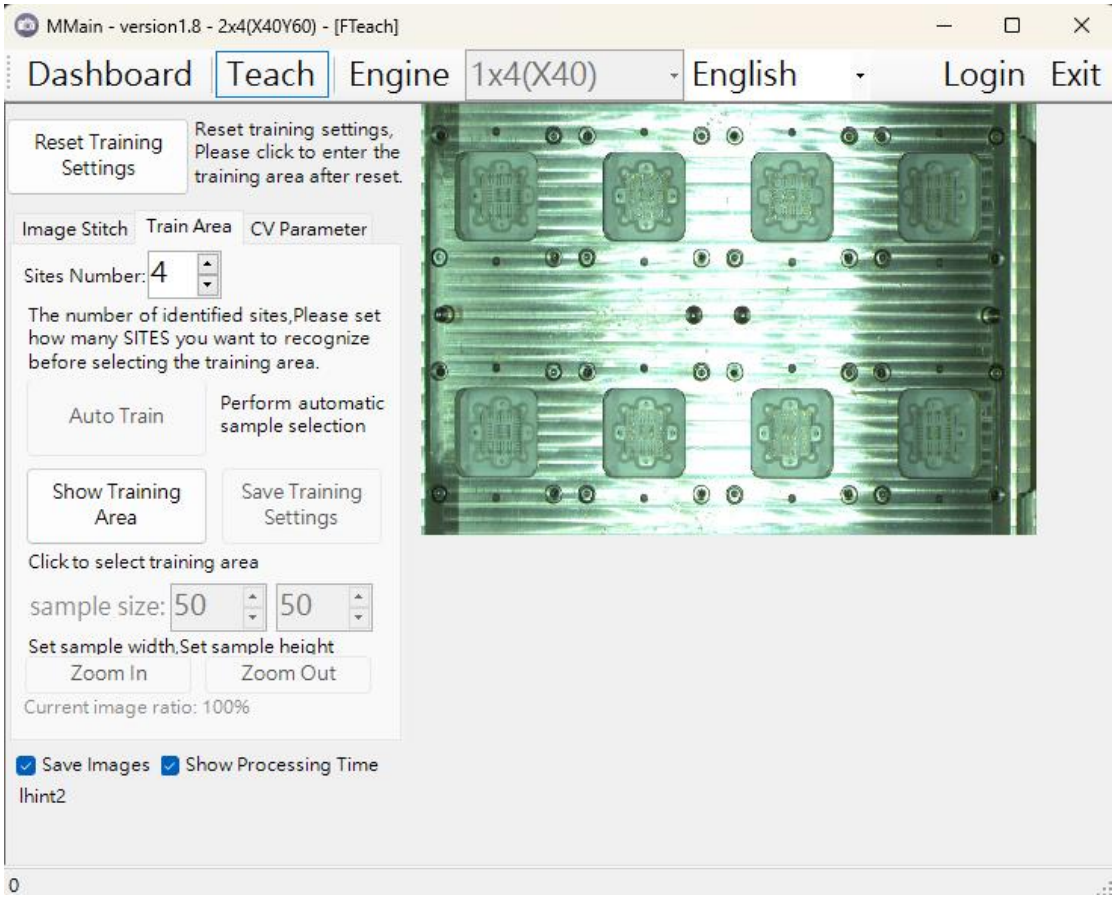
Includes the CCD model selection window, displays the image and recognition results.

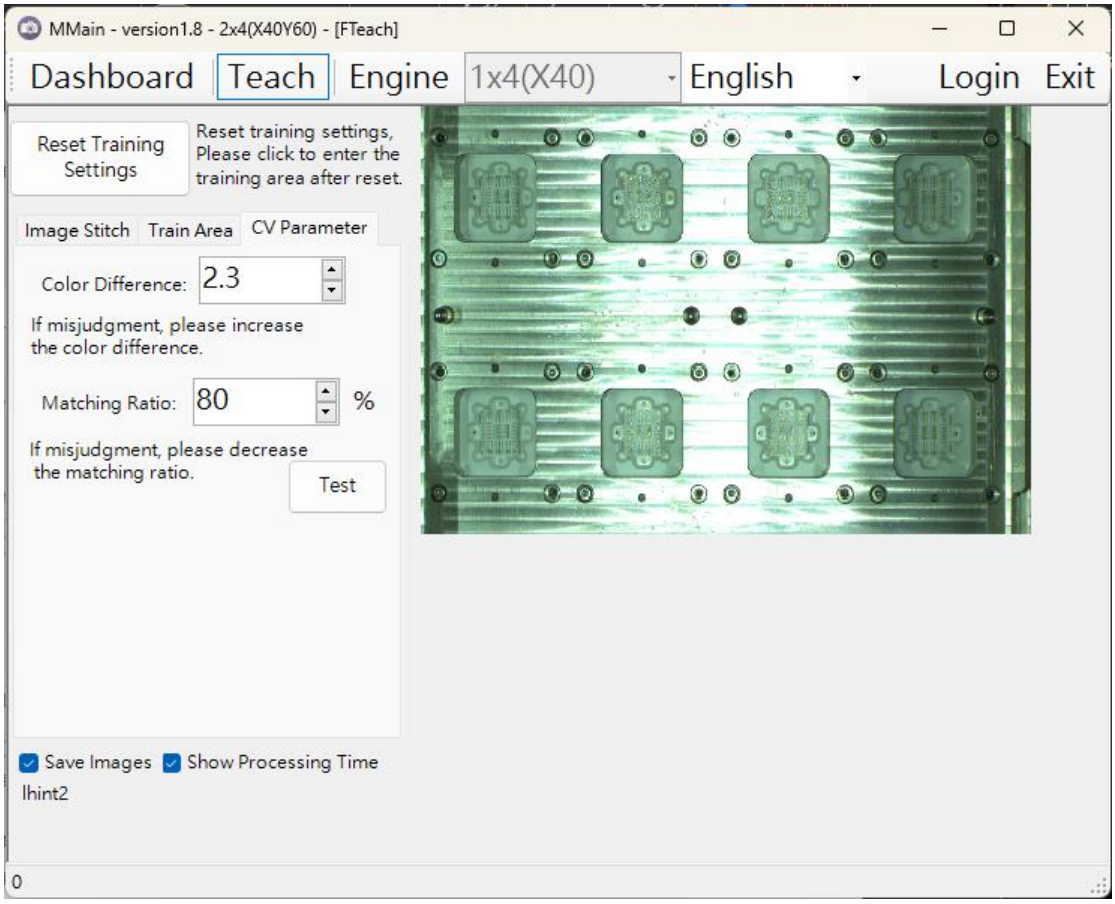


Teach page

Includes the CCD settings window, adjusts the recognition area, sample areas, image recognition parameter settings, Zoom out.


MMain - version1.8 - 2x4(X40Y60) - [FTeach]
Dashboard
Teach
Engine
1x4(X40)
English
Login
Exit
Reset Training Settings
Reset training settings, Please click to enter the training area after reset.
Image Stitch
Train Area
CV Parameter
CCD Settings
CCD parameters setting, includes exposure time, offsetY, reverseX, reverseY
Stitching Pixels:
245
Number of pixels to stitch each image
shuttle1to2:
4900
62500
Set the start/end grabbing point, and the image will be taken between 4900~62500
Save Images
Show Processing Time
lhint2
0


MMain - version1.8 - 2x4(X40Y60) - [FTeach]
Dashboard
Teach
Engine
1x4(X40)
English
Login
Exit
Reset Training Settings
Reset training settings, Please click to enter the training area after reset.
Image Stitch
Train Area
CV Parameter
Sites Number:
4
The number of identified sites,Please set how many SITES you want to recognize before selecting the training area.
Auto Train
Perform automatic sample selection
Show Training Area
Save Training Settings
Click to select training area
sample size:
50
50
Set sample width,Set sample height
Zoom In
Zoom Out
Current image ratio: 100%
Save Images
Show Processing Time
lhint2
0



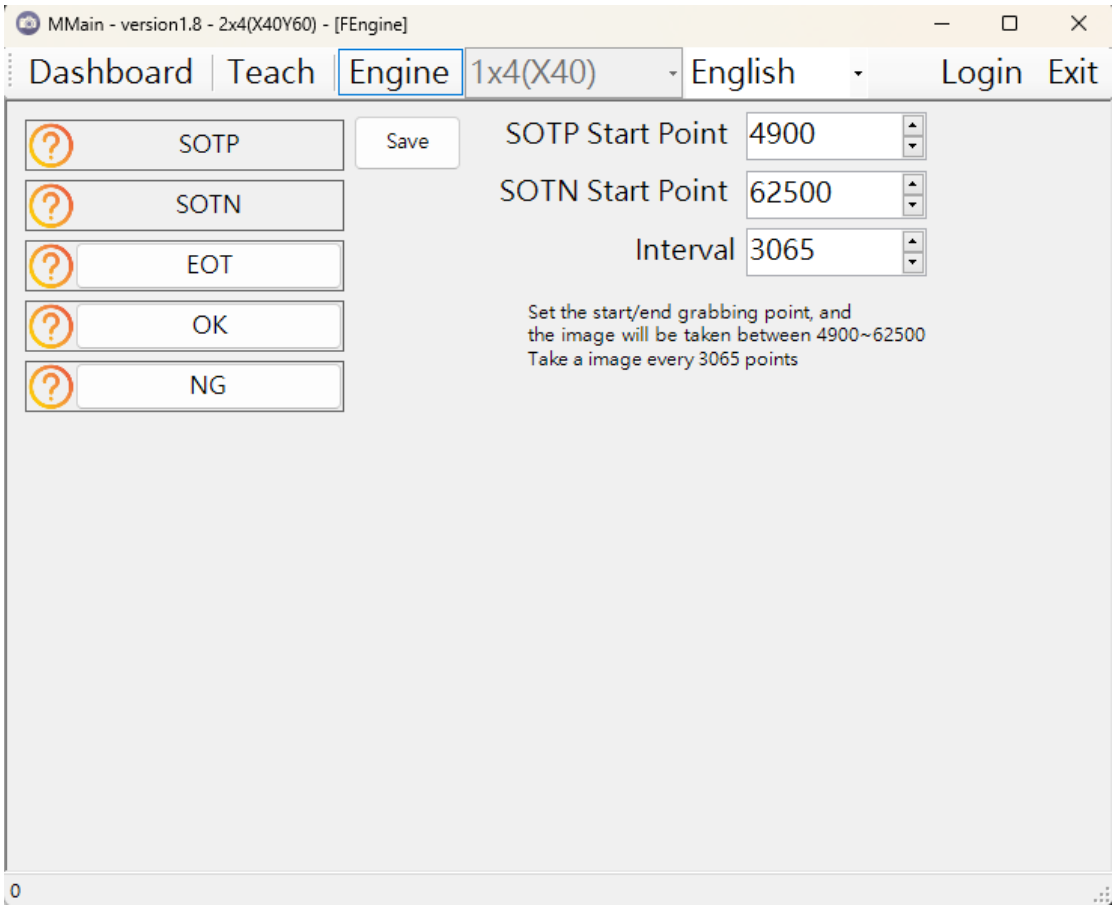
Engine page

Includes the I/O settings (SOTP, SOTN, EOT, OK, NG), SOTP/SOTN start point settings, and grabbing images interval.

*Take the following picture as an example, The CCD will take the images between 4900~62500 point.

1. SOTP ON -> Grab images starting at **4900** point -> Grab one image every **3065** point -> Grab images until **62500** point -> Image processing -> OK/NG -> EOT **(Take approximately** (62500-4900)/3065 = **19 images, and no error will be** reported **if the number of images taken is within 19±3)**

2. SOTN ON -> Grab images starting at **62500** point -> Grab one image every **-3065** point -> Grab images until **4900** point -> Image processing -> OK/NG -> EOT **(Take approximately** (62500-4900)/3065 = **19 images, and no error will be** reported **if the number of images taken is within 19±3)**



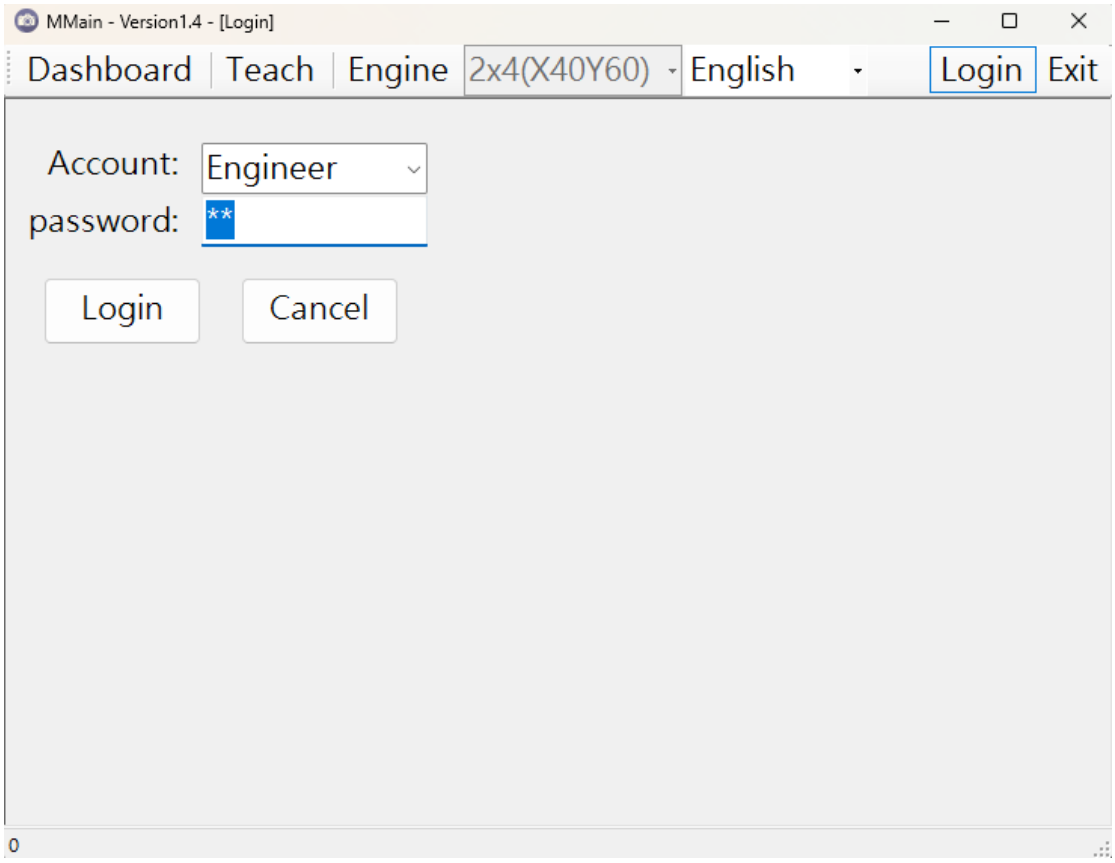
Login page

Login interface, with Engineer and Admin permissions.

Engineer password:39

Admin password:16552978

(Please refrain from logging in as Admin unless necessary.)

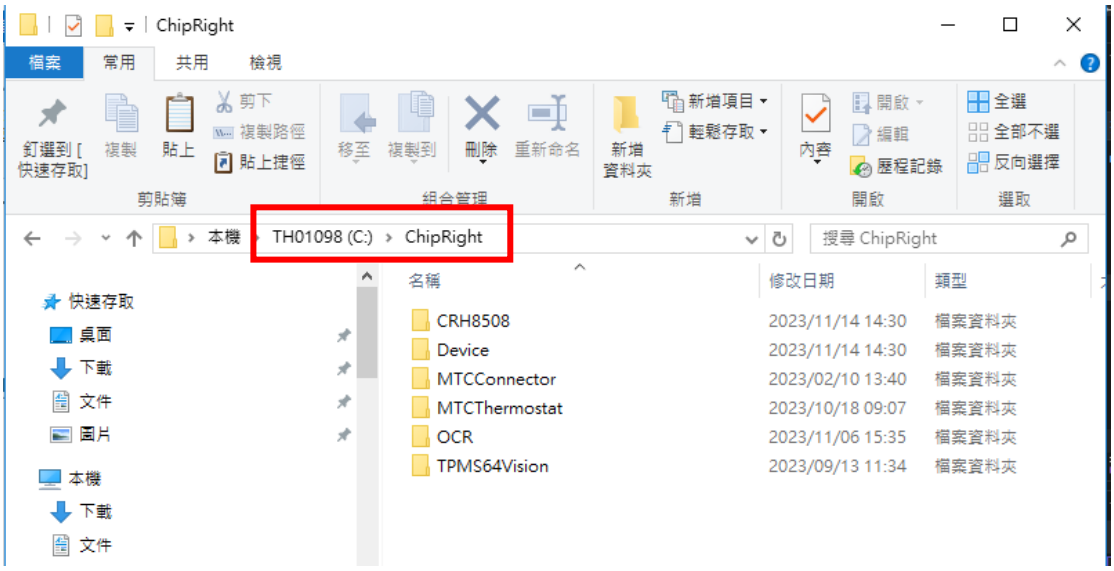

MMain - Version1.4 - [Login]
Dashboard
Teach
Engine
2x4(X40Y60)
English
Login
Exit
Account:
Engineer
password:
**
Login
Cancel
0

CRH8508 SocketVision Training Step

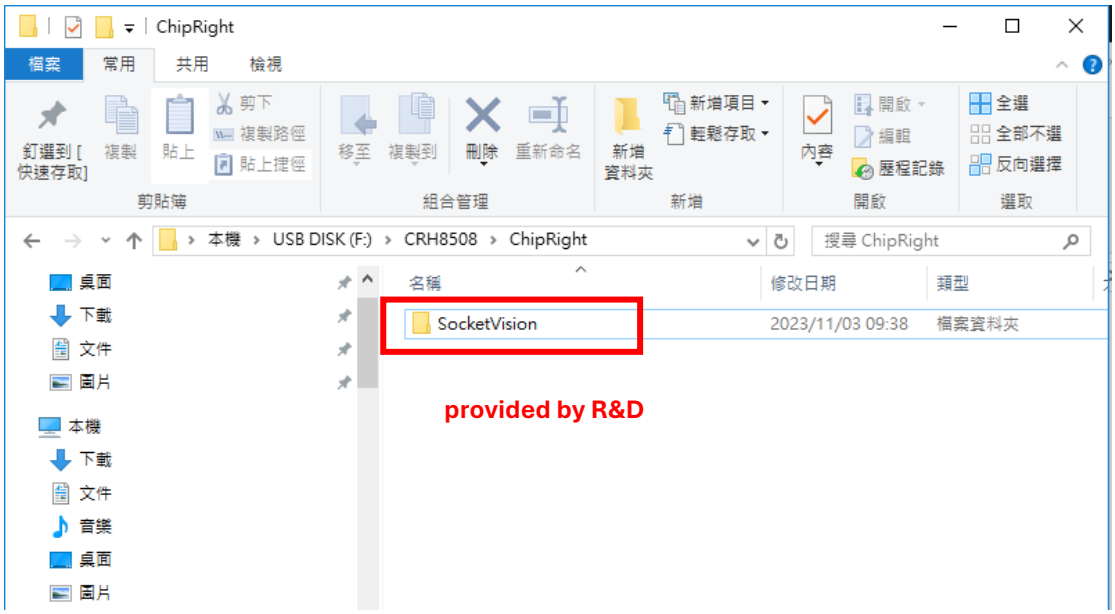
First time using CCD recognition software.

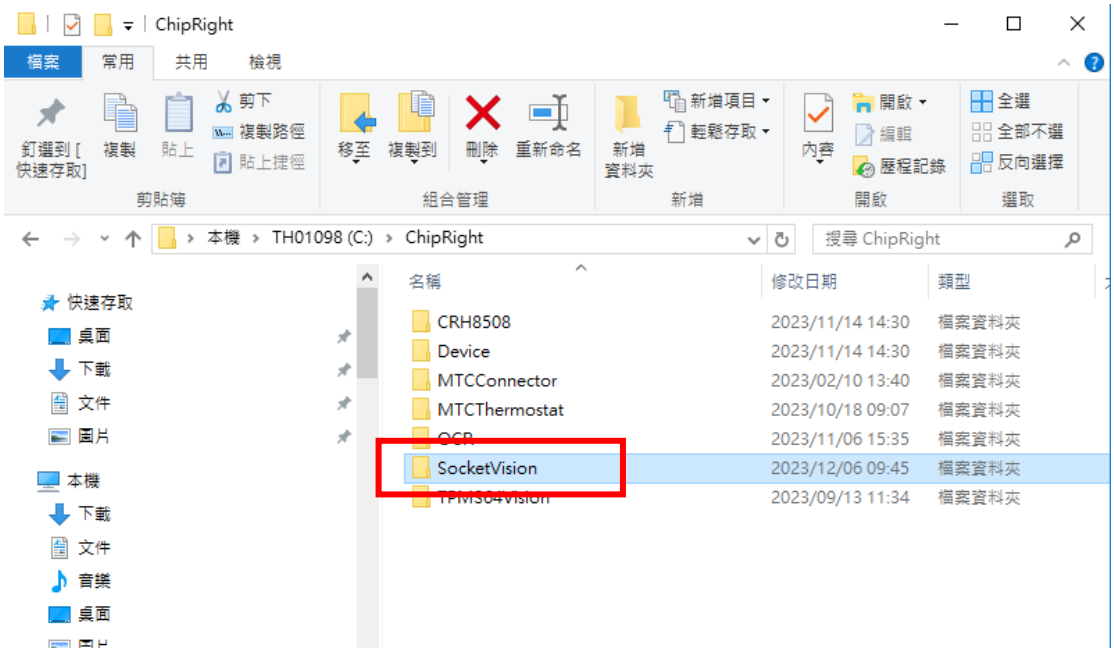
1. Create a folder in **C:/** and name it "ChipRight".

If it already have one here, please skip this step.



2. Copy the folder provided by R&D to **C:/ChipRight**

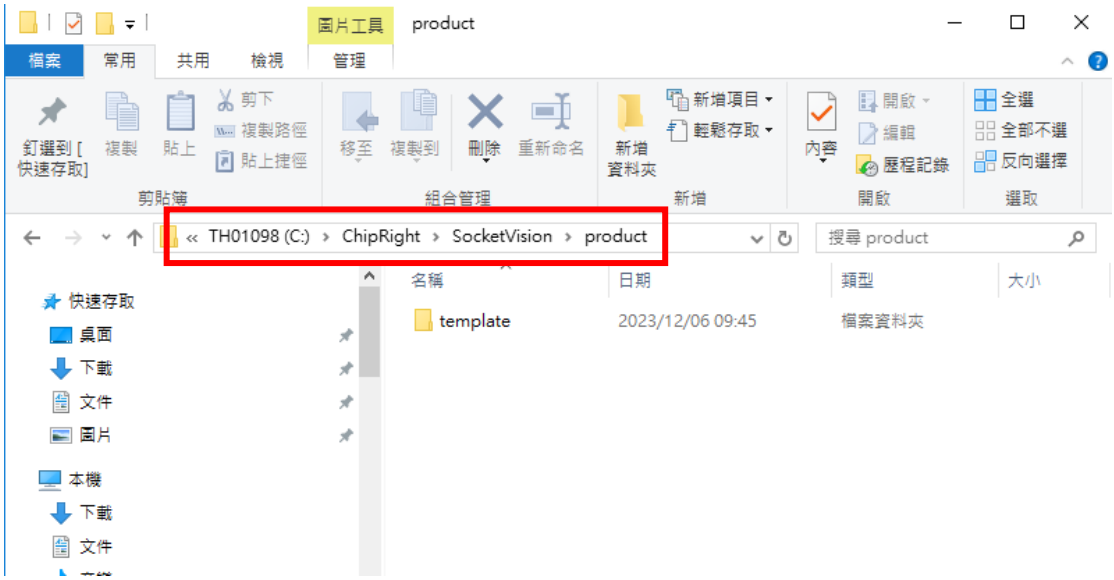


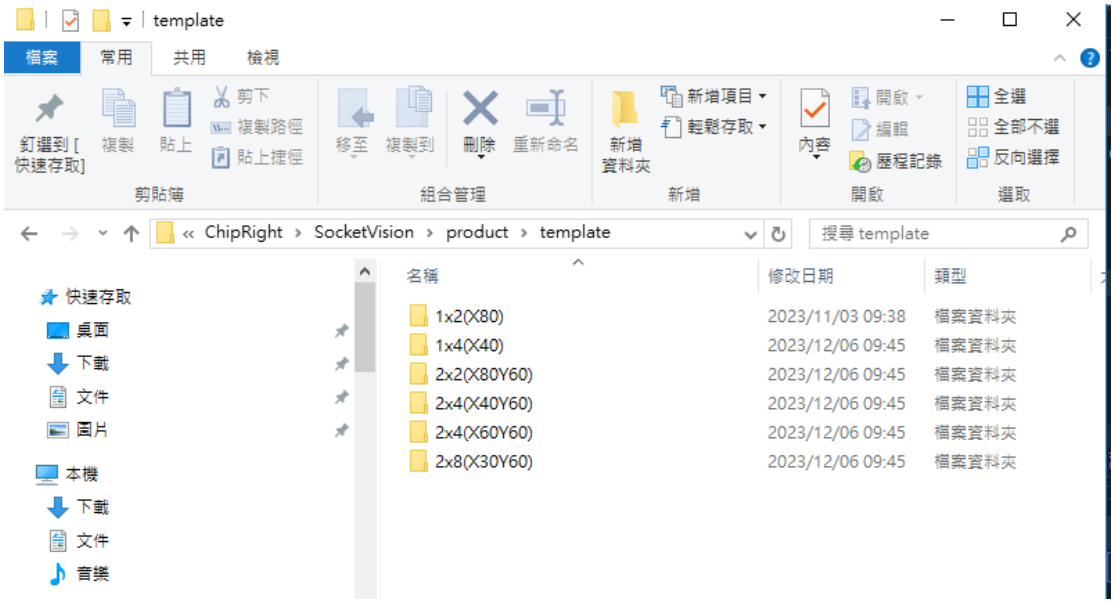


3. Create a new profile, there are two ways to create profile

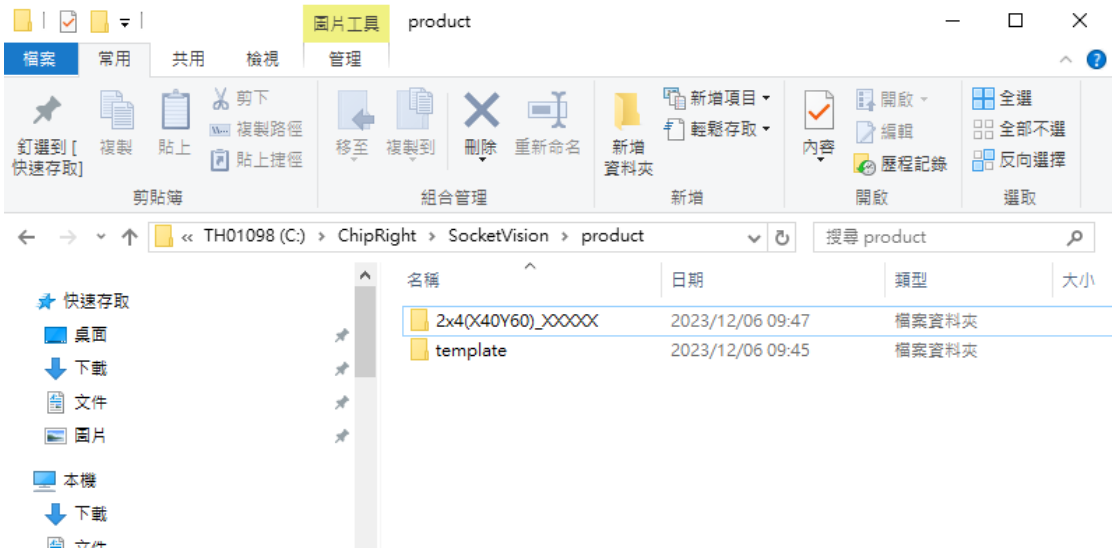
I. Copy the profile in the template folder

Enter the **C:\ChipRight\SocketVision\product** folder and there is a template folder. When you want to train, you can copy several profile files to the **product** folder. DO NOT modify the data in the Template folder.

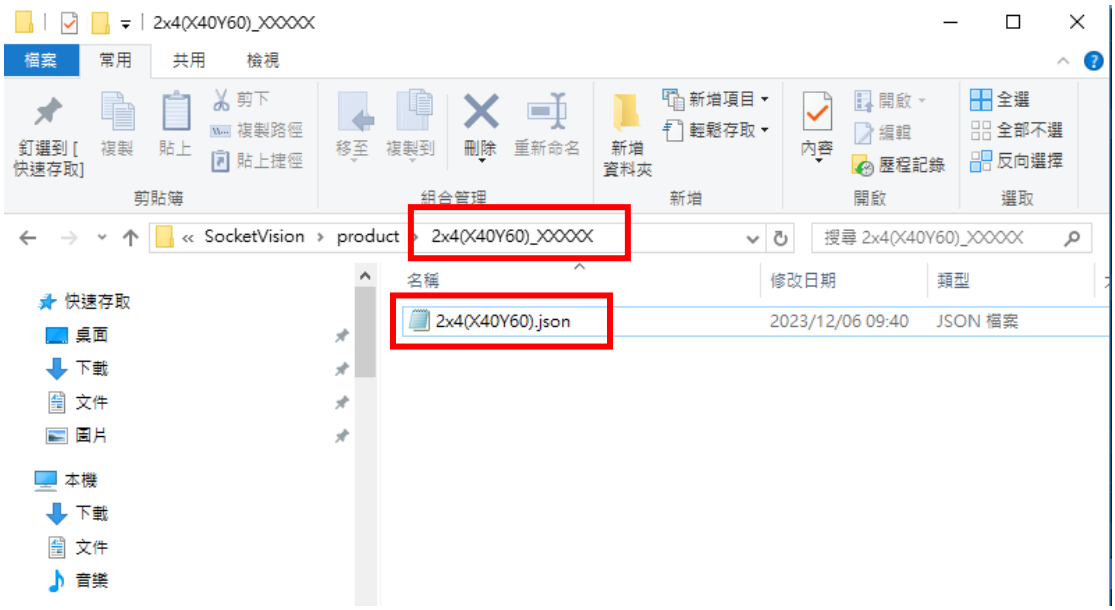


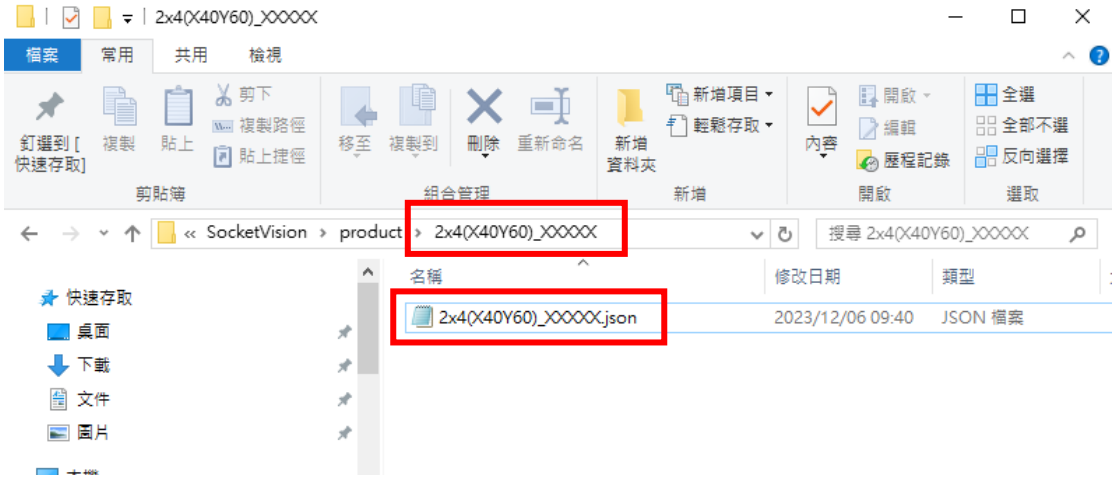


i. Copy the **model**(folder) you want to train and mark which product it corresponds to later to facilitate switching profile files later. Here the brackets are the actual spacing between sockets (unit: mm)

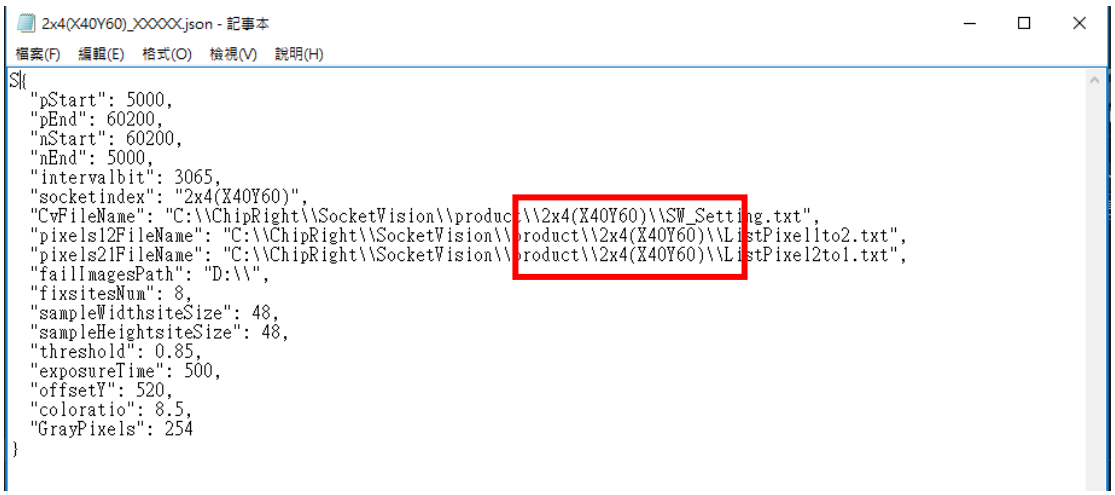


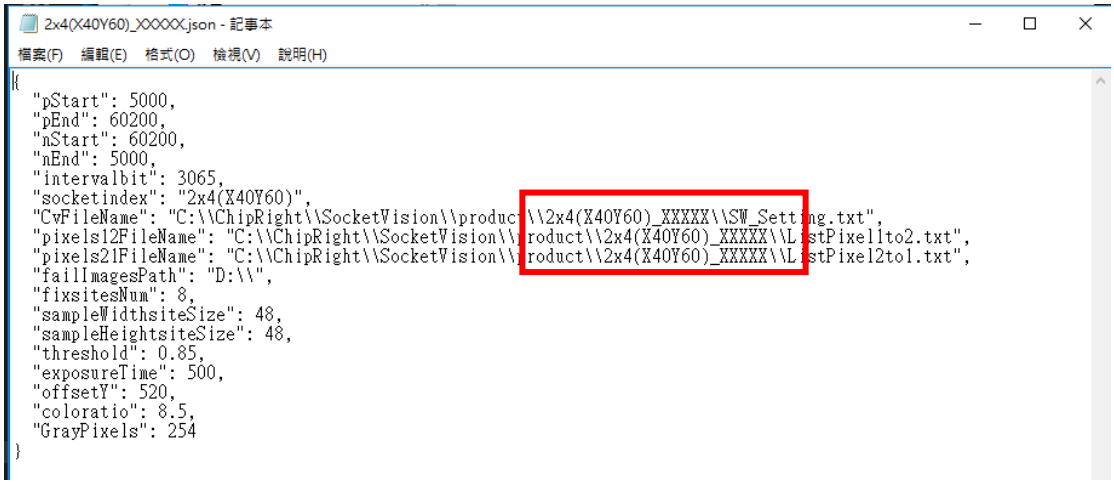
ii. Enter the profile folder and modify the JSON file name to be the same as the folder name.



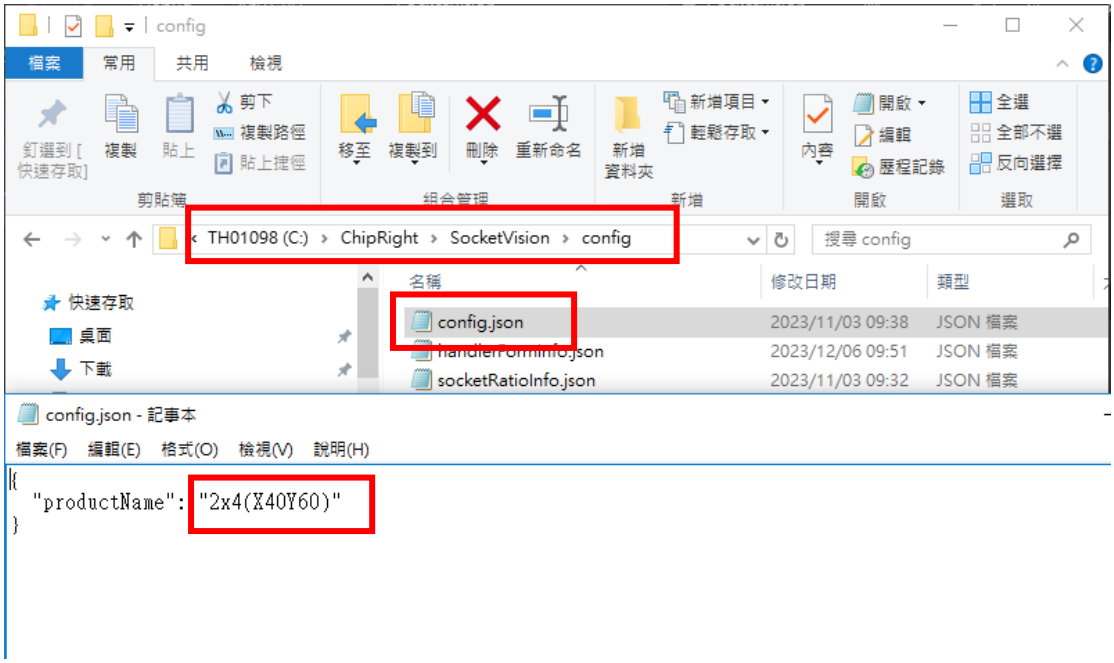


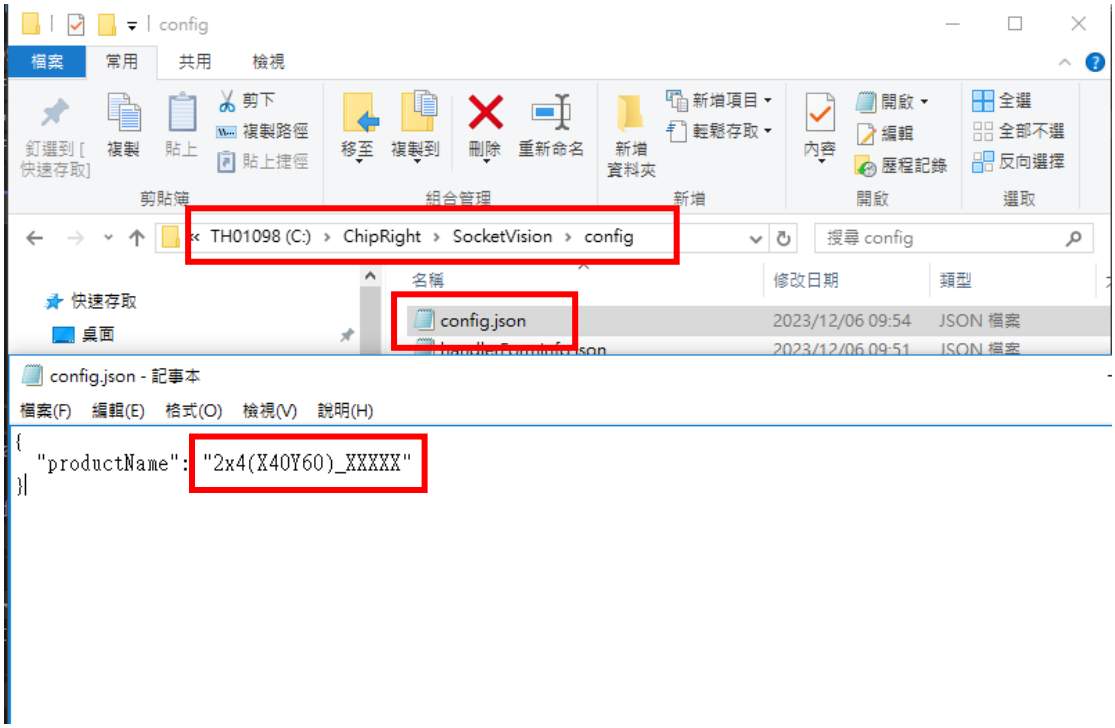
iii. Open the JSON file and modify the path





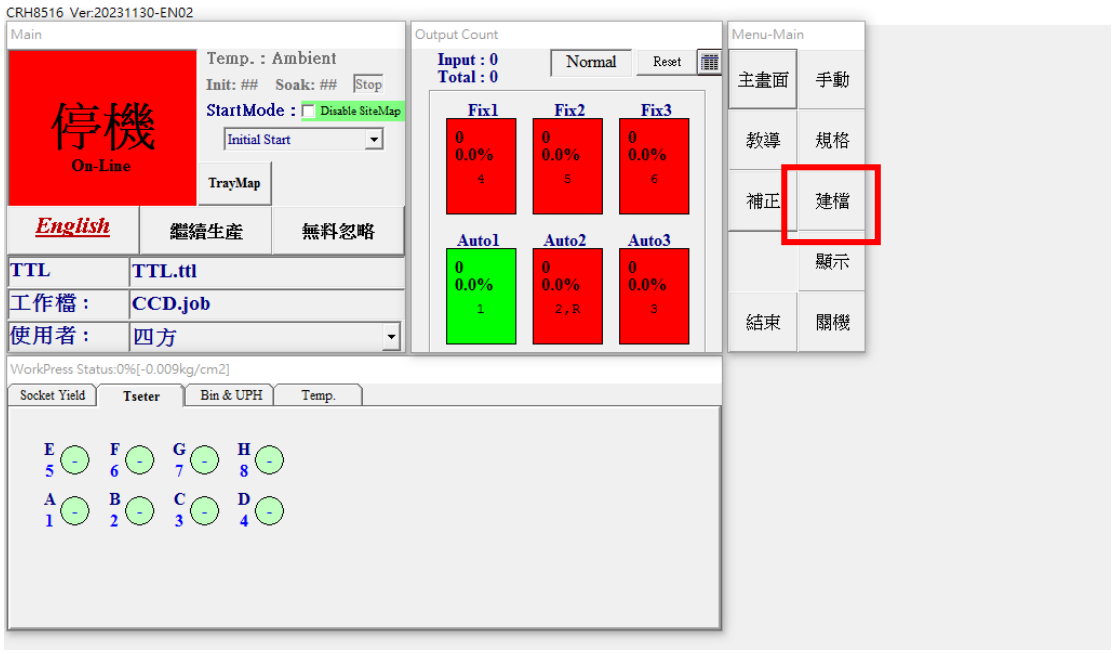
iv. Enter **C:\ChipRight\SocketVision\config**, open the **config.json** file, and change productName to the name of the working file just now

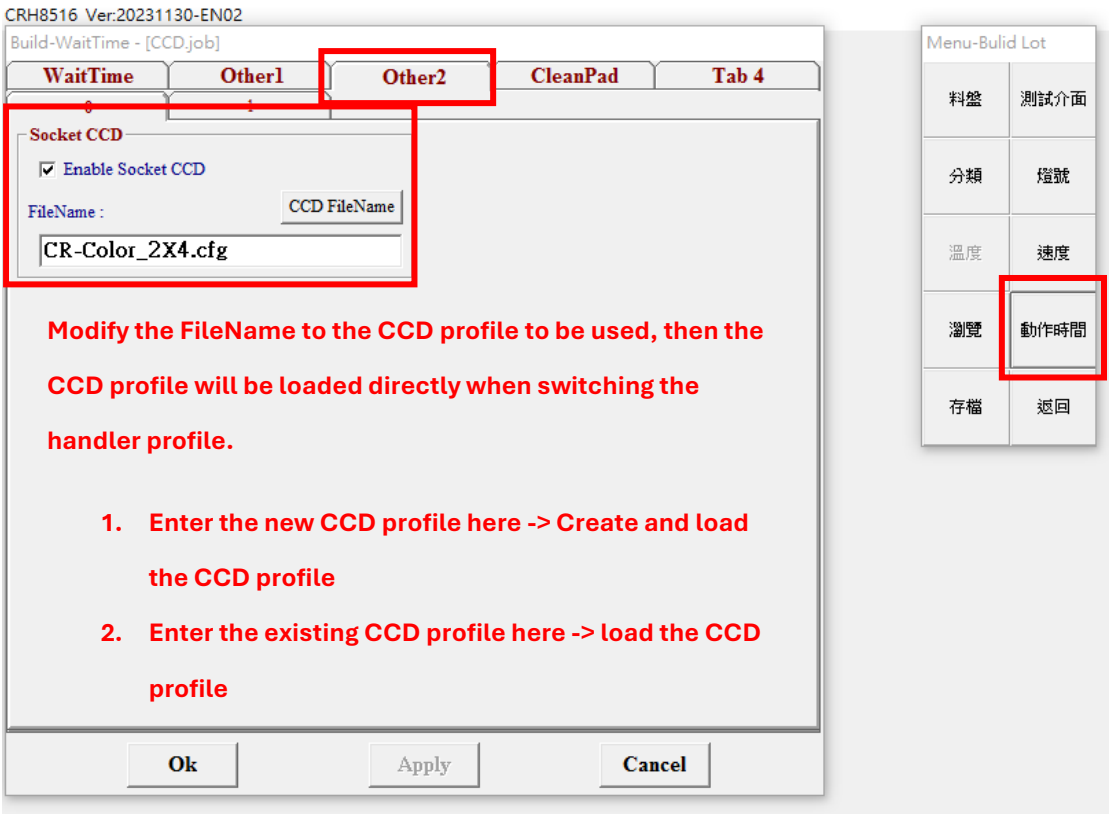




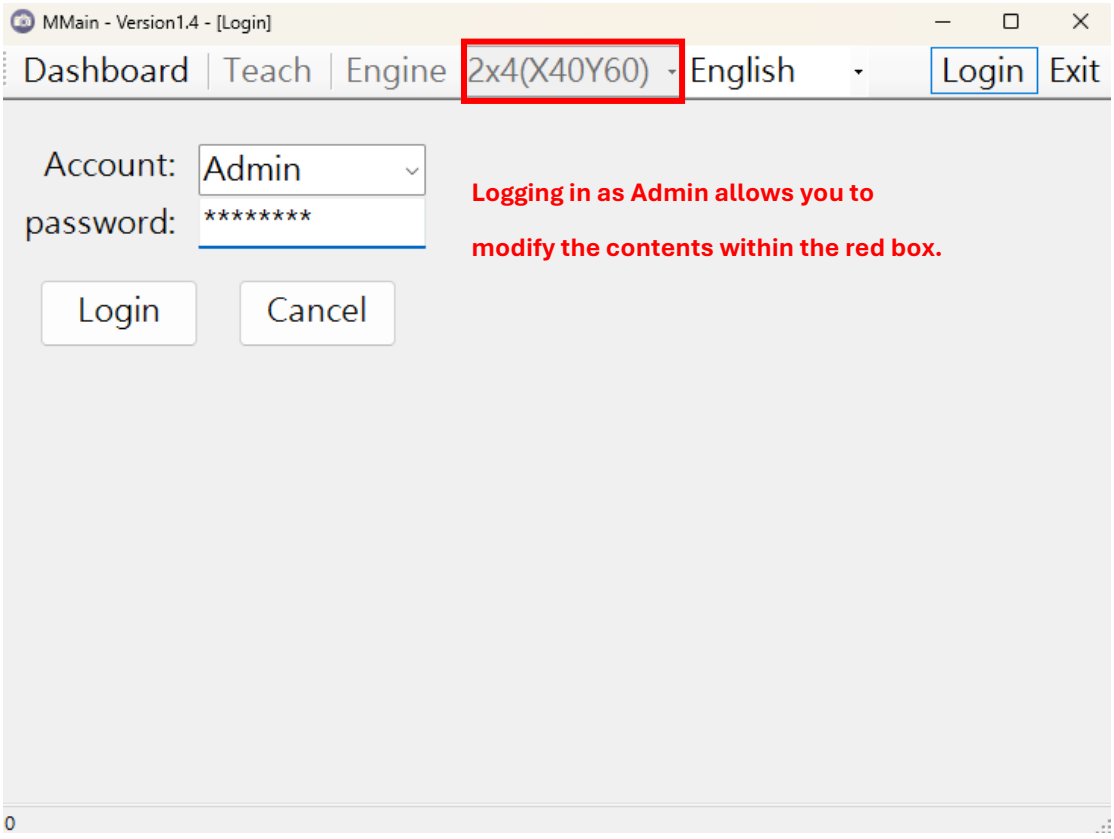
II. Create a new profile in handler

i. Enter in the handler, directly enter the new profile file name

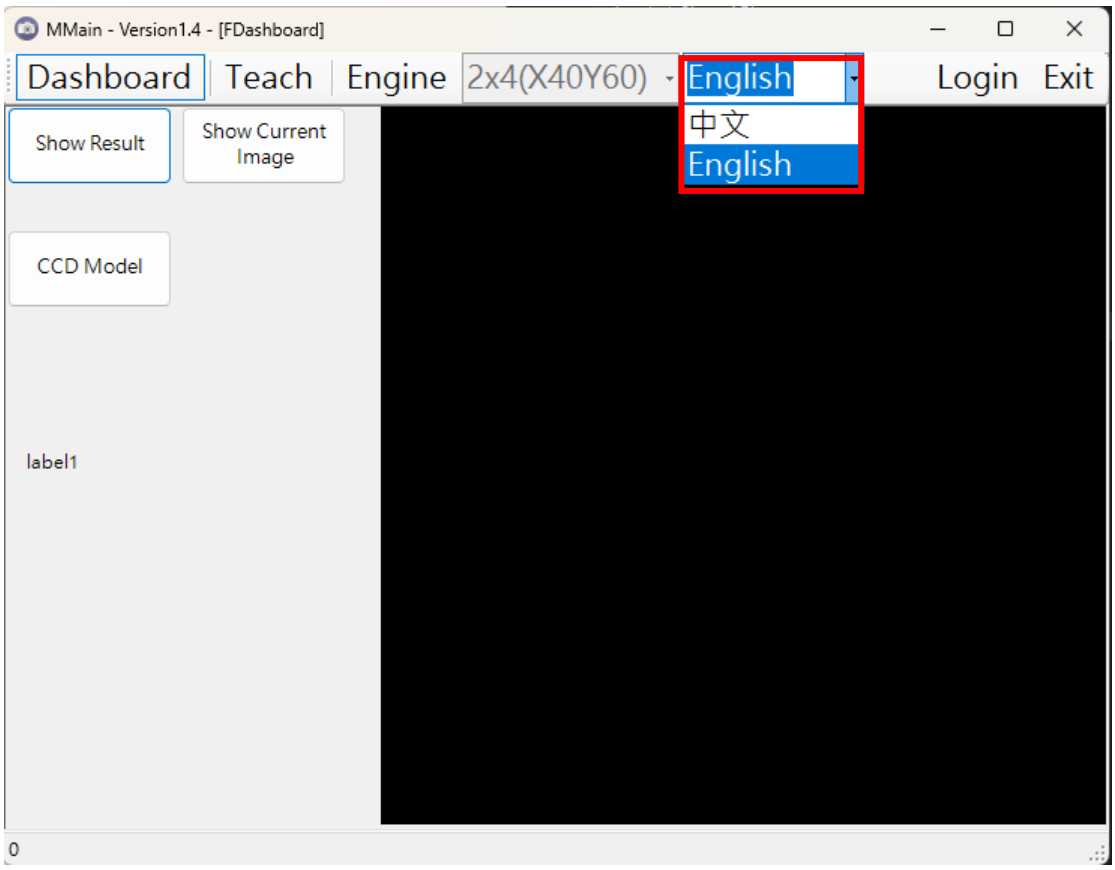




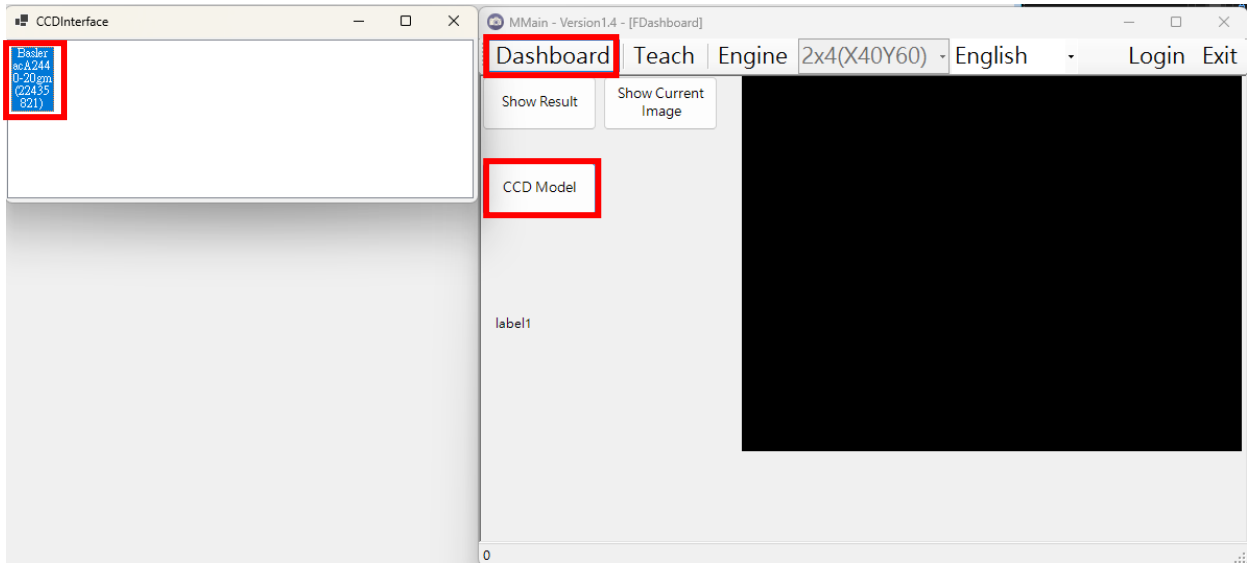
ii. Open the CCD vision software, modify the socket-based type



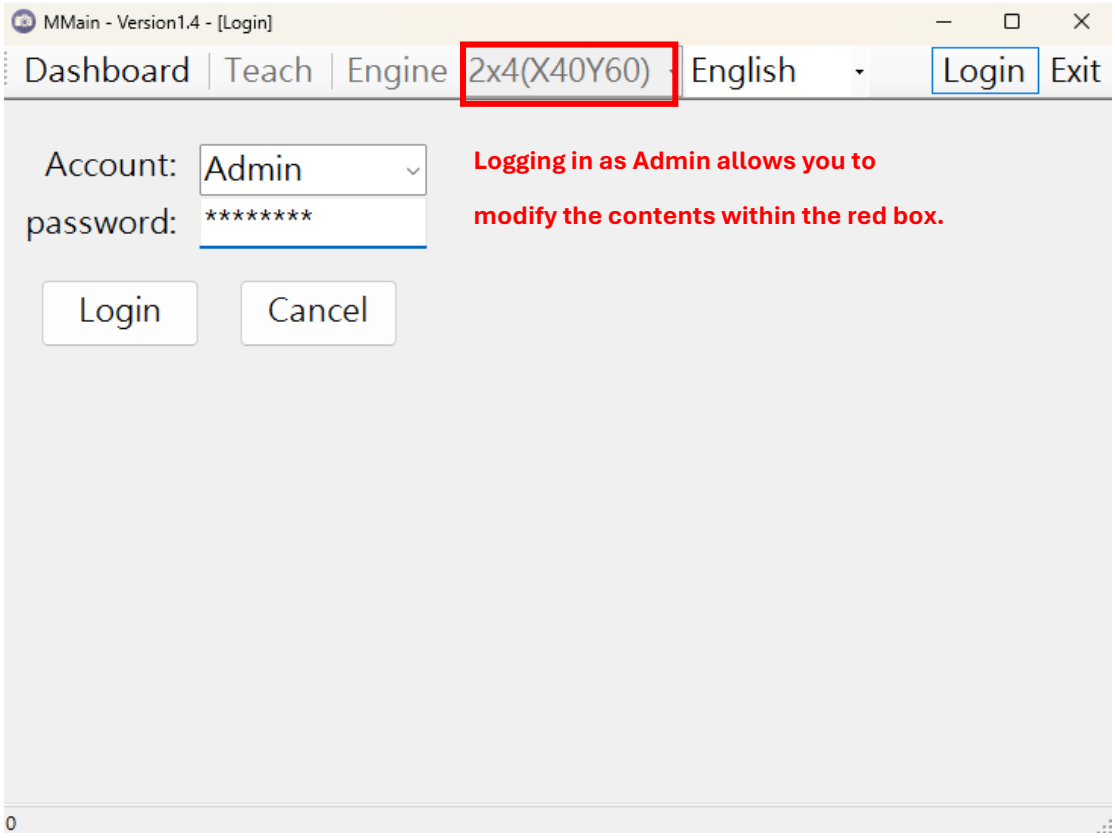
4. Open the CCD vision software and switch the language first.



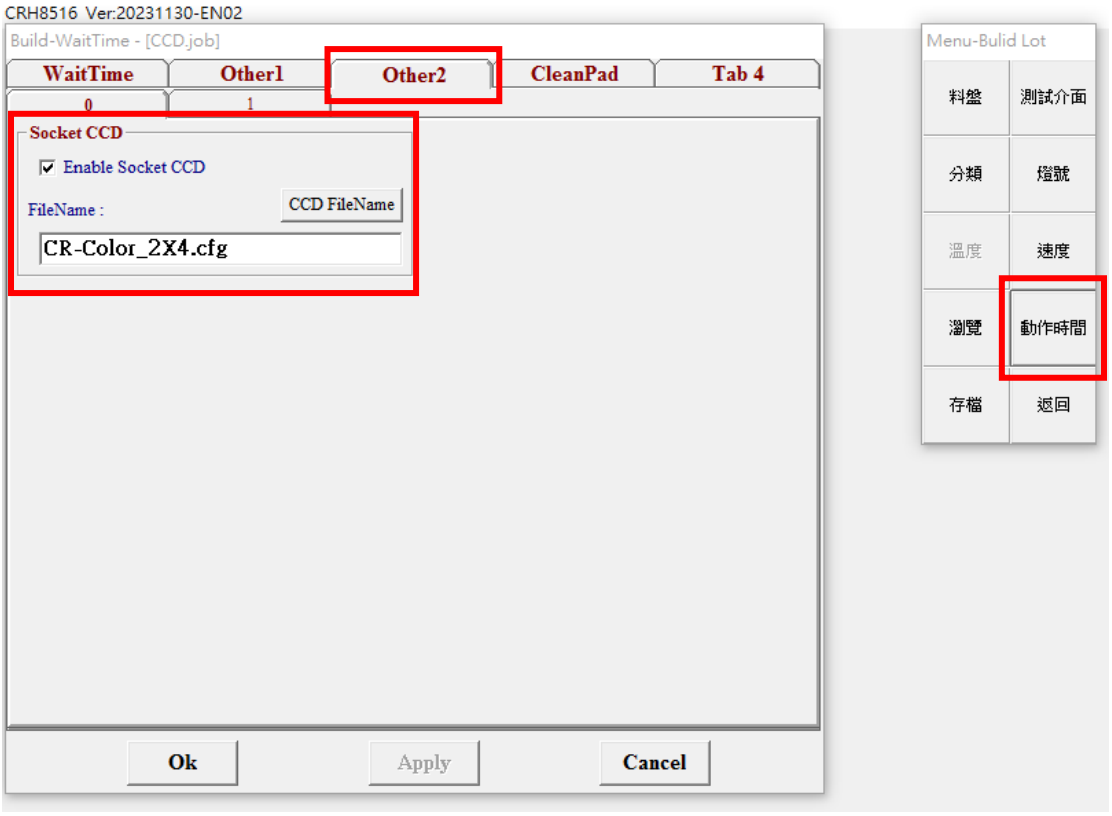
5. Connect the corresponding CCD model.

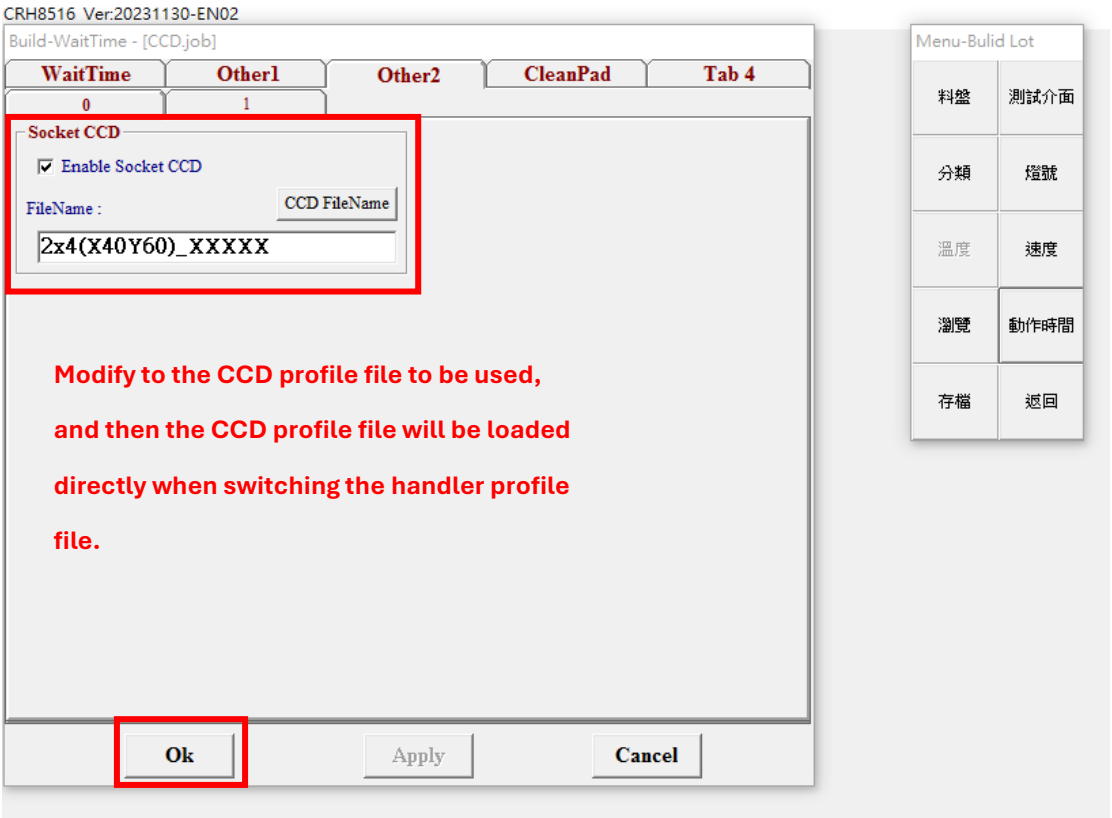


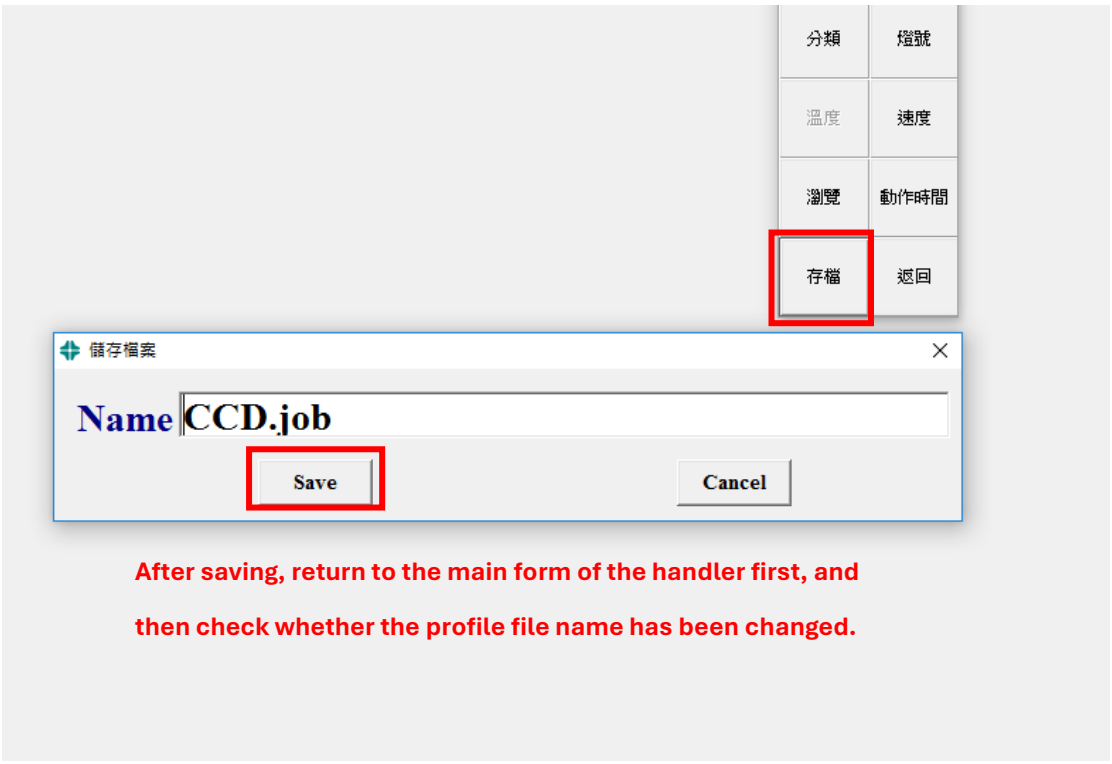
6. You need to log in first. Two levels of authority are set here: Engineer and Admin.



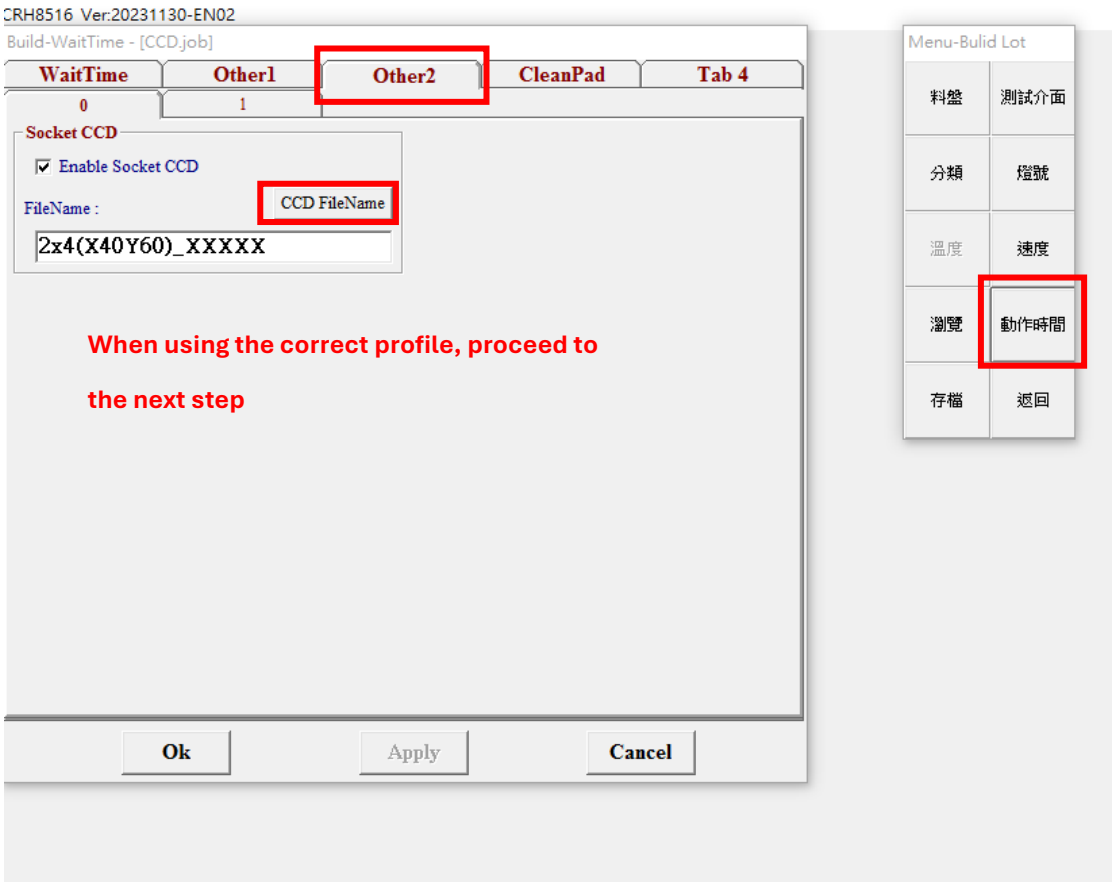
7. Enter the handler and modify the linked CCD profile file


CRH8516 Ver:20231130-EN02
Build-WaitTime - [CCD.job]
WaitTime
Other1
Other2
CleanPad
Tab 4
0
1
Socket CCD
Enable Socket CCD
FileName :
CCD FileName
CR-Color_2X4.cfg
Ok
Apply
Cancel
Menu-Bulid Lot
料盤
測試介面
分類
燈號
溫度
速度
瀏覽
動作時間
存檔
返回


CRH8516 Ver:20231130-EN02
Build-WaitTime - [CCD.job]
WaitTime
Other1
Other2
CleanPad
Tab 4
0
1
Socket CCD
Enable Socket CCD
FileName :
CCD FileName
2x4(X40Y60)_XXXXX
Modify to the CCD profile file to be used,
and then the CCD profile file will be loaded
directly when switching the handler profile
file.
Ok
Apply
Cancel
Menu-Bulid Lot
料盤
測試介面
分類
燈號
溫度
速度
瀏覽
動作時間
存檔
返回



After saving, return to the main form of the handler first, and then check whether the profile file name has been changed.



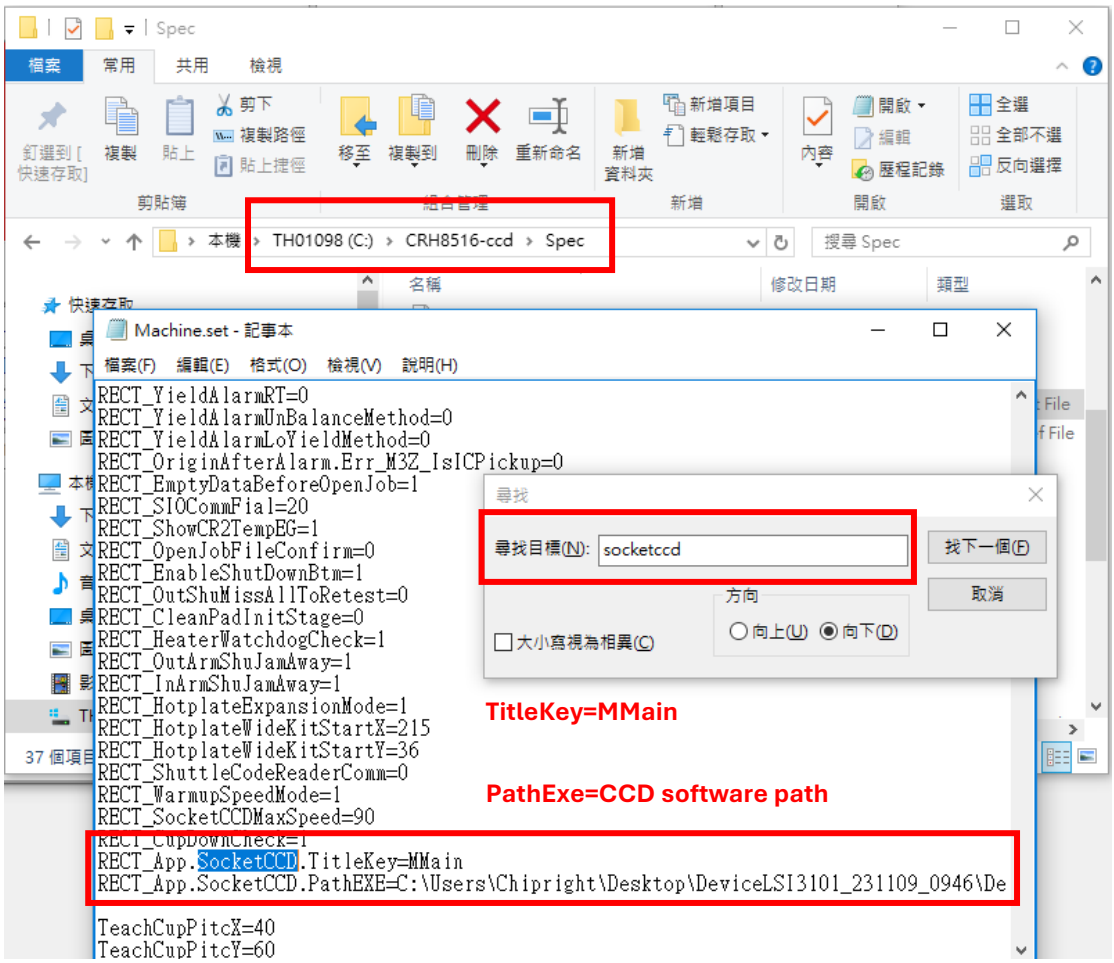
8. Check whether the I/O settings are correct


RH8516 Ver:20231130-EN02
Manual-Group IO
STACK1
STACK2
In/Out Arm
IndexArm
SHUTTLE
KEY PAD
SYSTEM1
SYSTEM2
Heater1
測頭1加熱器1
測頭1加熱器2
測頭1加熱器3
測頭1加熱器4
測頭1加熱器5
測頭1加熱器6
測頭1加熱器7
測頭1加熱器8
測頭2加熱器1
測頭2加熱器2
測頭2加熱器3
測頭2加熱器4
測頭2加熱器5
測頭2加熱器6
測頭2加熱器7
測頭2加熱器8
Heater2
進料梭1加熱器
進料梭2加熱器
預熱區1加熱器
預熱區2加熱器
控溫監視
Socket CCD
視覺正向觸發
視覺反向觸發
視覺測試結果正常
視覺測試結果異常
視覺測試完成
Menu-Manual
卡片IO
馬達
圖示IO
手測
MMain - [FEngine]
Dashboard
Teach
Engine
2x4(X40Y60)
English
Login
SOTP
SOTN
EOT
OK
NG
Save
SOTP Start Point
5000
SOTN Start Point
60200
Interval
3065


RH8516 Ver:20231130-EN02
Manual-Group IO
STACK1
STACK2
In/Out Arm
IndexArm
SHUTTLE
KEY PAD
SYSTEM1
SYSTEM2
Heater1
測頭1加熱器1
測頭1加熱器2
測頭1加熱器3
測頭1加熱器4
測頭1加熱器5
測頭1加熱器6
測頭1加熱器7
測頭1加熱器8
測頭2加熱器1
測頭2加熱器2
測頭2加熱器3
測頭2加熱器4
測頭2加熱器5
測頭2加熱器6
測頭2加熱器7
測頭2加熱器8
Heater2
進料梭1加熱器
進料梭2加熱器
預熱區1加熱器
預熱區2加熱器
控溫監視
Socket CCD
視覺正向觸發
視覺反向觸發
視覺測試結果正常
視覺測試結果異常
視覺測試完成
Menu-Manual
卡片IO
馬達
圖示IO
手測
MMain - [FEngine]
Dashboard
Teach
Engine
2x4(X40Y60)
English
Login
SOTP
SOTN
EOT
OK
NG
Save
SOTP Start Point
5000
SOTN Start Point
60200
Interval
3065

9. Confirm whether the Handler's CCD button is connected to the correct path.

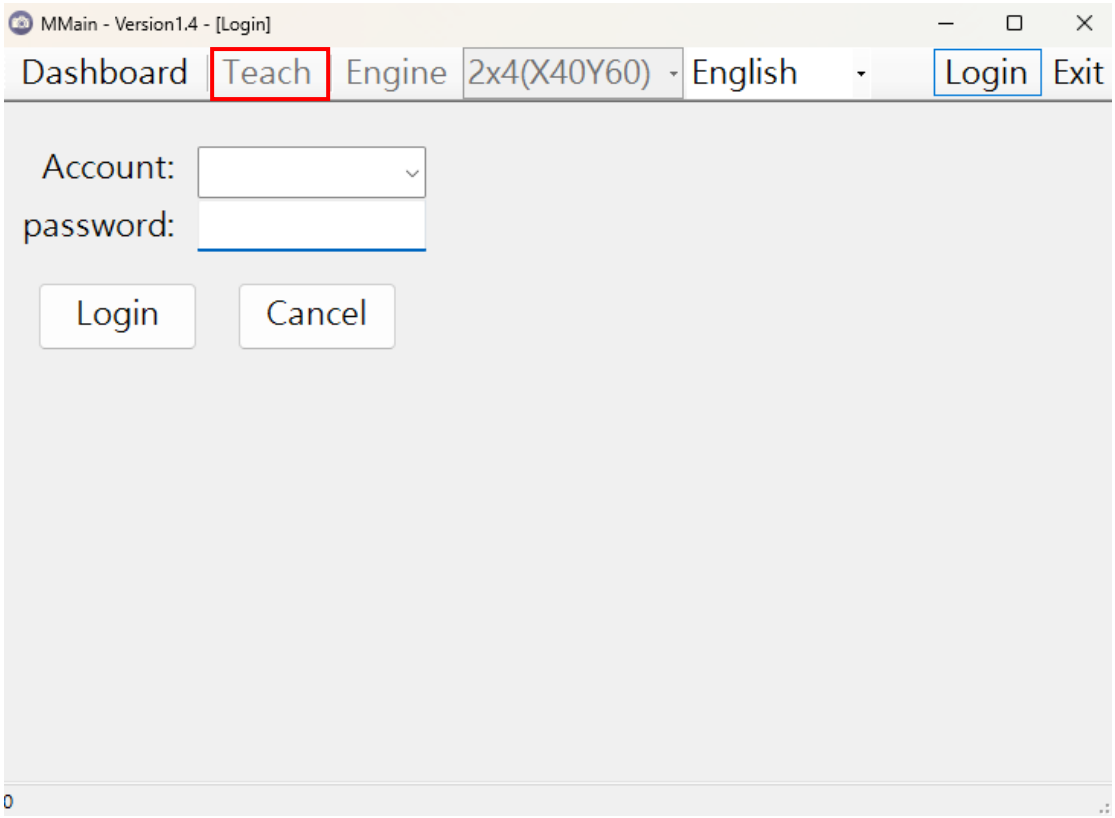
(Note: If there are any changes here, you need to restart the handler)

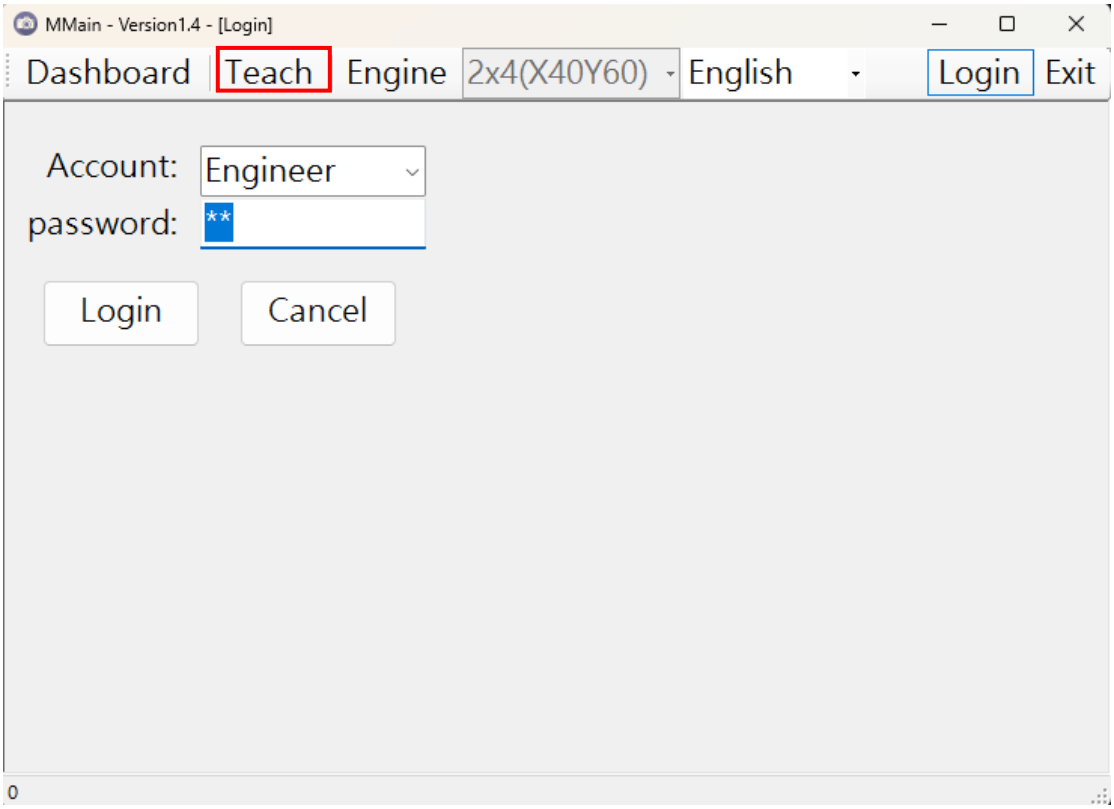

Spec
檔案
常用
共用
檢視
本機 › TH01098 (C:) › CRH8516-ccd › Spec
搜尋 Spec
名稱
修改日期
類型
Machine.set - 記事本
檔案(F) 編輯(E) 格式(O) 檢視(V) 說明(H)
RECT_YieldAlarmRT=0
RECT_YieldAlarmUnBalanceMethod=0
RECT_YieldAlarmLoYieldMethod=0
RECT_OriginAfterAlarm.Err_M3Z_IsICPickup=0
RECT_EmptyDataBeforeOpenJob=1
RECT_SIOCommFial=20
RECT_ShowCR2TempEG=1
RECT_OpenJobFileConfirm=0
RECT_EnableShutDownBtm=1
RECT_OutShuMissAllToRetest=0
RECT_CleanPadInitStage=0
RECT_HeaterWatchdogCheck=1
RECT_OutArmShuJamAway=1
RECT_InArmShuJamAway=1
RECT_HotplateExpansionMode=1
RECT_HotplateWideKitStartX=215
RECT_HotplateWideKitStartY=36
RECT_ShuttleCodeReaderComm=0
RECT_WarmupSpeedMode=1
RECT_SocketCCDMaxSpeed=90
RECT_CupDownCheck=1
RECT_App.SocketCCD.TitleKey=MMain
RECT_App.SocketCCD.PathEXE=C:\Users\Chipright\Desktop\DeviceLSI3101_231109_0946\De
TeachCupPitcX=40
TeachCupPitcY=60
尋找
尋找目標(N): socketccd
找下一個(F)
取消
方向
向上(U)
向下(D)
大小寫視為相異(C)
TitleKey=MMain
PathExe=CCD software path

Training Step

log in

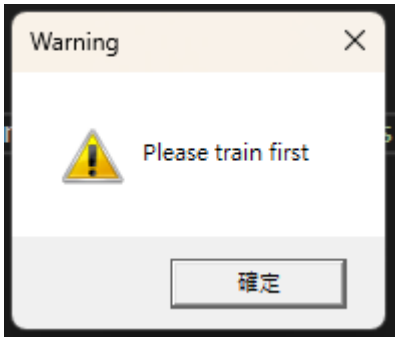
You need to log in first to have the permission to access the training interface.



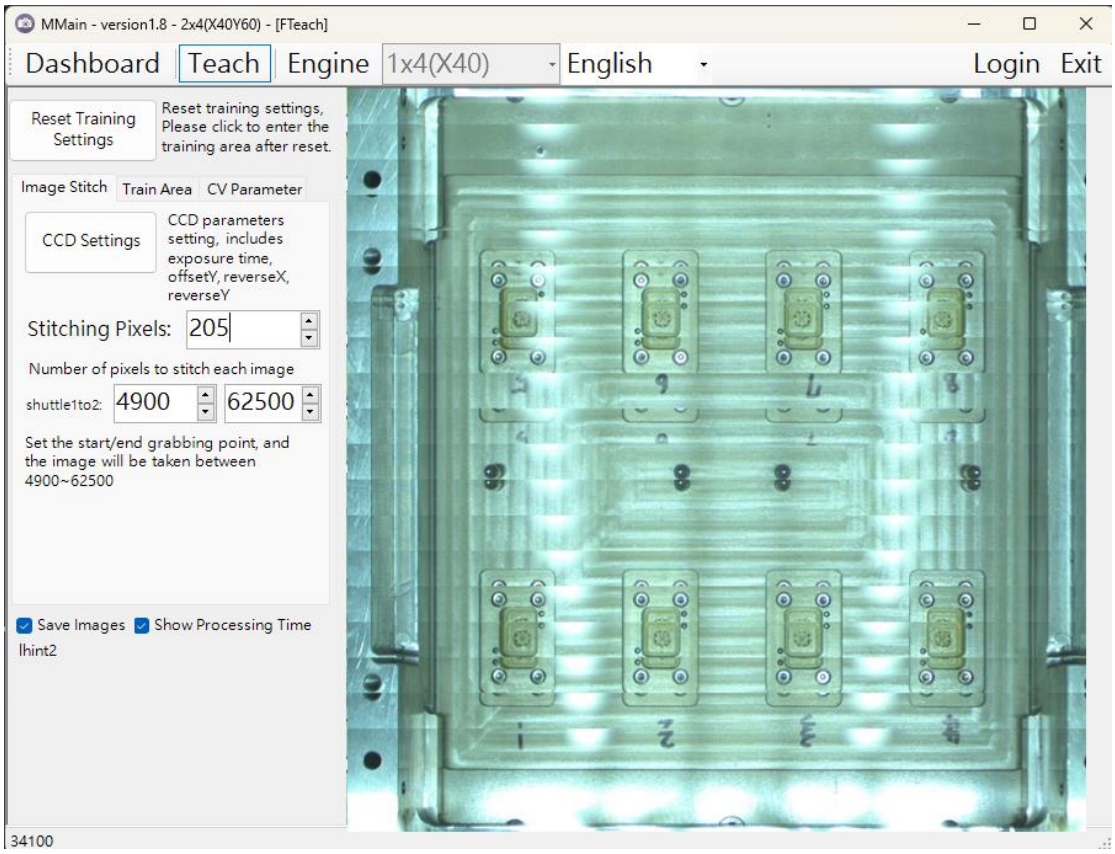


Training with CCD Recognition Software

I. Move the shuttle first.



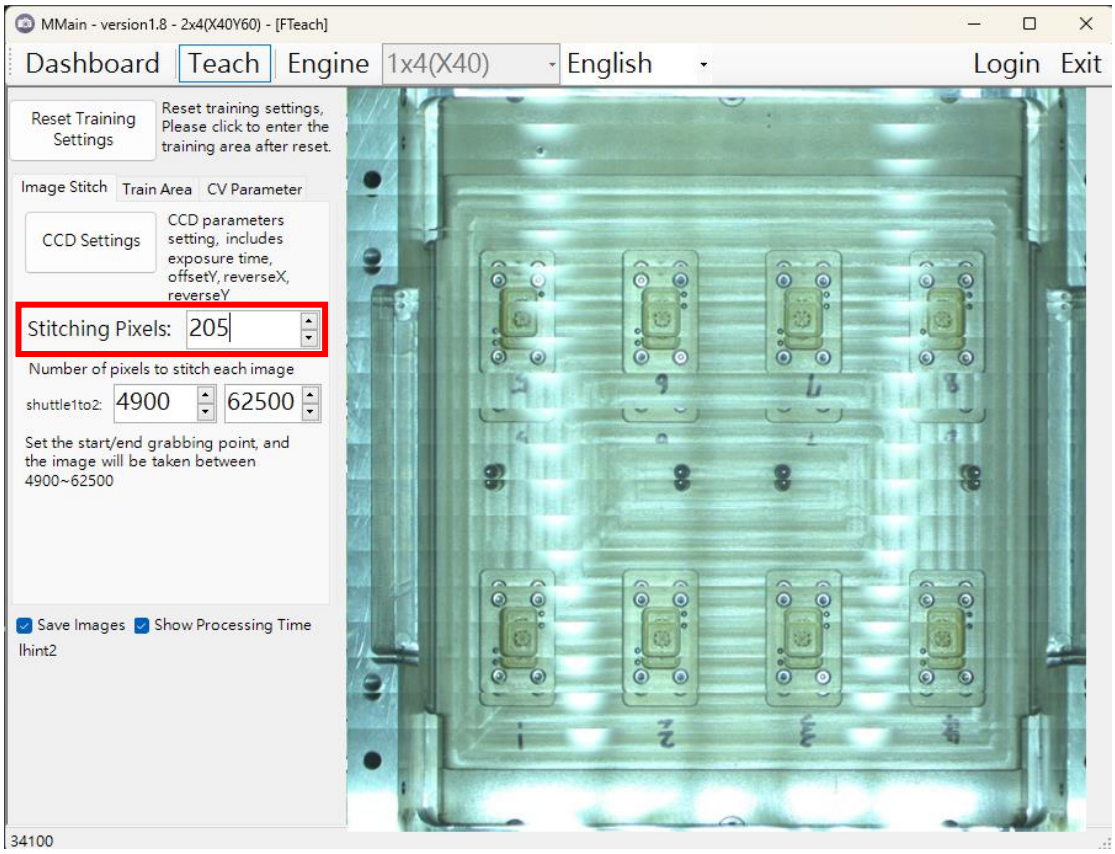
II. Close the warning window before seeing the stitching image.

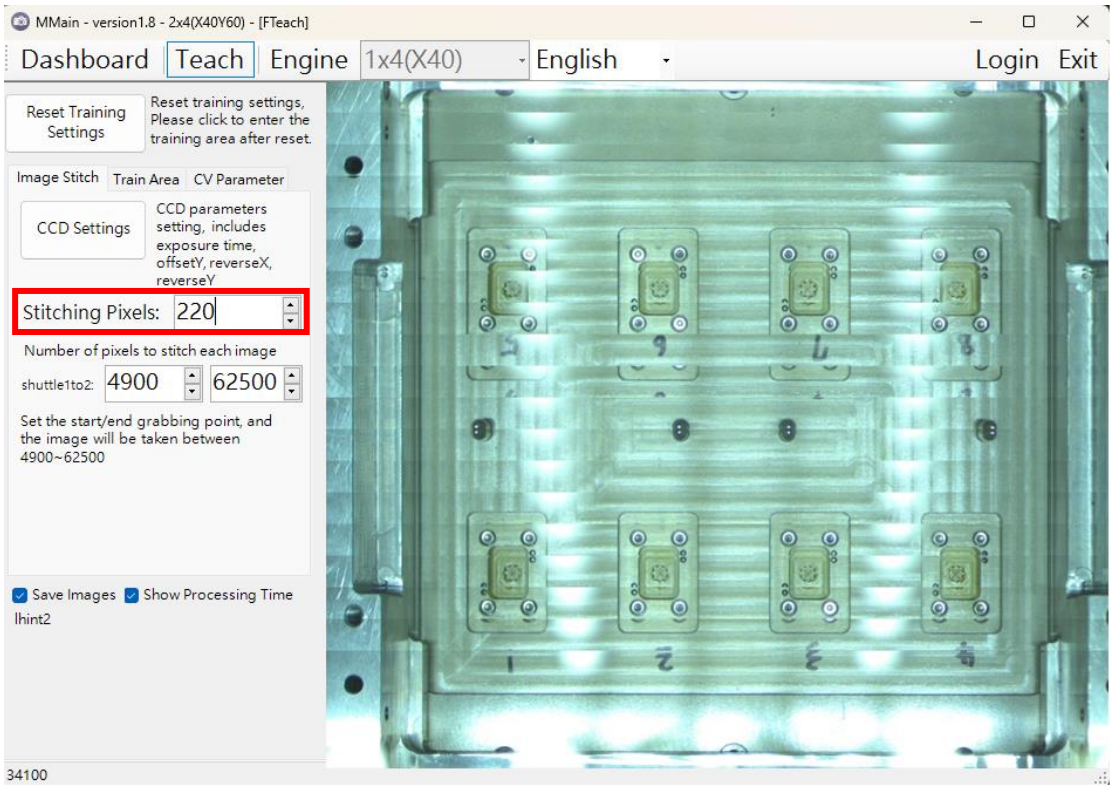


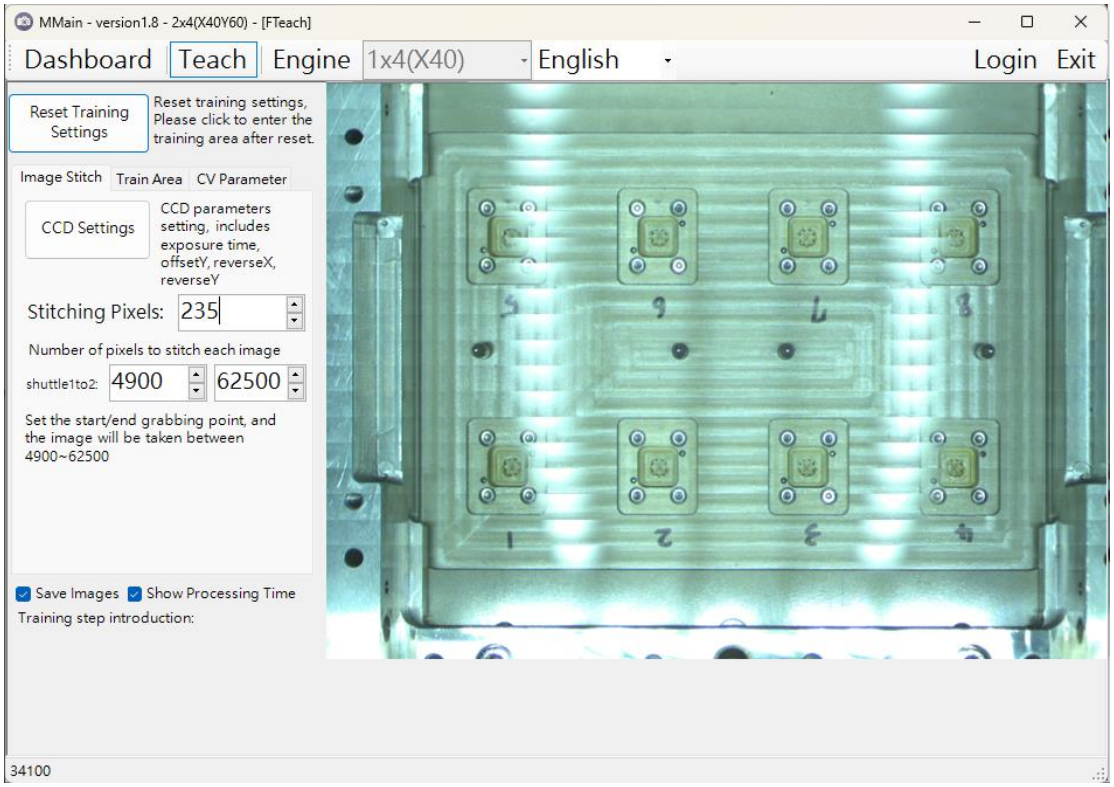
III. Image Stitching Settings

i. You can see that the proportion of the result is incorrect. Adjust the "Stitching Pixels"

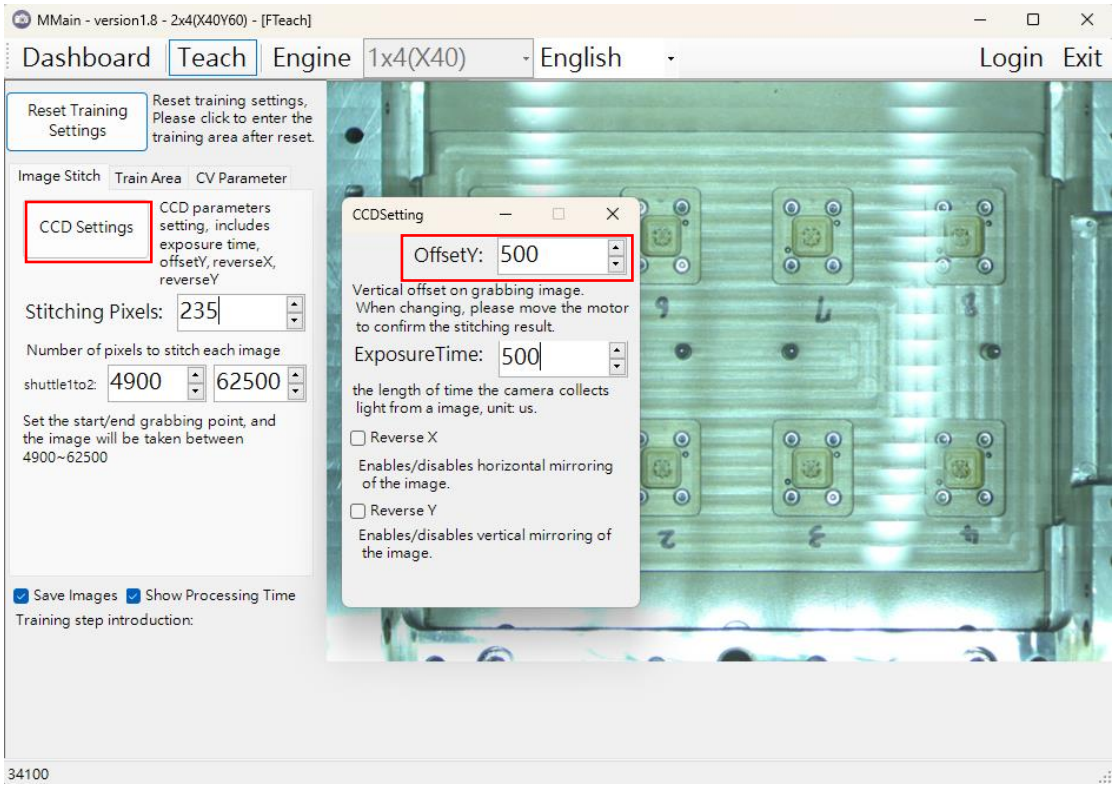
You can see the stitching results immediately

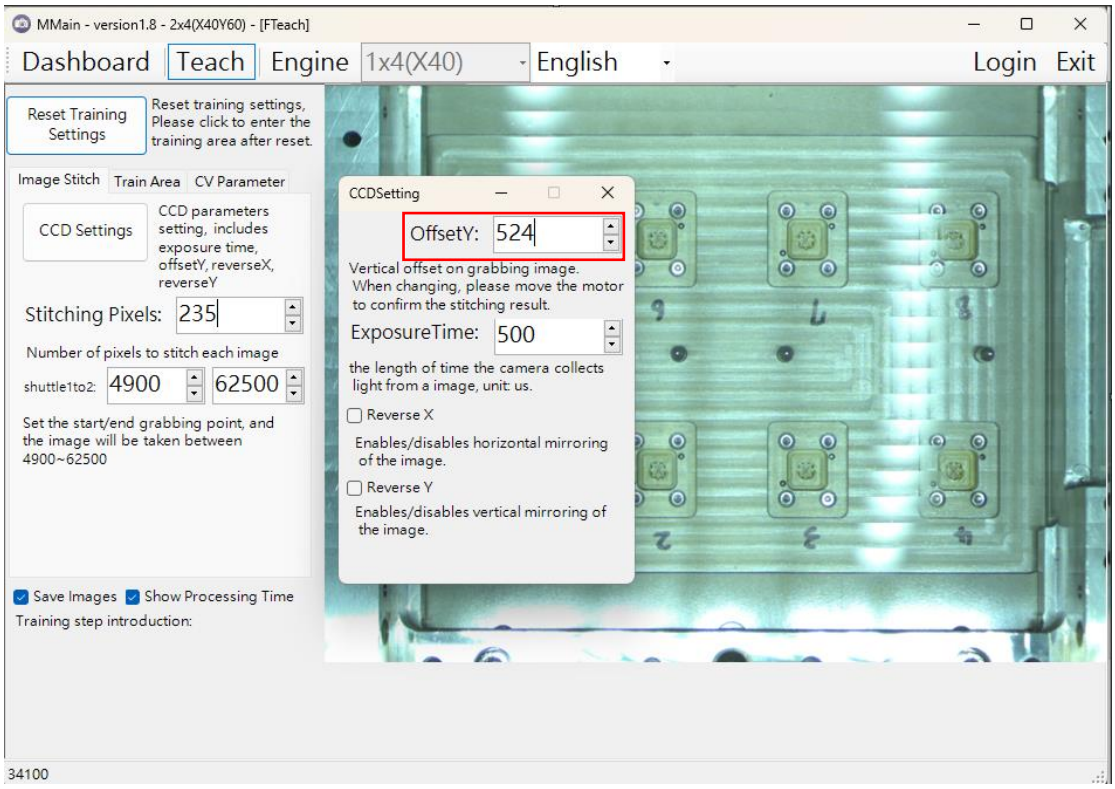

MMain - version1.8 - 2x4(X40Y60) - [FTeach]
Dashboard
Teach
Engine
1x4(X40)
English
Login
Exit
Reset Training Settings
Reset training settings, Please click to enter the training area after reset.
Image Stitch
Train Area
CV Parameter
CCD Settings
CCD parameters setting, includes exposure time, offsetY, reverseX, reverseY
Stitching Pixels: 205
Number of pixels to stitch each image
shuttle1to2: 4900 62500
Set the start/end grabbing point, and the image will be taken between 4900~62500
Save Images
Show Processing Time
lhint2
34100


MMain - version1.8 - 2x4(X40Y60) - [FTeach]
Dashboard
Teach
Engine
1x4(X40)
English
Login
Exit
Reset Training Settings
Reset training settings, Please click to enter the training area after reset.
Image Stitch
Train Area
CV Parameter
CCD Settings
CCD parameters setting, includes exposure time, offsetY, reverseX, reverseY
Stitching Pixels: 220
Number of pixels to stitch each image
shuttle1to2: 4900 62500
Set the start/end grabbing point, and the image will be taken between 4900~62500
Save Images
Show Processing Time
lhint2
34100

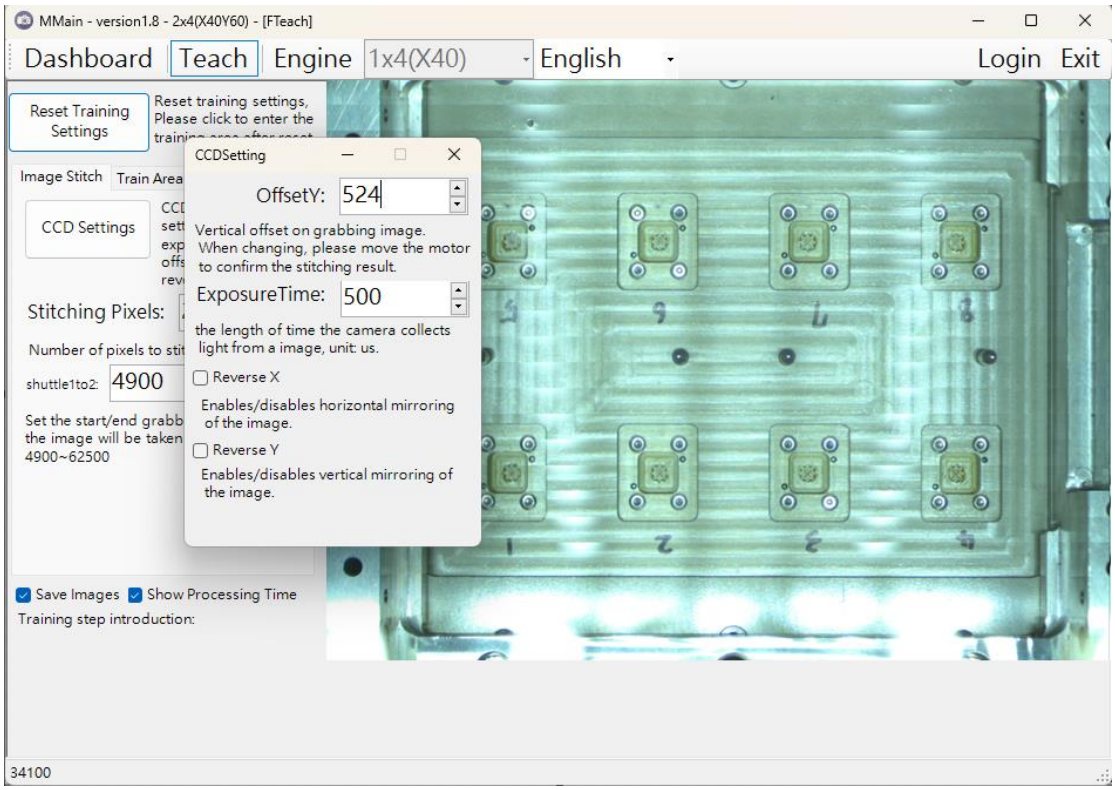


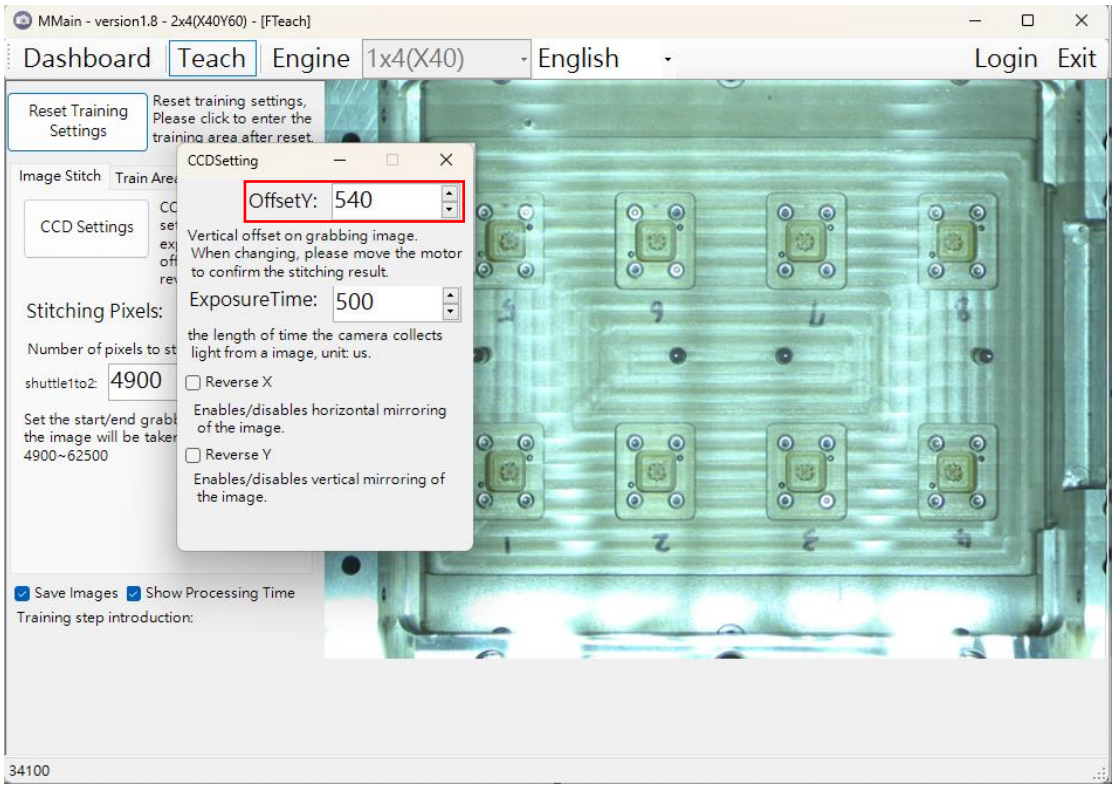
ii. You can clearly see that there are splicing lines one by one. Adjust the OffsetY here to try to make the lighting in the middle of the image.



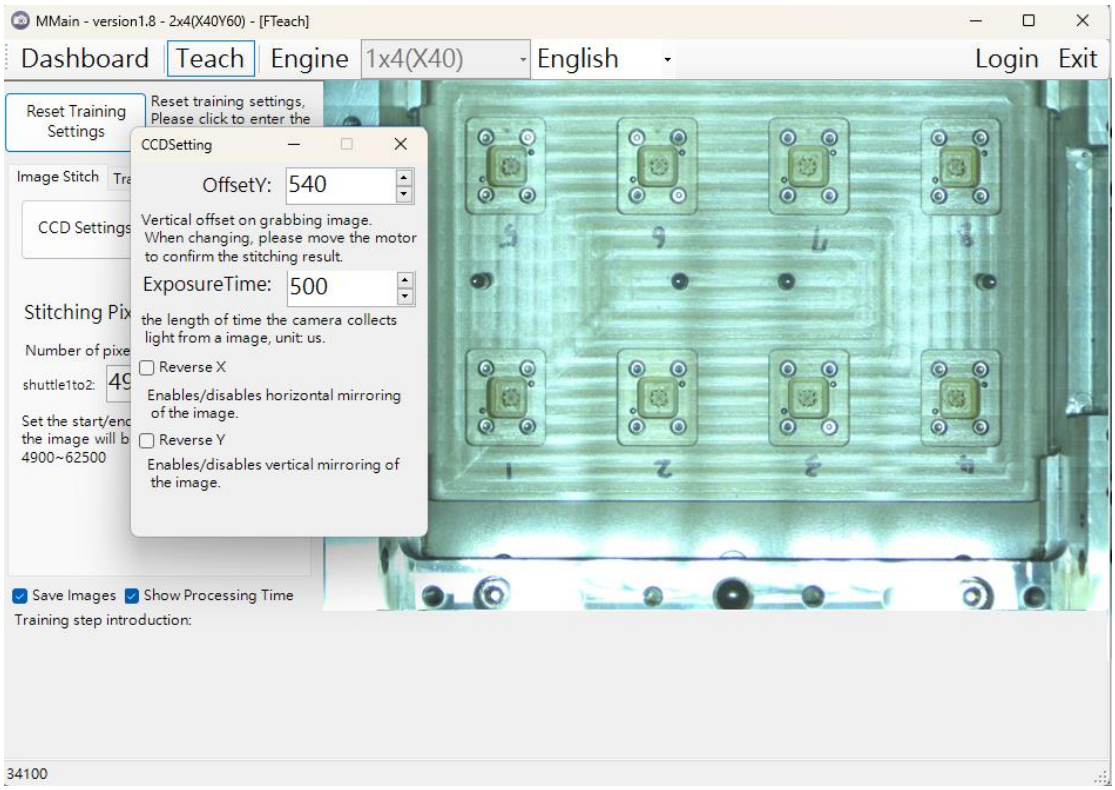


Move the shuttle and see the stitching image result

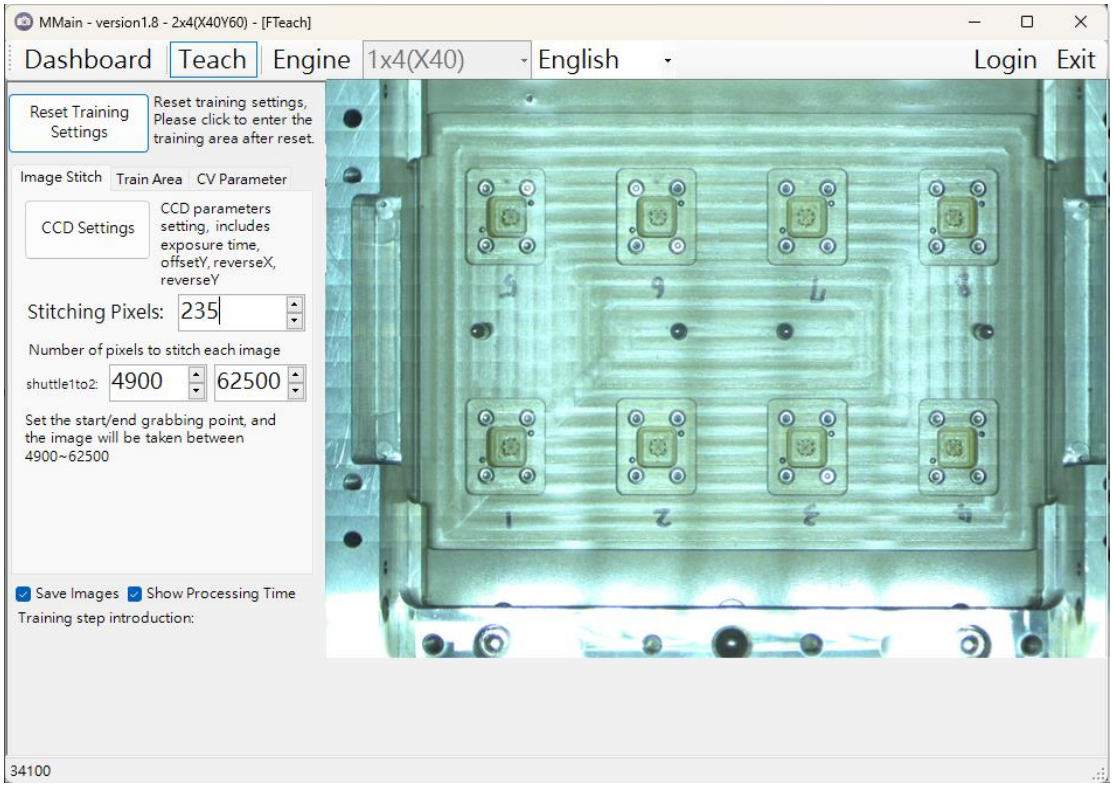




Move the shuttle and see the stitching image result



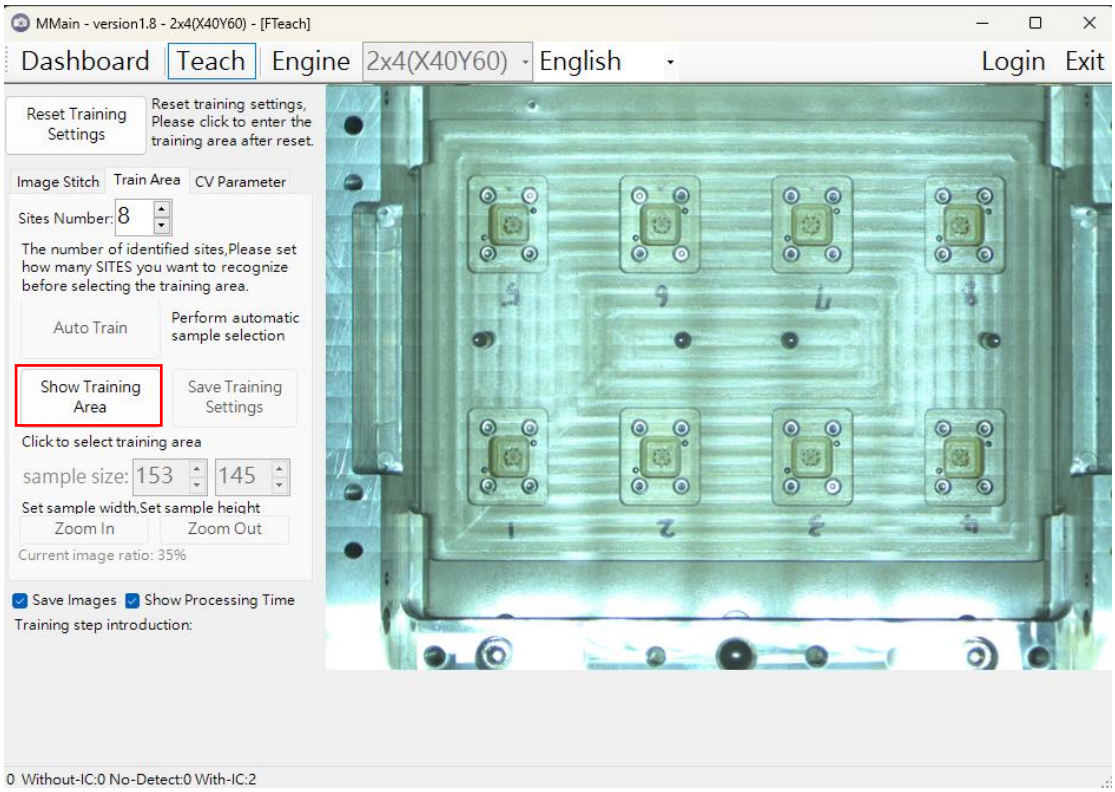
You can move the shuttle several times to confirm whether it is covered by the machine.

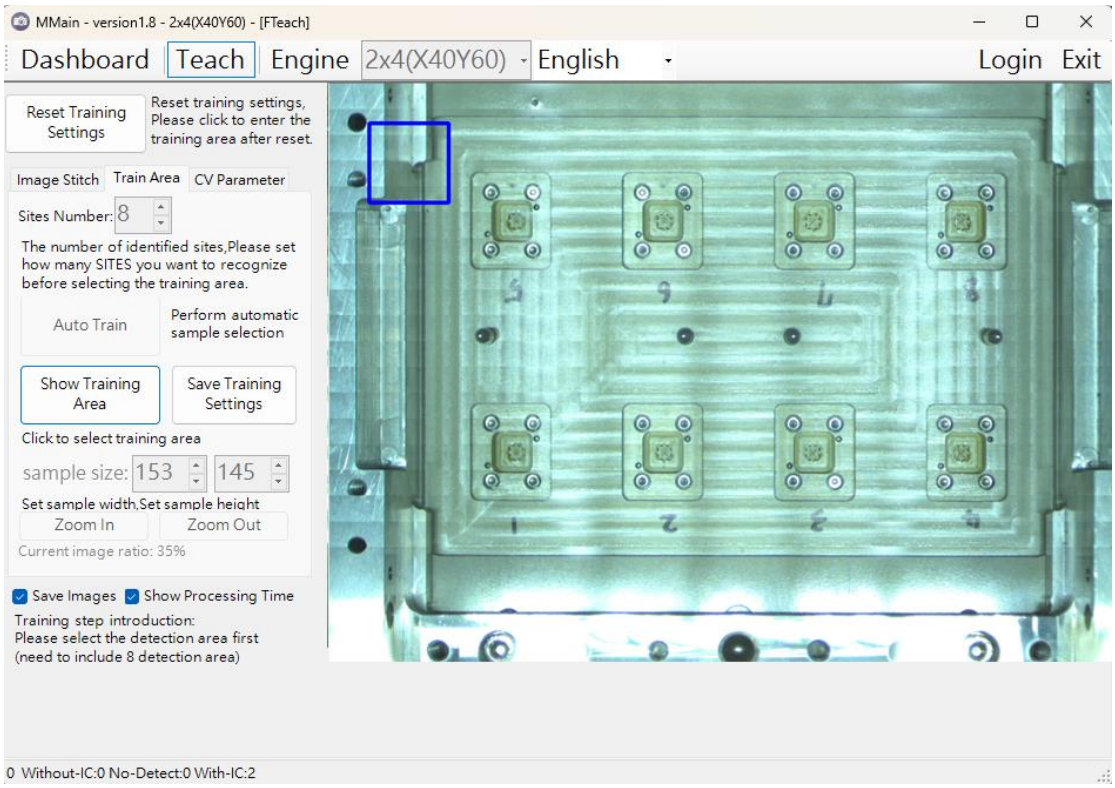


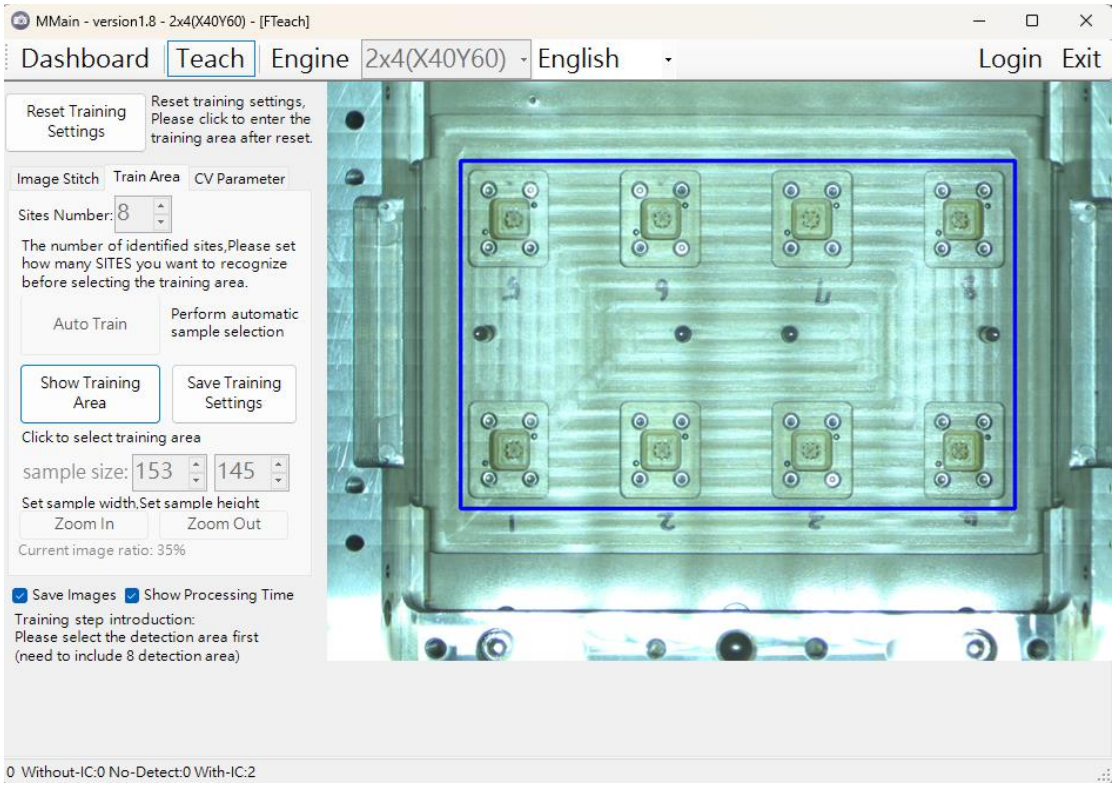
IV. Training Area Settings

i. Click "Show Training Area" to proceed with the training.

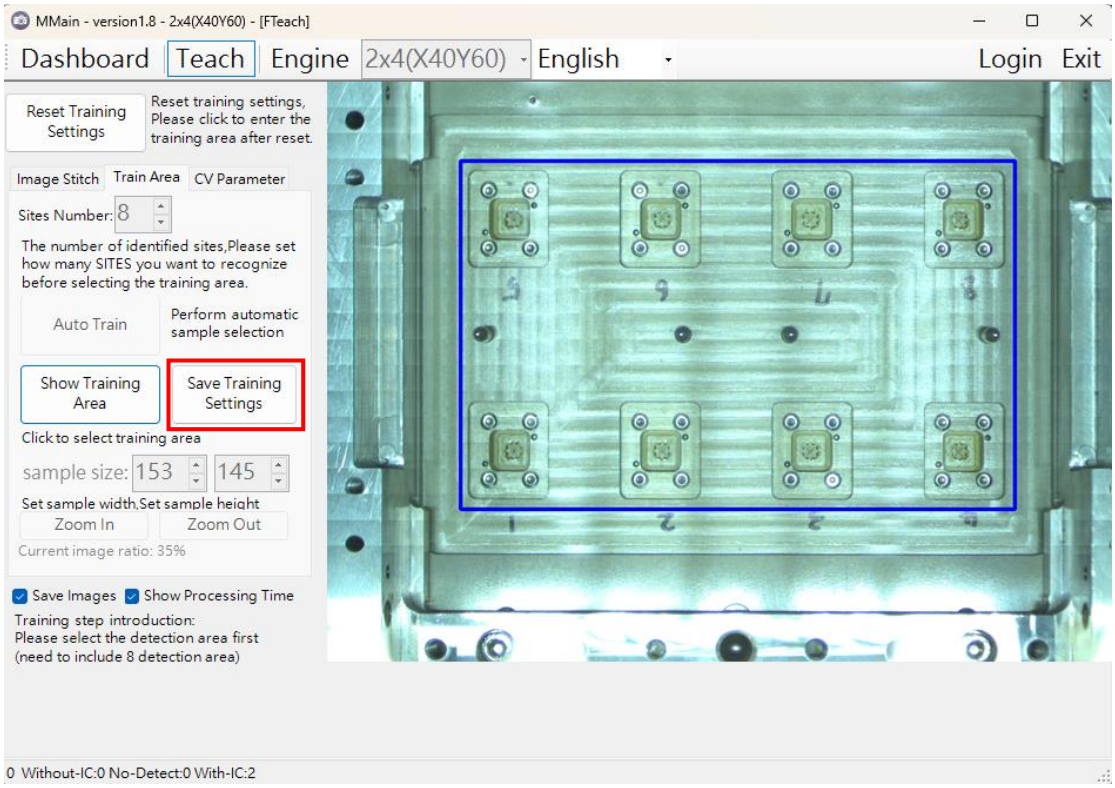
click "Reset Training Settings" to reset all training area configurations.

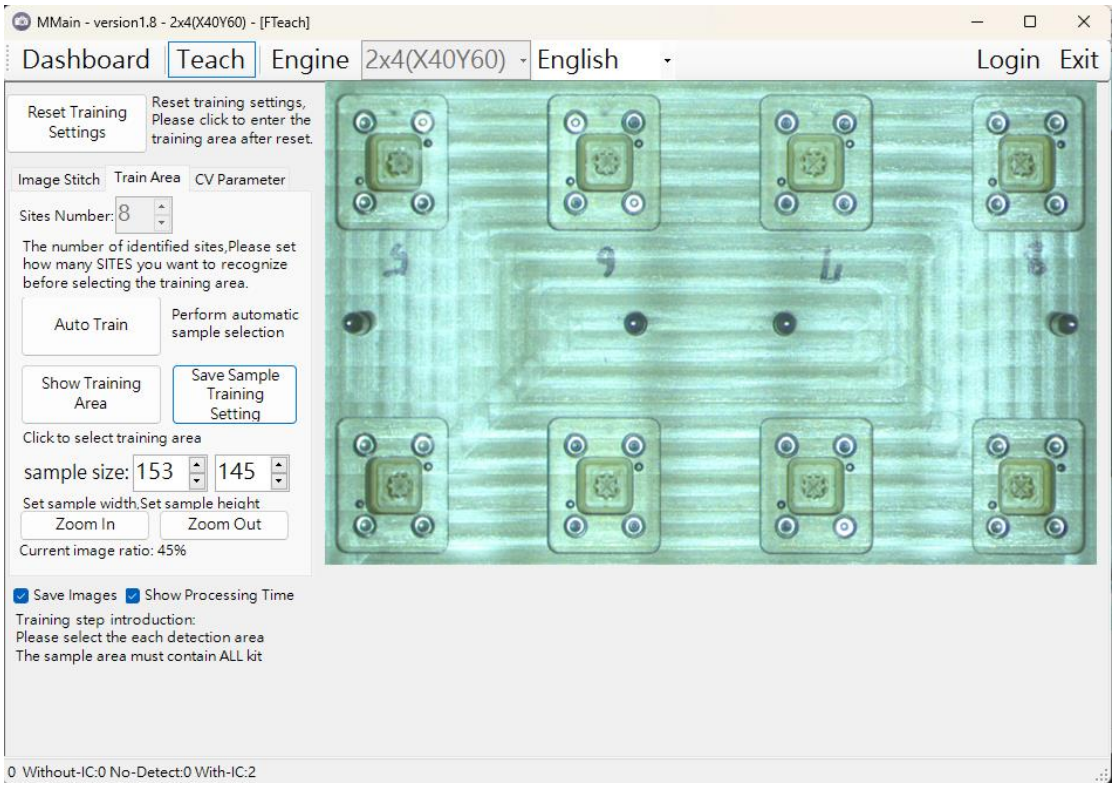

MMain - version1.8 - 2x4(X40Y60) - [FTeach]
Dashboard
Teach
Engine
2x4(X40Y60)
English
Login
Exit
Reset Training Settings
Reset training settings, Please click to enter the training area after reset.
Image Stitch
Train Area
CV Parameter
Sites Number: 8
The number of identified sites,Please set how many SITES you want to recognize before selecting the training area.
Auto Train
Perform automatic sample selection
Show Training Area
Save Training Settings
Click to select training area
sample size: 153 145
Set sample width,Set sample height
Zoom In
Zoom Out
Current image ratio: 35%
Save Images
Show Processing Time
Training step introduction:
0 Without-IC:0 No-Detect:0 With-IC:2


MMain - version1.8 - 2x4(X40Y60) - [FTeach]
Dashboard
Teach
Engine
2x4(X40Y60)
English
Login
Exit
Reset Training Settings
Reset training settings, Please click to enter the training area after reset.
Image Stitch
Train Area
CV Parameter
Sites Number: 8
The number of identified sites,Please set how many SITES you want to recognize before selecting the training area.
Auto Train
Perform automatic sample selection
Show Training Area
Save Training Settings
Click to select training area
sample size: 153 145
Set sample width,Set sample height
Zoom In
Zoom Out
Current image ratio: 35%
Save Images
Show Processing Time
Training step introduction:
Please select the detection area first
(need to include 8 detection area)
0 Without-IC:0 No-Detect:0 With-IC:2



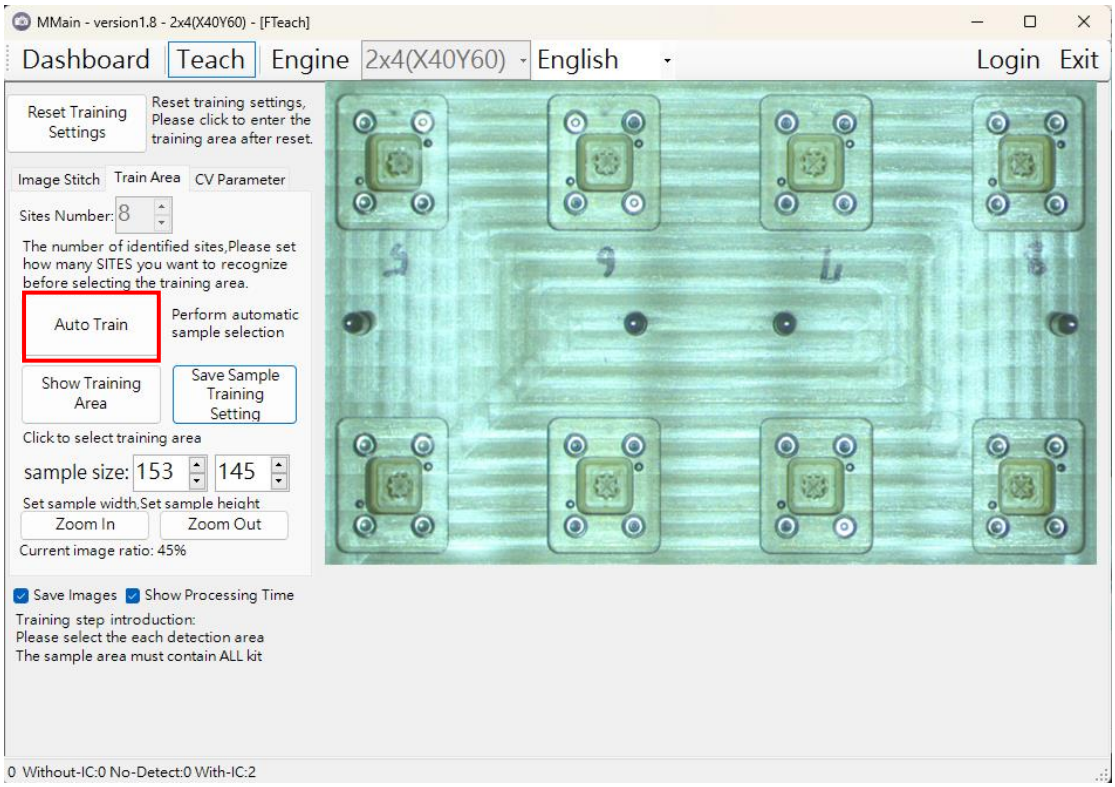
ii. After adjusting, click "Save Training Setting".

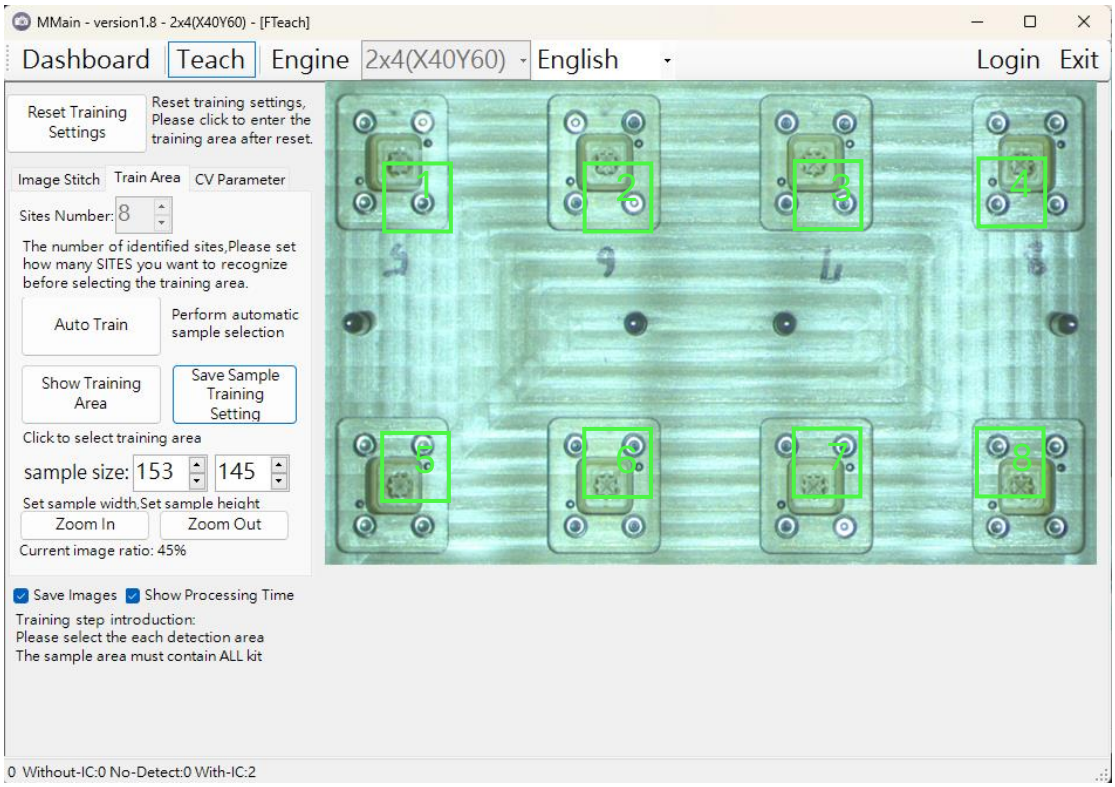




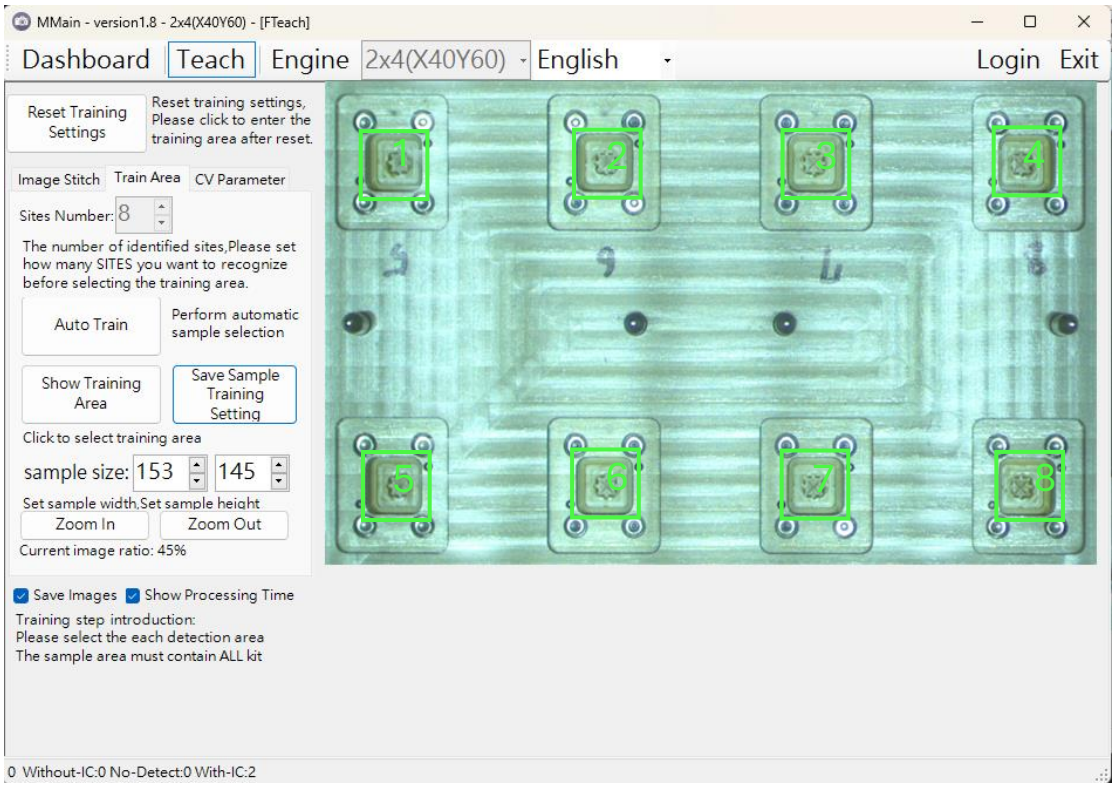
iii. Select the sample training area.

1. AutoTrain

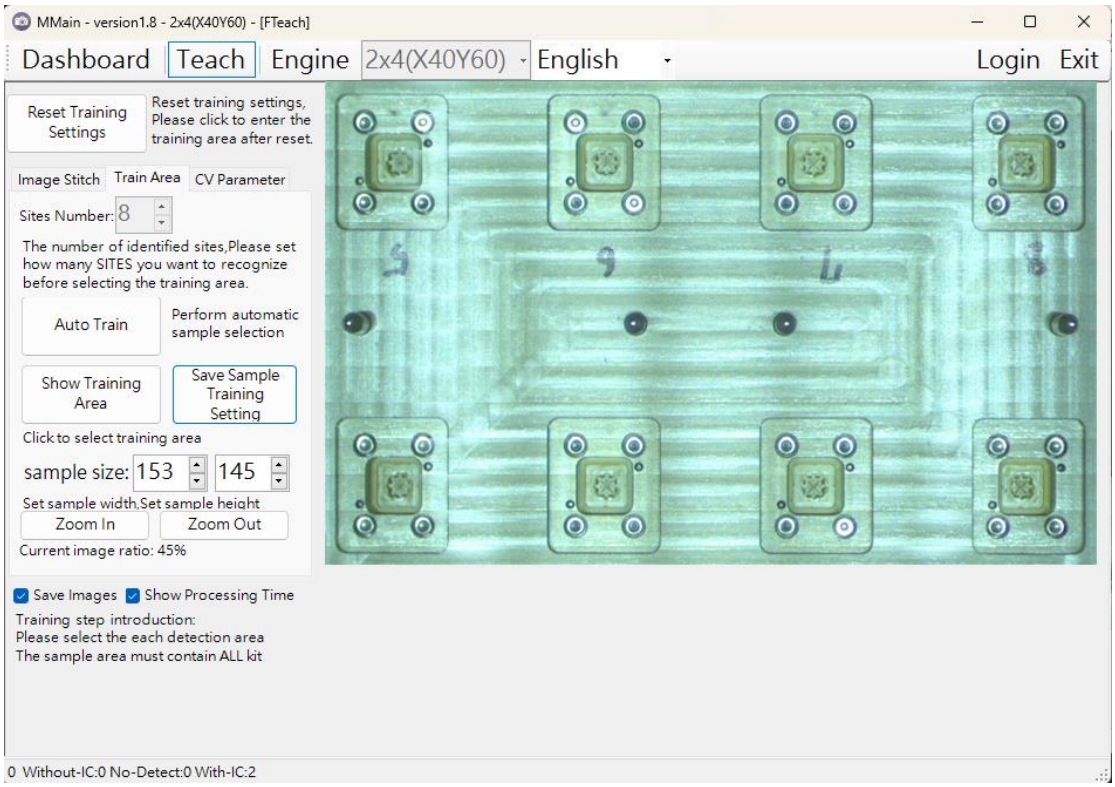




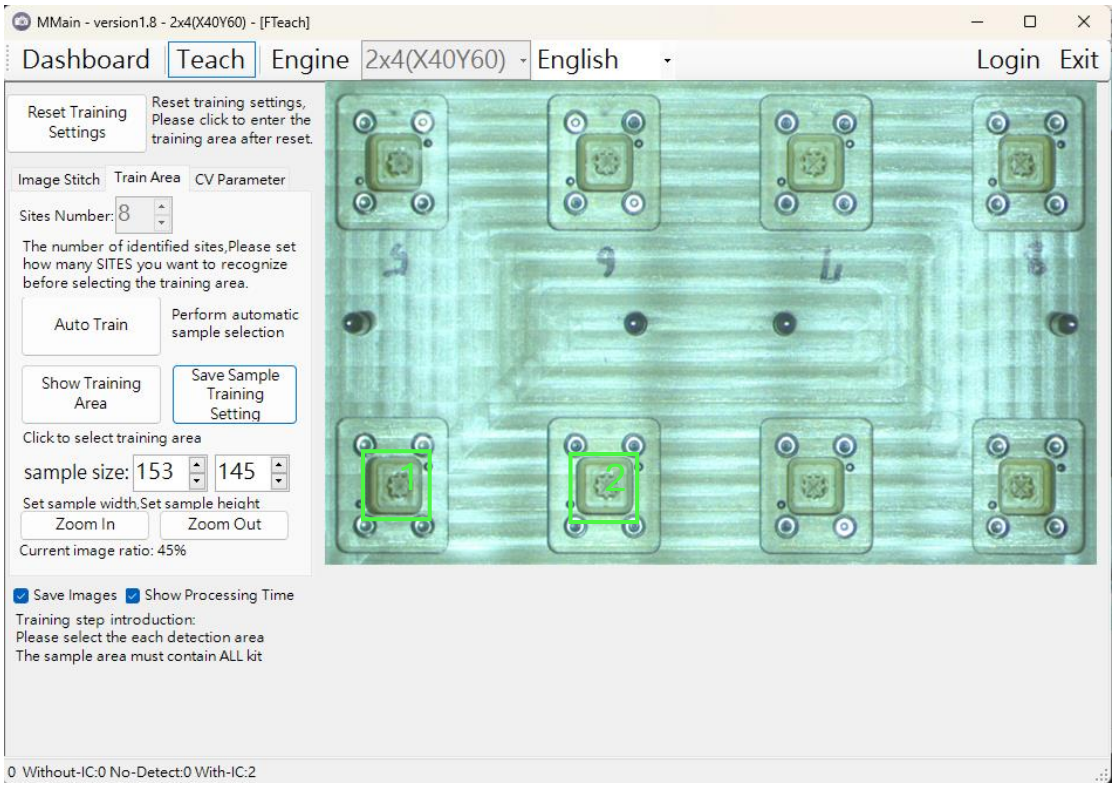
Move the small green boxes over the samples.

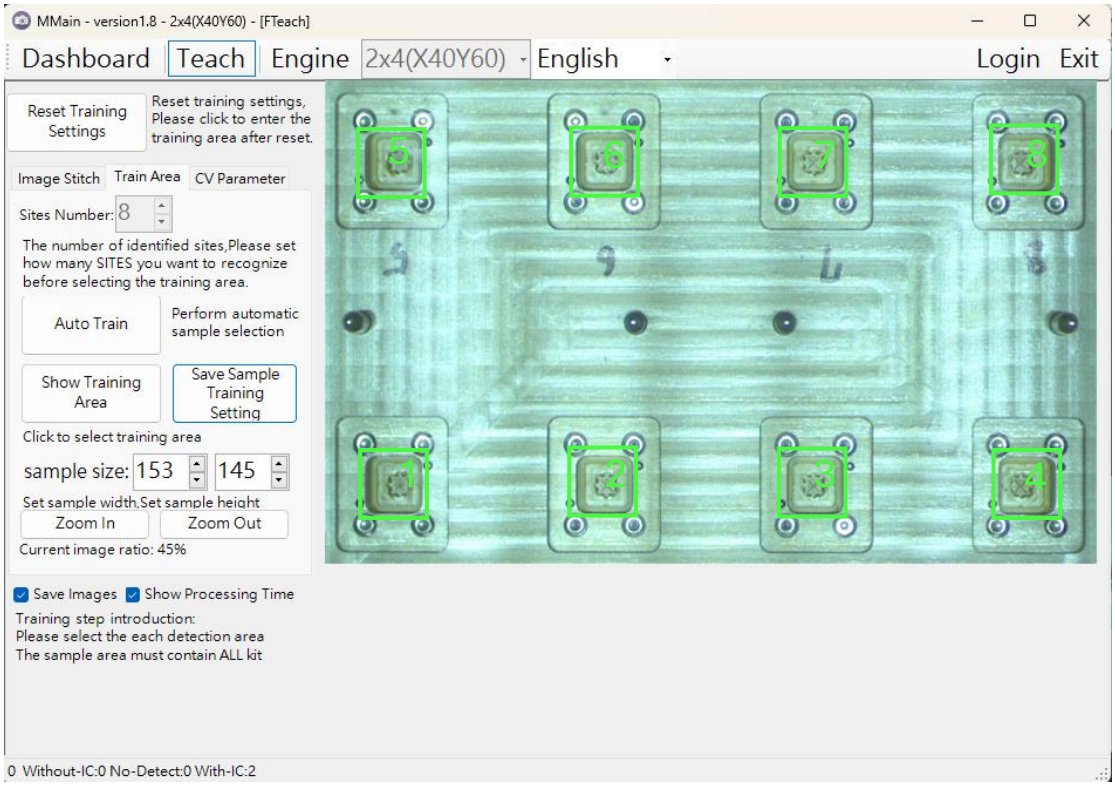


2. Manually select samples.

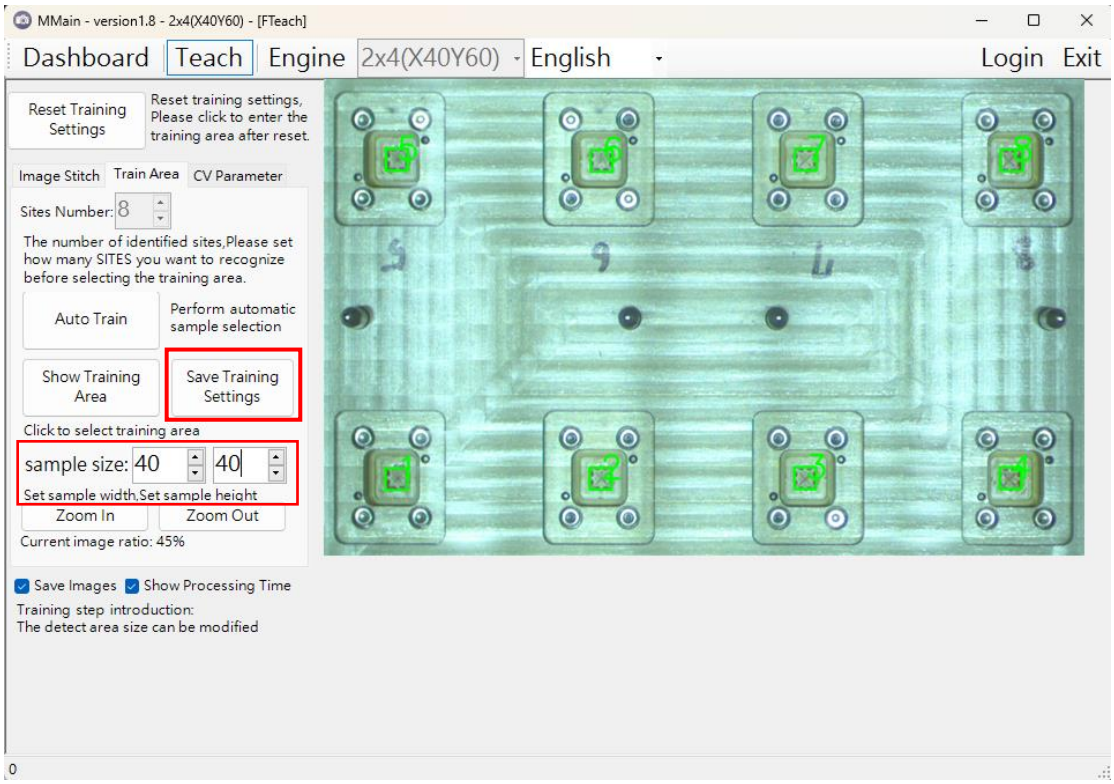


Click on the center of samples.





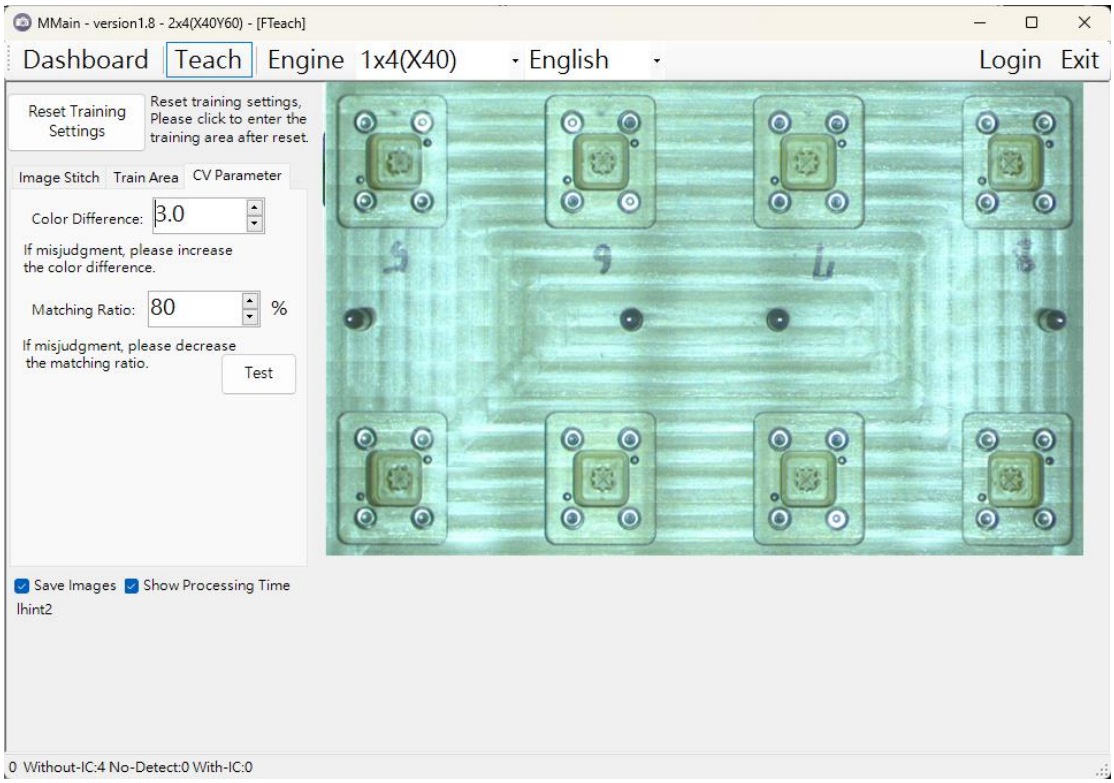
iv. Adjust the size of the sample, and after adjusting, click "Save Sample Training Setting" or "Save Training Settings".



V. Image recognition parameter settings – Color Difference、Matching Ratio

“Matching Ratio” - Match the grabbed image with the sample, the result lower than set value (Matching Ratio) will be filtered out. Ratio that are too high or too low may lead to false positives.

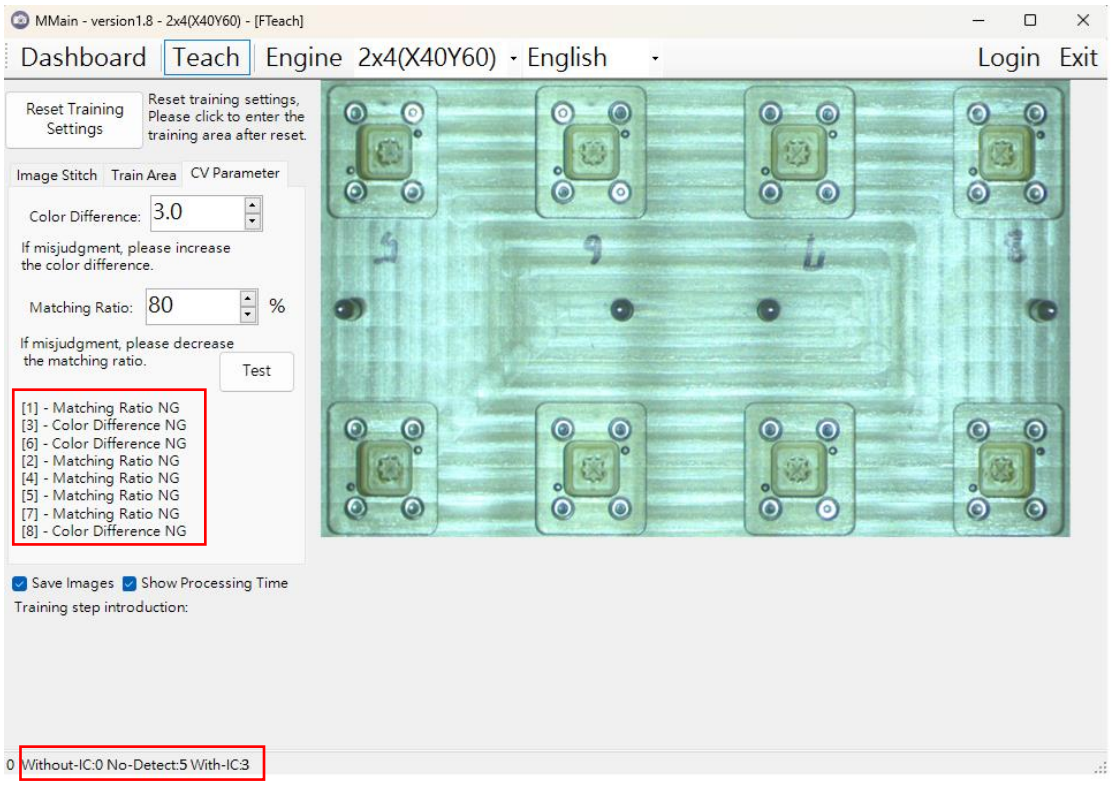
"Color Difference" - Compare the total color difference between the grabbed image and the sample. If the total amount of color difference compared is higher than the set value (Color Difference), it means there is IC; if the total amount of color difference compared is lower than the set value (Color Difference), it means there is no IC.



i. Move the shuttle, and check which parameters lead to NG.

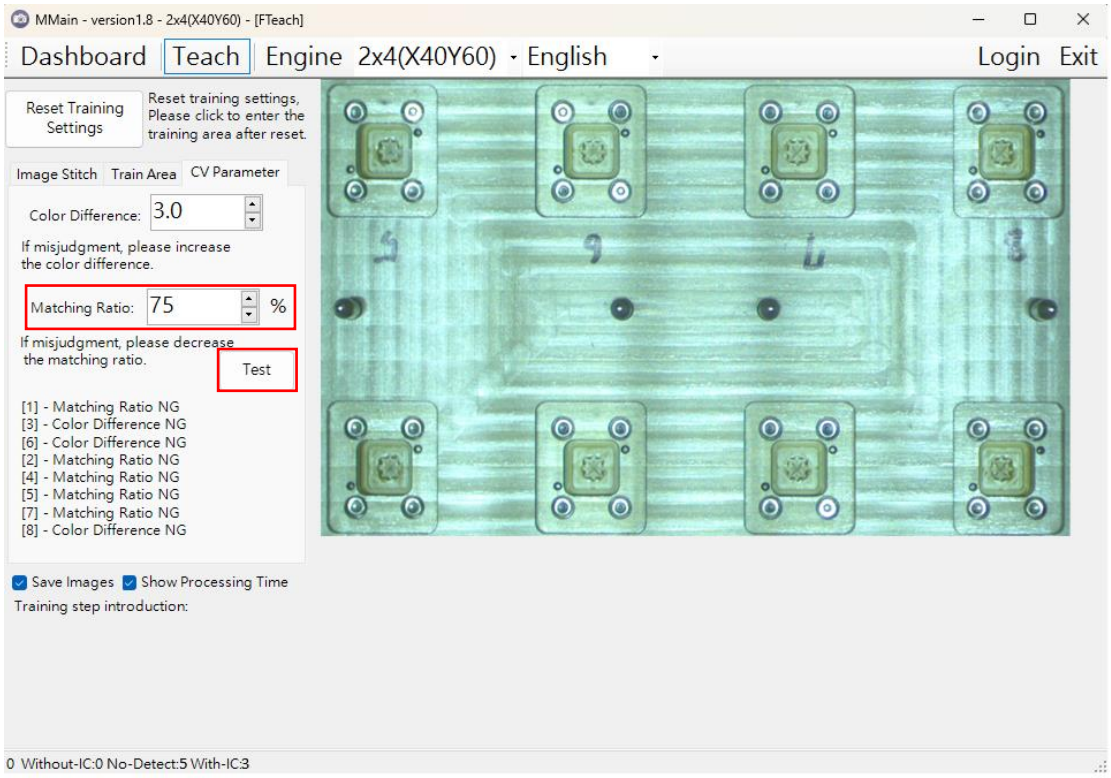
1. Matching Ratio NG, decrease the setting value (**Matching Ratio**).

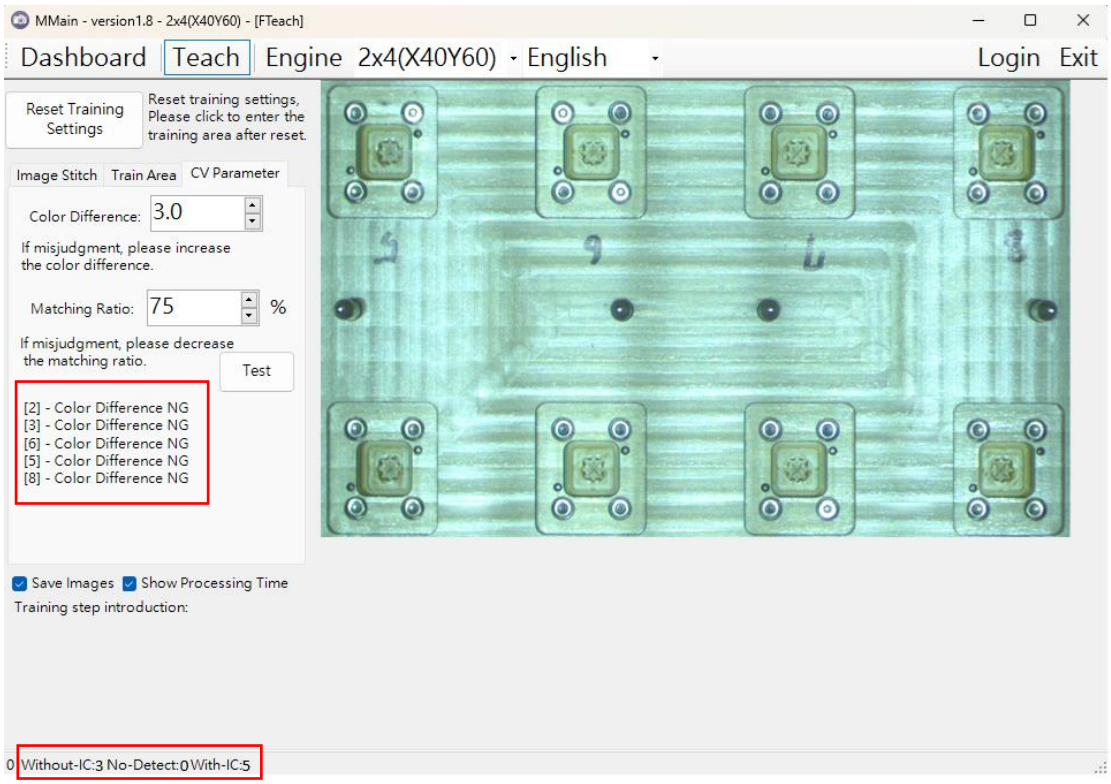
(If these parameters are set too high, it will become overly sensitive in recognition, leading to false positives)



Decrease the set value (**Matching Ratio**), the following are two methods to verify the setting value.

- Click the "Test" button





- Move the shuttle

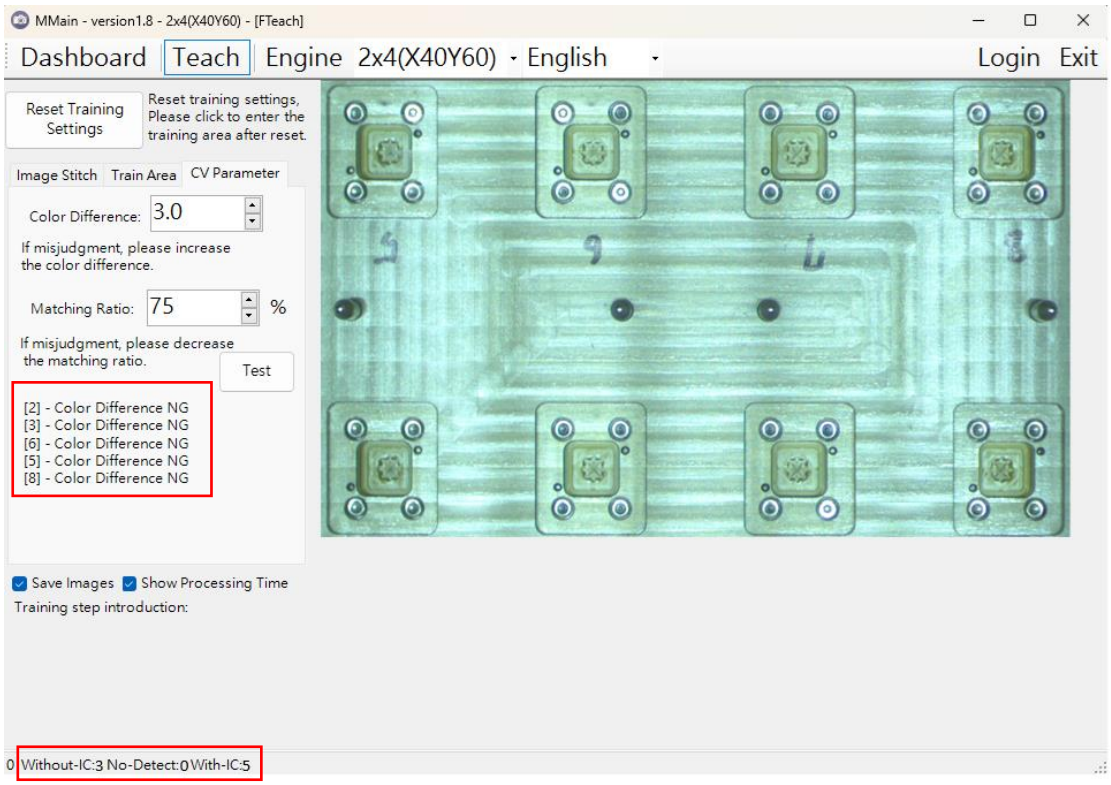
Move the shuttle and verify if the recognition count in the status bar below matches the DUT.

If "**Without-IC**" is inconsistent, decrease the Matching Ratio and move the shuttle again until the "**Without-IC**" count in the status bar below matches the DUT.

If "**Without-IC**" is consistent, then increase the matching ratio until reaching the threshold of inconsistency.

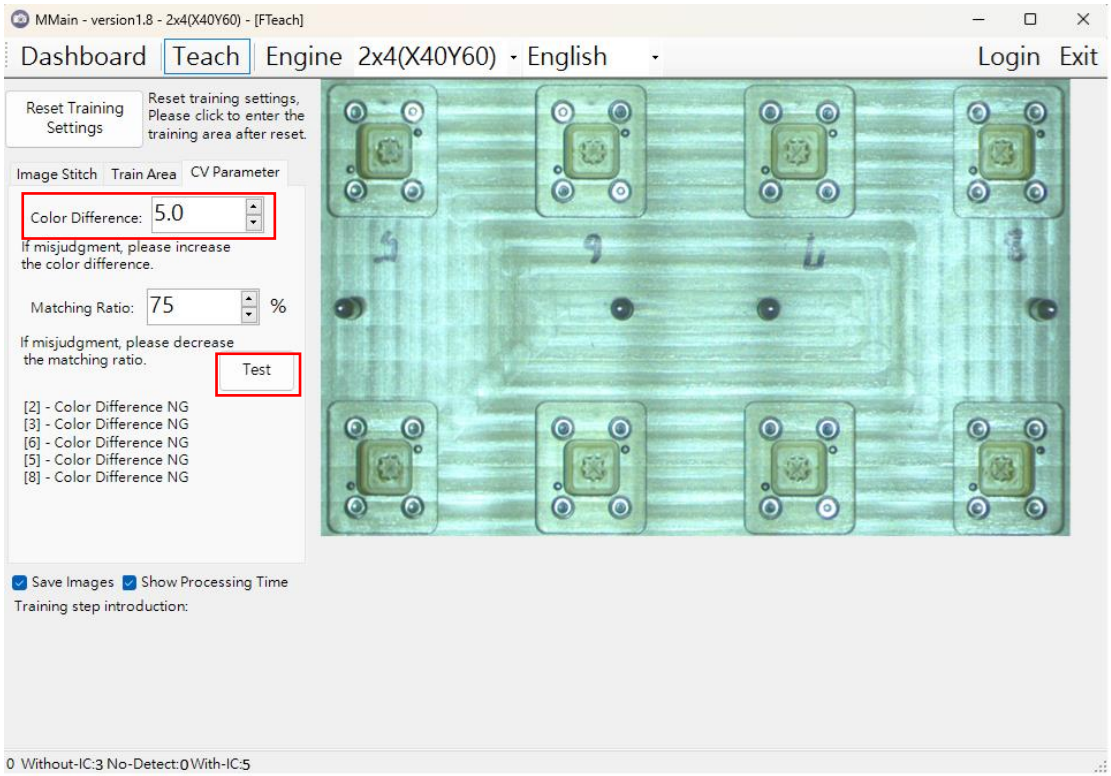
2. Color Difference NG, increase the setting value (**Color Difference**).

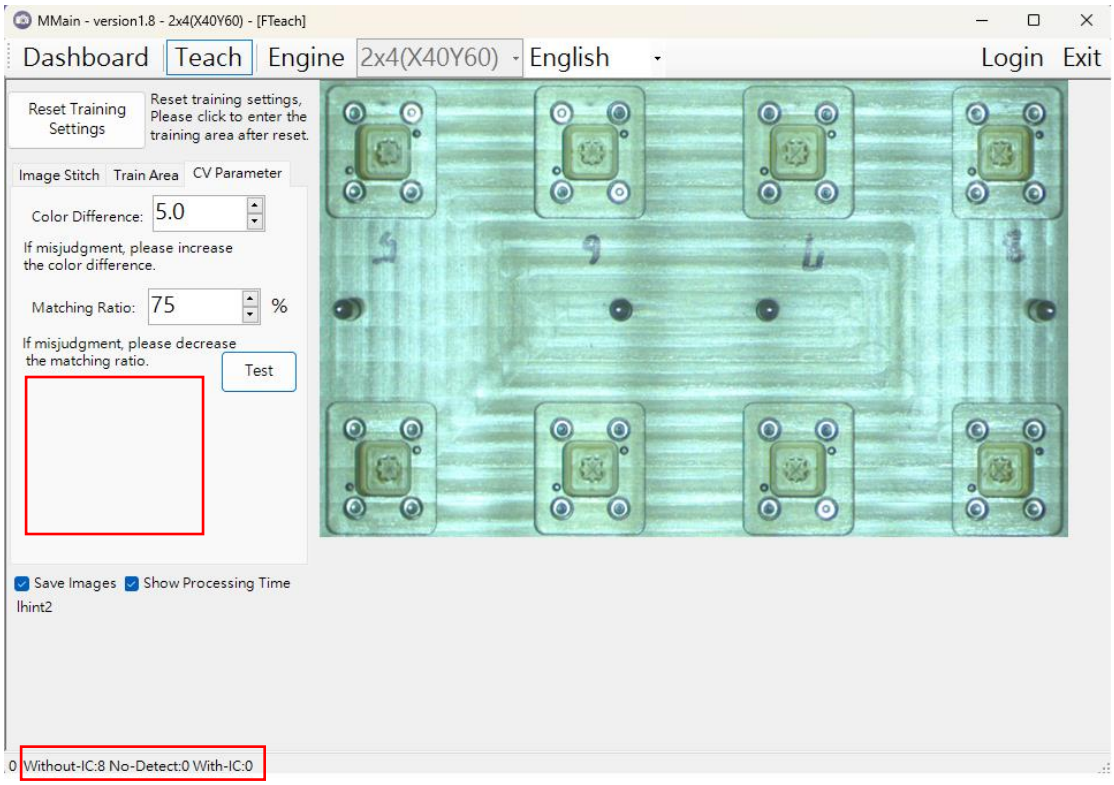
(If these parameters are set too low, it will become overly sensitive in recognition, leading to false positives)



Decrease the set value (**Color Difference**), the following are two methods to verify the setting value.

- Click the "Test" button





- Move the shuttle

Move the shuttle and verify if the recognition count in the status bar below matches the DUT.

If "**Without-IC**" is inconsistent, increase the Color Difference and move the shuttle again until the "**Without-IC**" count in the status bar below matches the DUT.

If "**Without-IC**" is consistent, then decrease the Color Difference until reaching the threshold of inconsistency.

ii. Move the shuttle, and there is no NG

1. Increase the setting value (**Matching Ratio**)

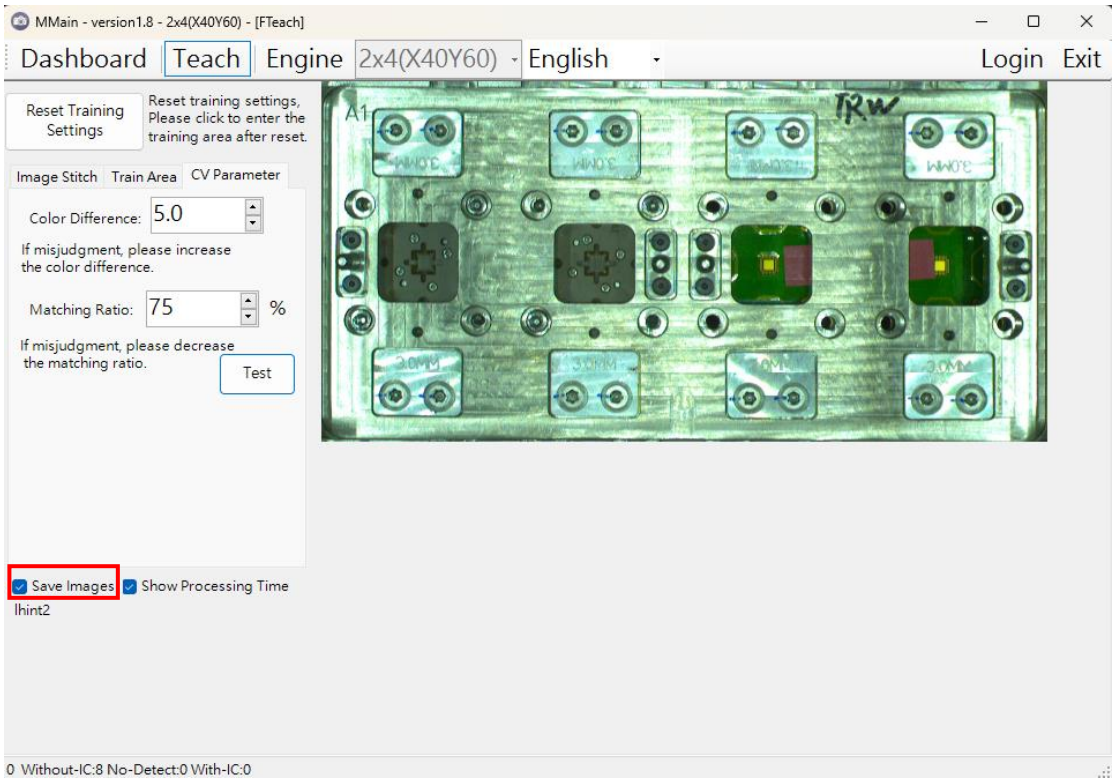
Increase the setting value (**Matching Ratio**) and move the shuttle until reaching the threshold of inconsistency.

2. Decrease the setting value (**Color Difference**)

decrease the setting value (**Color Difference**) and move the shuttle until reaching the threshold of inconsistency.

Other Parameters

Save Images Settings



It will save NG images.

Image file: *D:\SocketVision\FailData*

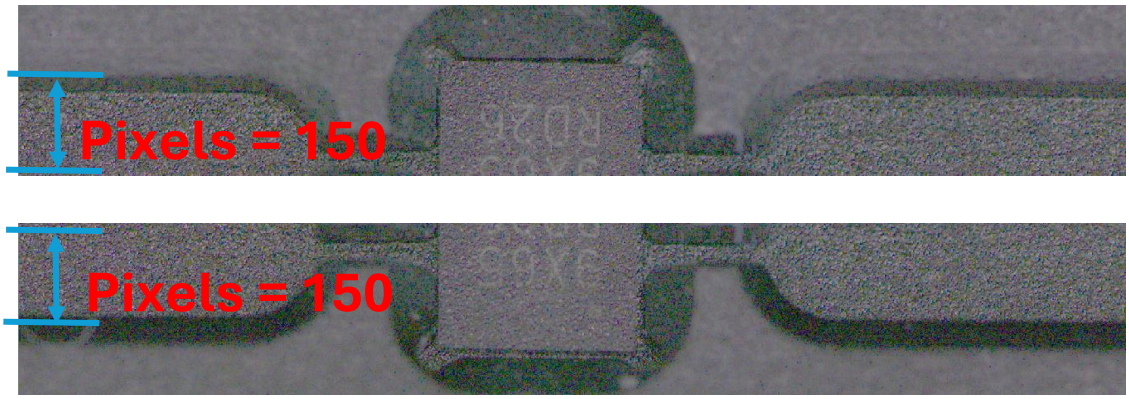
Stitching Pixels

The meaning is how many pixels each image needs to overlap.

For example, suppose there are 10 images of 1920*300. The movement of the shuttle causes the image to move only in the Y-axis.

The **Stitching Pixels** is set to 150, and the upper and lower images are stitched together.

Modify this parameter to see the stitching results immediately.



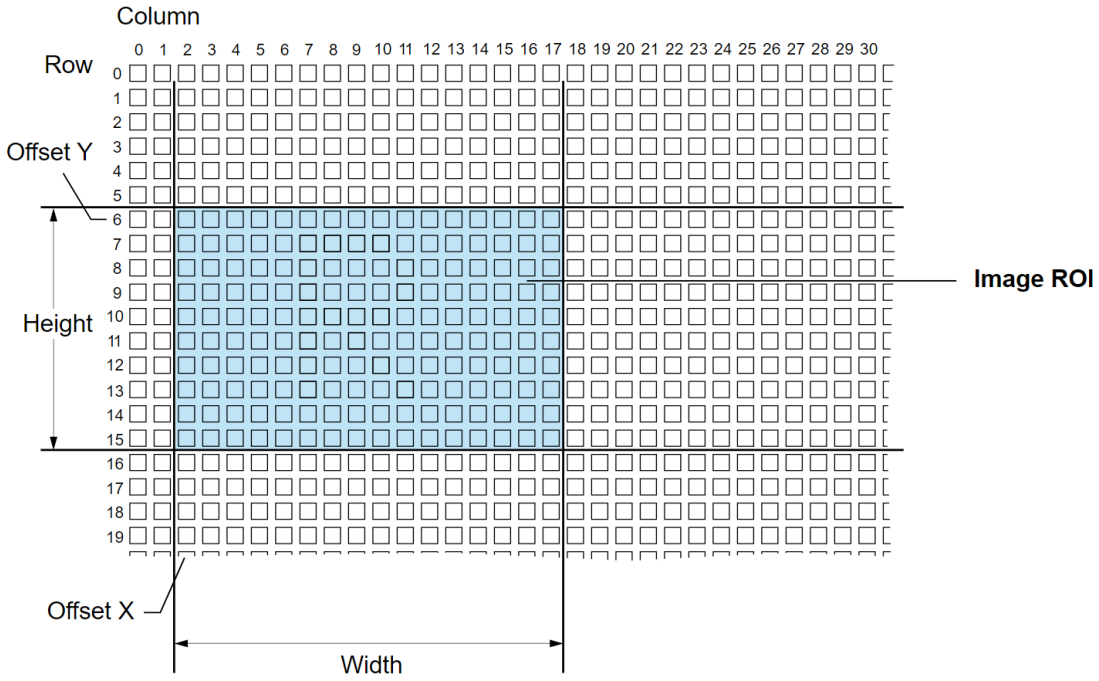
CCD parameters

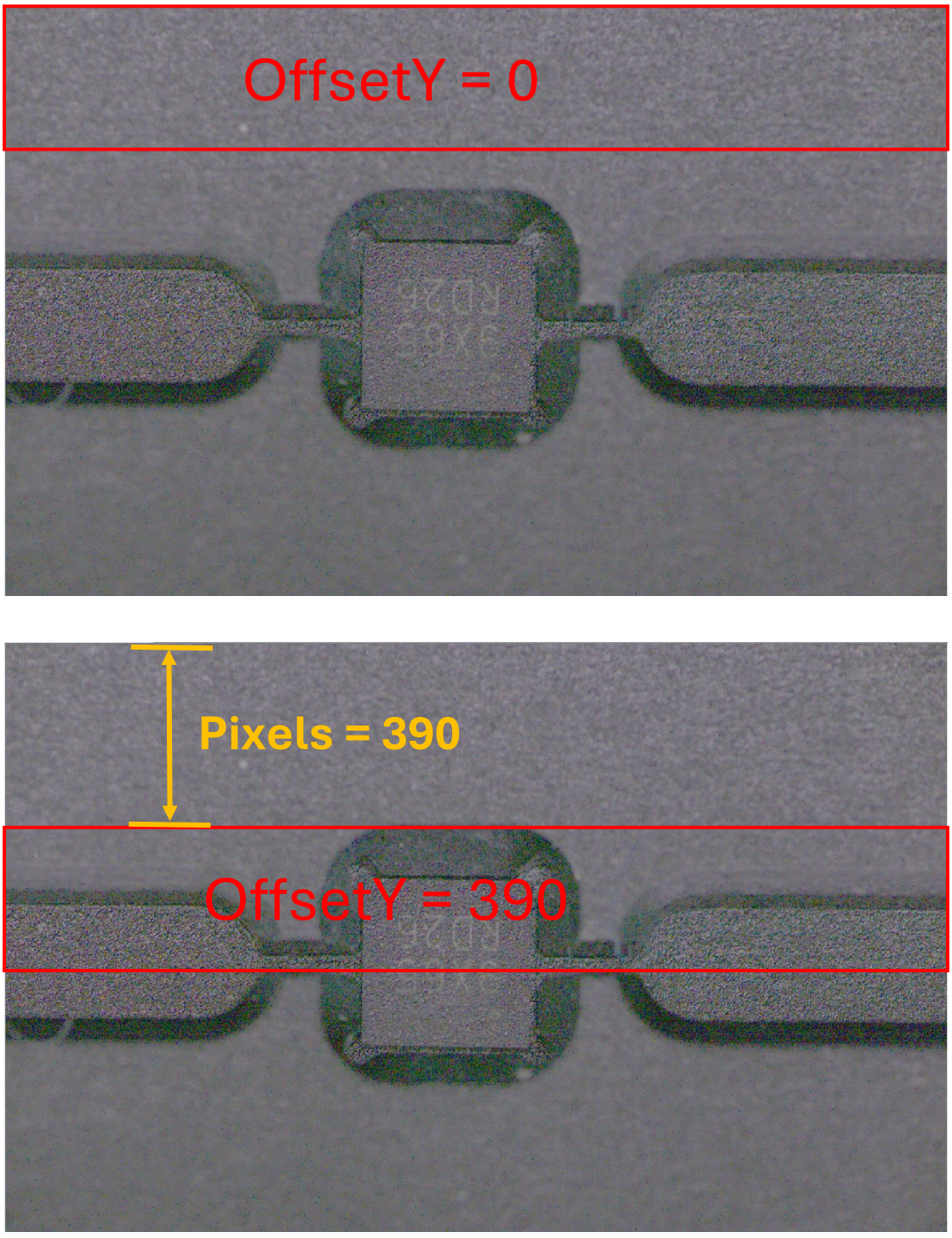
Due to the need for image stitching, the image size is changed to Width*Height **(1920*300)**

OffsetY

OffsetY - Vertical offset from the top of the sensor to the region of interest (area of interest) (in pixels).

Attention: **The image of ROI location may be obscured by the machine or overexposed. Be sure to adjust this parameter.**





Exposure Time

Exposure Time - the length of time the camera collects light from your sample.

Unit: us (The CCD recognition software can set the maximum value to 5000us)

ReverseX

Enables/disables horizontal mirroring of the image. The pixel values of every line in a captured image will be swapped along the line's center.

ReverseY

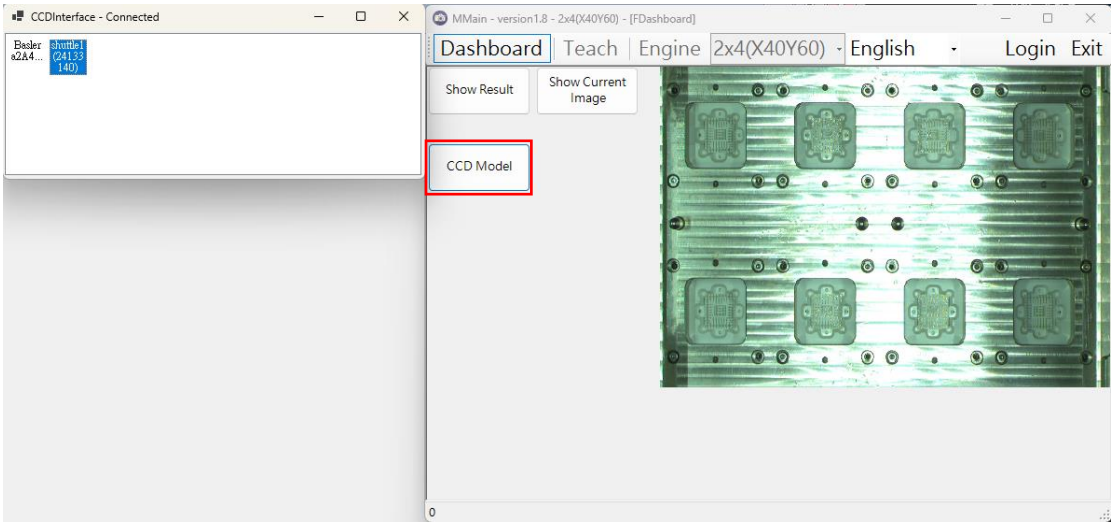
Enables/disables vertical mirroring of the image. The pixel values of every column in a captured image will be swapped along the column's center.

Exception Handling

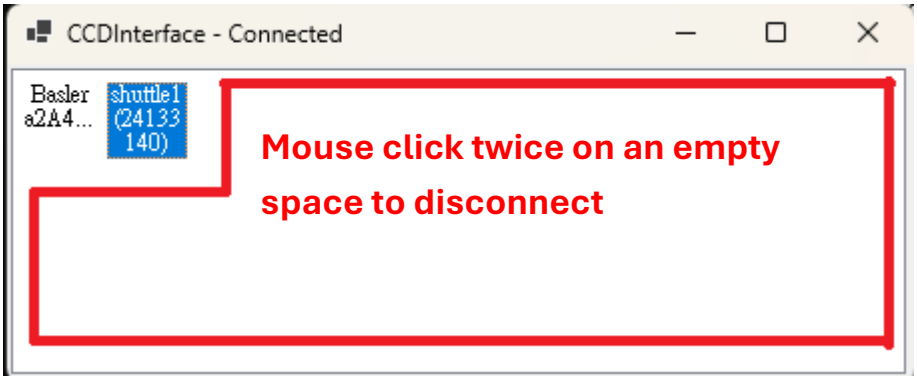
Check for **overexpose** using "pylon Viewer"

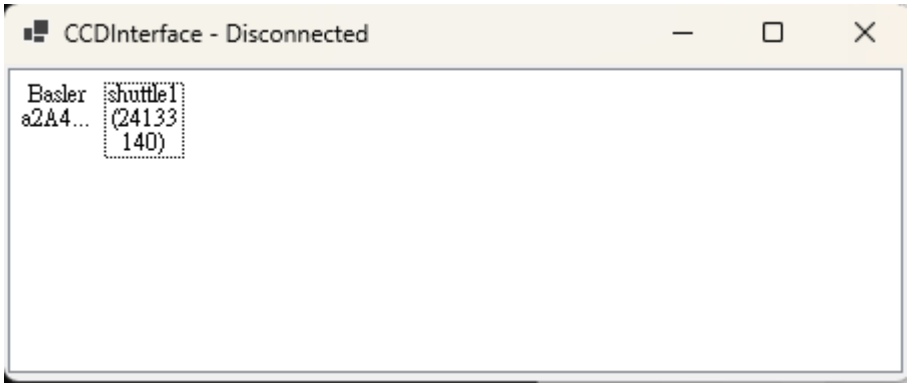
1. Please open the CCD recognition software first and connect the corresponding CCD model.

Purpose: **Set CCD hardware parameters**



2. Disconnect the CCD recognition software and CCD hardware





3. Open "pylon Viewer" software

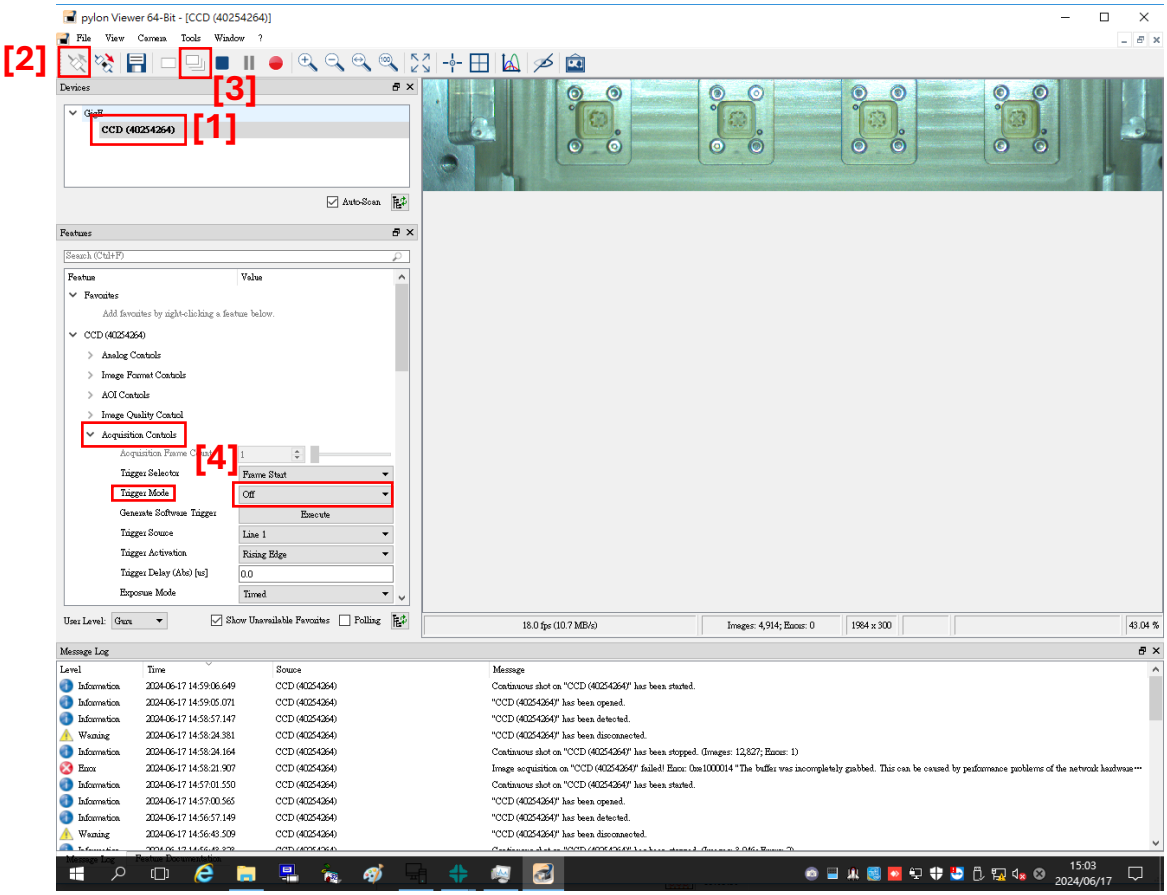
I. Preset CCD parameters

[1] Click on the corresponding CCD model

[2] Connect to CCD hardware

[3] Click on the "continuous Shot"

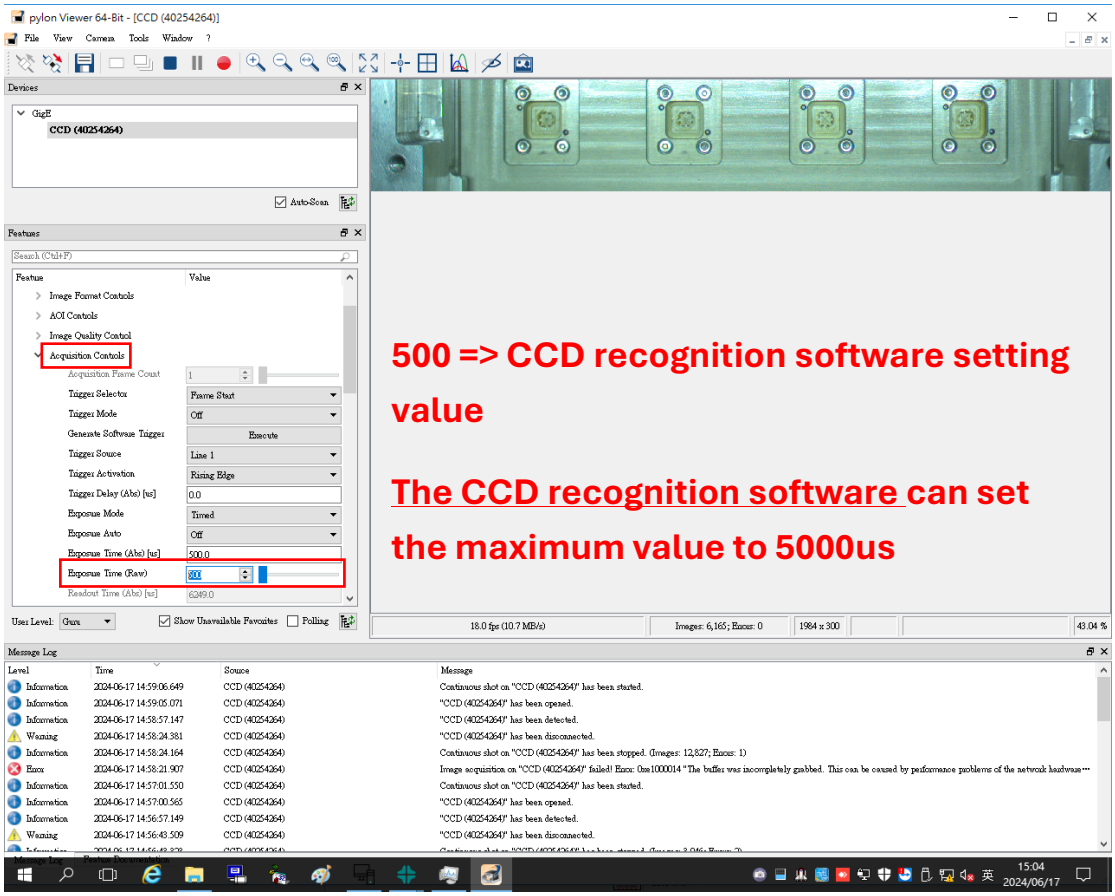
[4] **Acquisition Control-> Trigger Mode -> set to Off**

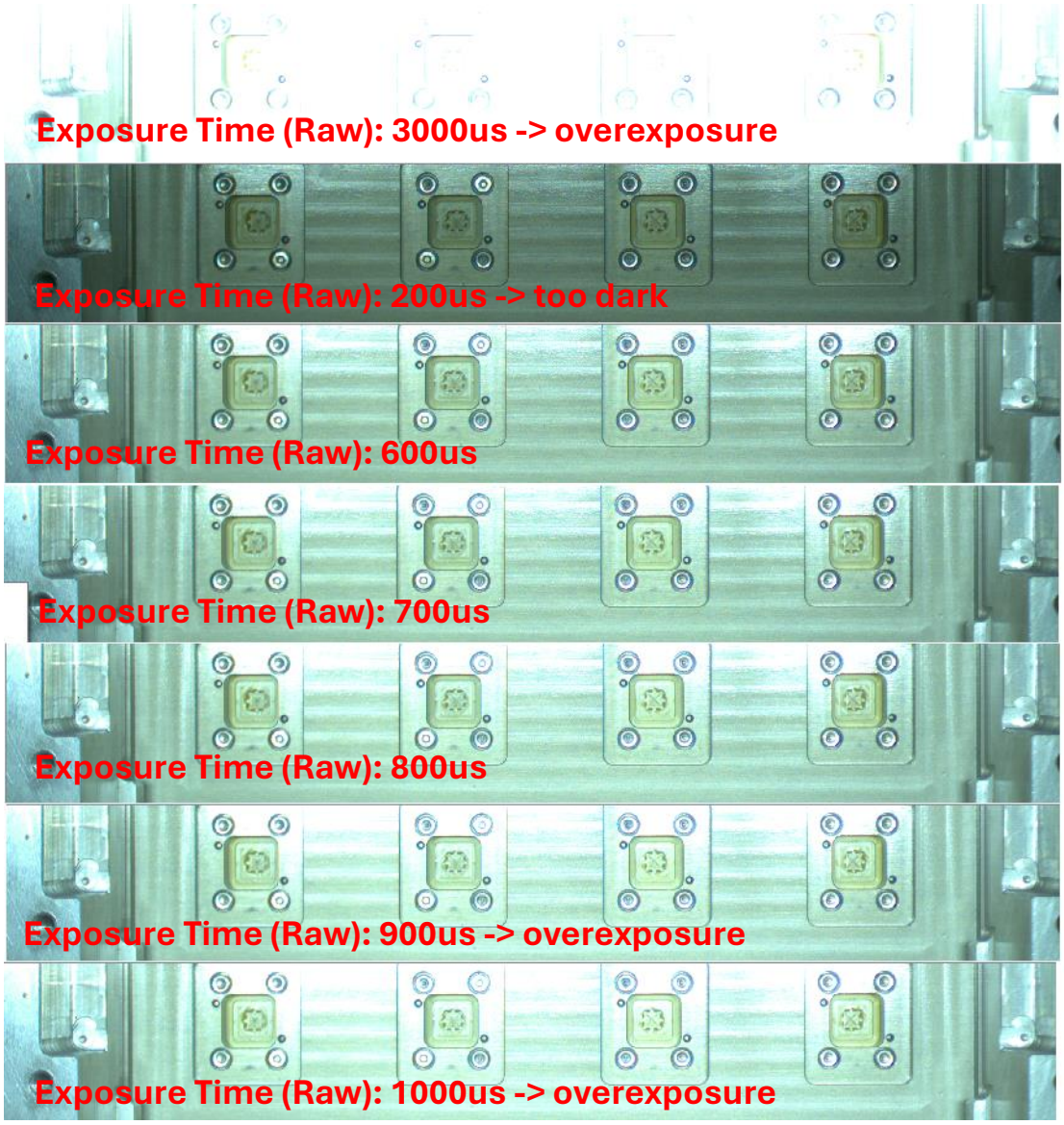


II. Set **Exposure Time (Raw)**

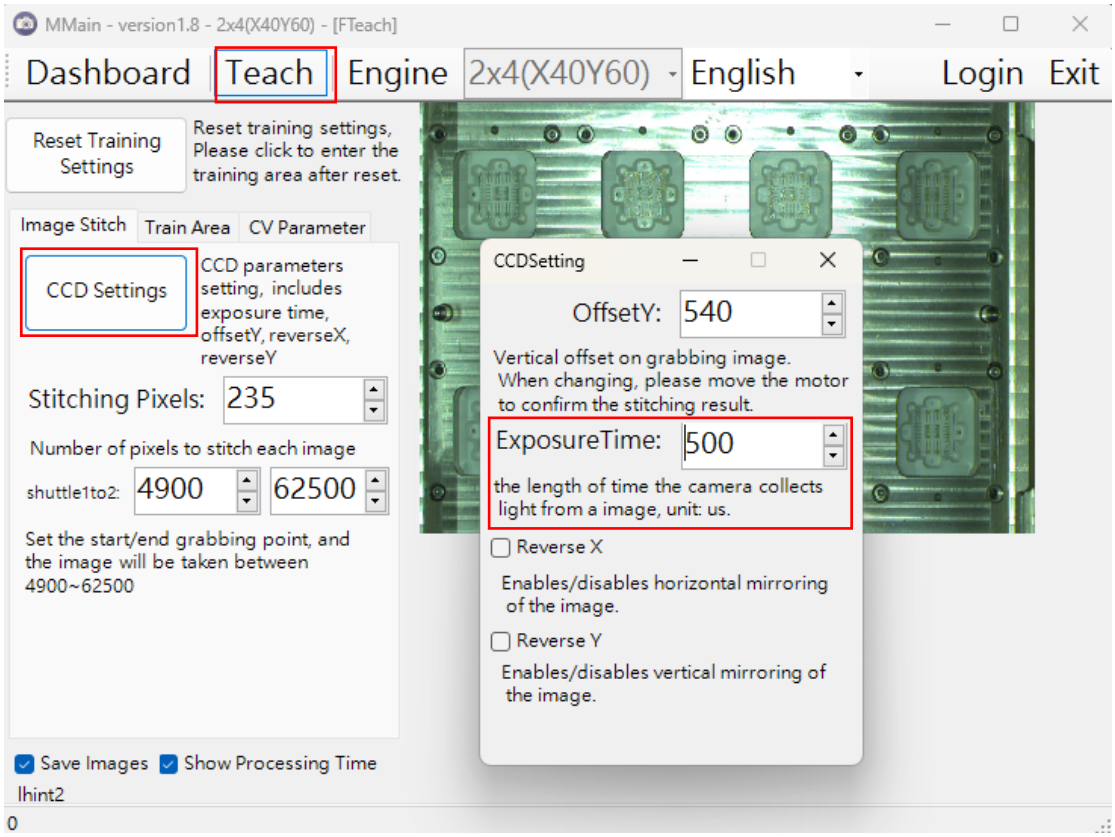
Path: **Acquisition Control -> Exposure Time (Raw)**

Please use Exposure Time (Raw)±100 as increment.





4. Record the Exposure Time (Raw) value and set it in the CCD recognition software.
    I. Close the "pylon Viewer"
    II. Open the CCD recognition software
    III. Set the CCD parameter - exposure time


MMain - version1.8 - 2x4(X40Y60) - [FTeach]
Dashboard
Teach
Engine
2x4(X40Y60)
English
Login
Exit
Reset Training Settings
Reset training settings, Please click to enter the training area after reset.
Image Stitch
Train Area
CV Parameter
CCD Settings
CCD parameters setting, includes exposure time, offsetY, reverseX, reverseY
Stitching Pixels:
235
Number of pixels to stitch each image
shuttle1to2:
4900
62500
Set the start/end grabbing point, and the image will be taken between 4900~62500
Save Images
Show Processing Time
lhint2
0
CCDSetting
OffsetY:
540
Vertical offset on grabbing image. When changing, please move the motor to confirm the stitching result.
ExposureTime:
500
the length of time the camera collects light from a image, unit: us.
Reverse X
Enables/disables horizontal mirroring of the image.
Reverse Y
Enables/disables vertical mirroring of the image.

The image result which be grabbed is black/dark

The following situations may occur:

[1] The image is completely BLACK. No images were grabbed due to an abnormality in the trigger line.

Trigger line anomaly: Please reinsert the CCD power cable (which includes the trigger line) and check if the cable is damaged. If there is any damage, you will need to replace it with a new CCD power cable.

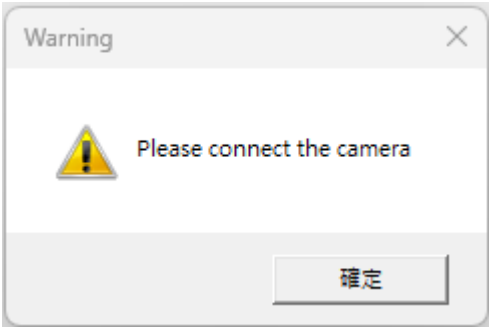
[2] The exposure time is set too low, resulting in a dark image. Please refer to the PylonViewer to check for overexposure. After adjusting the exposure time, proceed with the training.

[3] The light strip is burnt out, resulting in a dark image. Please check the hardware first and replace the light strip. After adjusting it, proceed with the training.

[4] The light strip cable is not properly connected, resulting in a dark image. Please check the hardware first and properly connect the cable. After adjusting it, proceed with the training.

Display a warning window

Please connect the camera



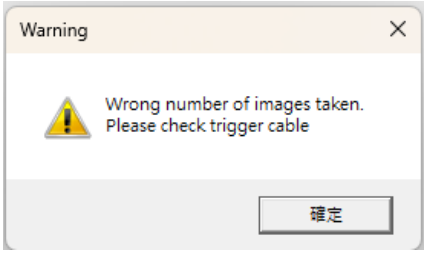
The possible scenarios are as follows:

[1] Due to a trigger line anomaly, the CCD hardware and CCD recognition software were disconnected during operation. Please reconnect and check the trigger line.
Trigger line anomaly: Please reinsert the CCD power cable (which includes the trigger line) and check if the cable is damaged. If there is any damage, you will need to replace it with a new CCD power cable.

[2] The CCD hardware is not ready (not powered on, cable not connected, or CCD hardware IP not properly configured).

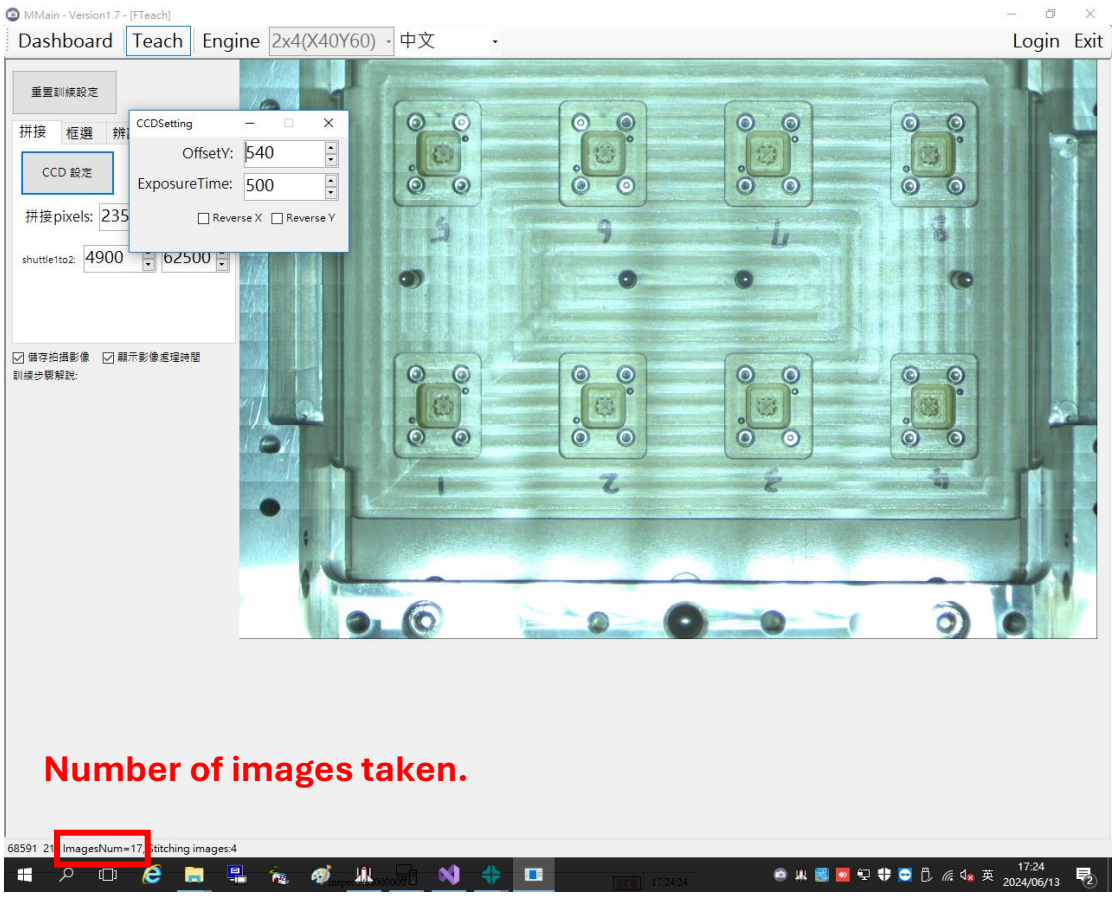
[3] When using the CCD recognition software for the first time, you need to select the CCD model. Once the model is selected, it will automatically connect to the corresponding CCD model in future sessions.

Wrong number of images taken. Please check trigger cable

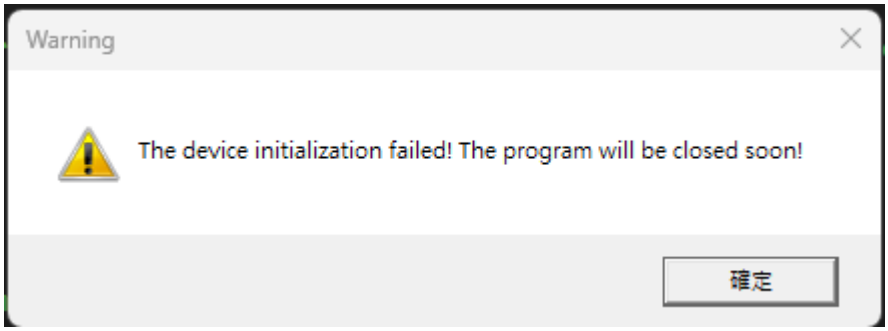


Determine if there is a trigger line anomaly based on the number of images taken. If the count is zero or if an incorrect number of images is taken, this warning window will be displayed. Please refer to the Engine page.

Trigger line anomaly: Please reinsert the CCD power cable (which includes the trigger line) and check if the cable is damaged. If there is any damage, you will need to replace it with a new CCD power cable.



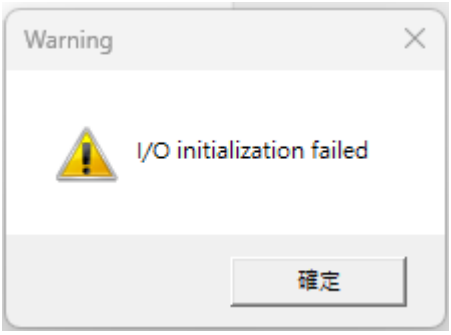
The device initialization failed! The program will be closed soon!



Initialization failed when opening the program. Please send the folder back to R&D for analysis.

path: **C:\ChipRight\SocketVision**

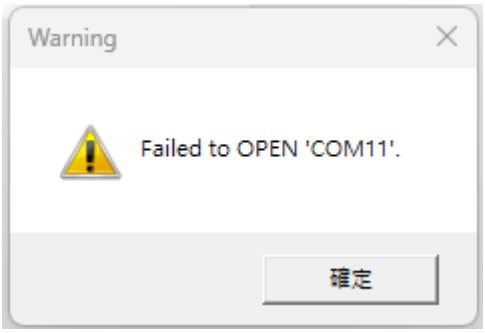
I/O initialization failed



Initialization failed when opening the program. Please send the folder back to R&D for analysis.

path: **C:\ChipRight\SocketVision**

Failed to OPEN 'COM11'

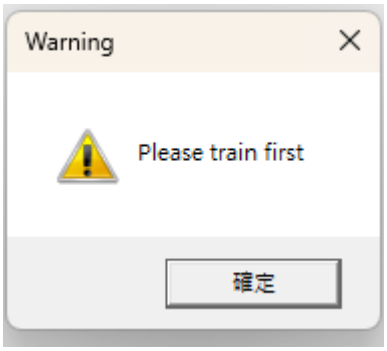


Use RS232 Comport for communication with the handler (CCD: COM11, handler: COM10). The possible scenarios for a connection failure are as follows:

[1] COM11 is not connected.

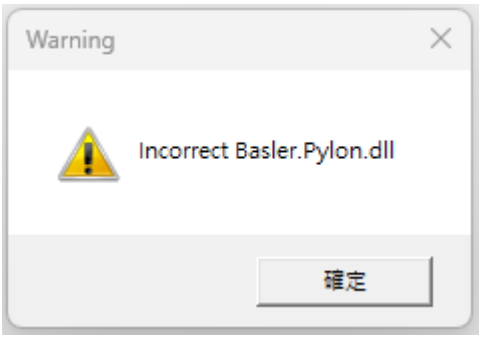
[2] The CCD software was not properly closed, causing it to remain connected to COM11. A computer restart is required.

Please train first



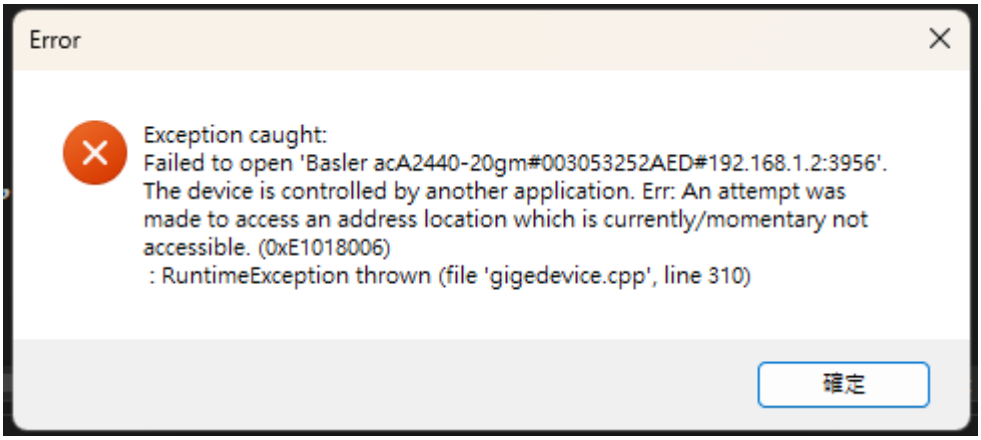
If there are no training images yet, this warning window will pop up. Please proceed with the training.

Incorrect Basler.Pylon.dll



Please contact R&D to replace it with the correct CCD software DLL.

EXCEPTION CAUGHT: warning window



Indicates that another application is currently connected to the CCD hardware. You can restart the CCD network and reconnect.

※ Note: If there are other error messages starting with "Exception caught," please take a screenshot and save it.

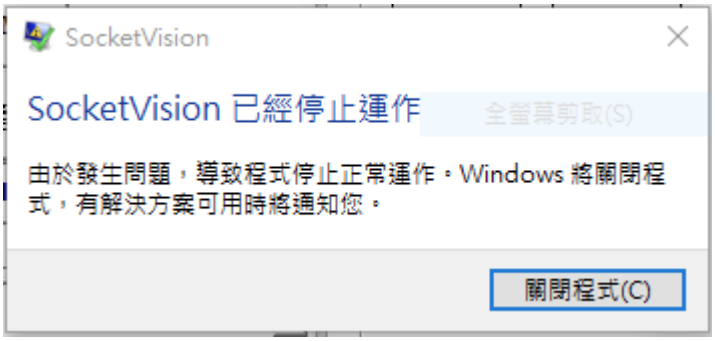
Replace the socket base

Each time you replace the socket base, please connect the corresponding CCD profile. Refer to "Creating/Connecting profile" (P.15~P.20) for details.

For example, a 2x4 socket base corresponds to a 2x4 CCD profile; a 1x4 socket base corresponds to a 1x4 CCD profile.

Afterward, proceed with the training steps.

SOCKETVISION crashes



Please send the folder back to R&D for analysis.

path: **C:\ChipRight\SocketVision**

path: **D:\SocketVision\failData\Current Date**

Other CCD software anomalies

Please send the folder back to R&D for analysis.

path: **C:\ChipRight\SocketVision**

path: **D:\SocketVision\failData\Current Date**